Model Comparison for the Density Structure **Across Solar Coronal Loops**



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1. Motivation

AIM: To infer the properties of the spatial distribution of the mass density across solar coronal loops.

WHY: They govern time and spatial scales for wave damping and energy dissipation in MHD wave based heating mechanisms.

HYPOTHESIS: Observed transverse oscillations show evidence for in situ damping. If interpreted as MHD kink waves, resonant damping offers a plausible explanation. In that case, damping vs. dissipation scales are governed by the cross-field density structuring.

THIS WORK: We present a method to combine wave observations and theory to determine the cross-field density structuring of solar atmospheric waveguides.

3. Bayesian Data Analysis



 $p(\theta|d)$: posterior; $p(d|\theta)$: likelihood function; $p(\theta)$: prior; p(d): evidence

State of knowledge on model parameters θ is a combination of what is known a priori independently of the data, $p(\theta)$, and the likelihood of obtaining a data realization actually observed as a function of the parameter vector, $p(d|\theta)$.

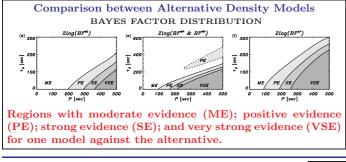
3 LEVELS OF BAYESIAN INFERENCE:

PARAMETER INFERENCE: infer unknown parameters from marginalisation of the full posterior.

MODEL COMPARISON: compare performance of alternative models in explaining data by taking posterior ratios. AVERAGING: compute averaged posterior MODEL weighted with evidence for each model, in view of data.

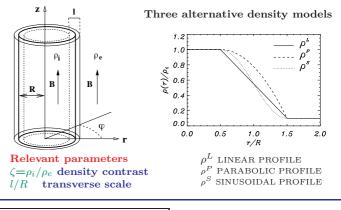
5. Model Comparison

Bayesian model comparison between density models. Bayes factors as a function of period and damping time. Assign levels of evidence to Bayes factor magnitude.



2. Cross-Field Density Models

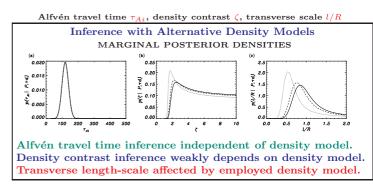
PHYSICAL MODEL: Classic one-dimensional waveguide with cross-field density variation over a length-scale l.



4. Parameter Inference

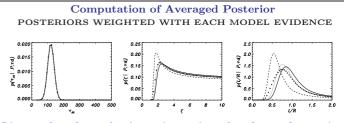
Bayesian inversion of cross-field density structuring.

Observations: loop oscillation period and damping times. Theory: resonantly damped MHD kink modes.



6. Model Averaging

Bayesian model averaging. Take into account the evidence for each model for constructing an averaged posterior.



Line styles show the inversion using the three alternative models. Symbols represent averaged posteriors, weighted with the evidence for each of the considered models.

- Conclusions
- * Inference of the unknown parameters depends on the density model used.
- Model comparison enables us to assess which density model better explains observed period and damping times.
- Model averaging offers the most general inference, using all the available information in a consistent way: prior information, data with uncertainty, model predictions, and model evidence