Example slides from a few Prosper-based seminar presentations

... with lots of graphics

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Principle of virtual displacements for a linearly elastic ring of undeformed radius R₀ and thickness h, subject to load f:

$$\int_{0}^{2\pi} \left[\gamma \,\delta\gamma + \frac{1}{12} \left(\frac{h}{R_0} \right)^2 \kappa \,\delta\kappa - \frac{1}{12} \left(\frac{h}{R_0} \right)^3 \left(\left(\frac{R_0}{h} \right) \mathbf{f} - \lambda_T^2 \frac{\partial^2 \mathbf{R}_w}{\partial t^2} \right) \cdot \delta \mathbf{R}_w \right] \,d\zeta = 0.$$



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 γ and κ represent the ring's mid-plane strain and change of curvature, respectively.



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• Load non-dimensionalised by bending stiffness K, i.e.

$$\mathbf{f}^* = K \mathbf{f}$$
 where $K = \frac{E}{12(1-\nu^2)} \left(\frac{h}{R_0}\right)^3$.

Momentum:

$$\iiint \left[-\frac{\partial p}{\partial x_i} + \frac{\partial}{\partial x_j} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \right] \psi^{(F)} \, \mathrm{d}V = 0$$

Momentum:

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[...integrate by parts.]

Momentum:

$$\begin{split} & \iiint \left[p \frac{\partial \psi^{(F)}}{\partial x_i} - \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \frac{\partial \psi^{(F)}}{\partial x_j} \right] \, \mathrm{d}V \\ & + \iint \left[-pn_i + \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) n_j \right] \psi^{(F)} \, \mathrm{d}S = 0 \end{split}$$

[...split the surface integral into $dS = dS_f + dS_{\backslash S_f}$]

Momentum:

$$\begin{split} &\iint \left[p \frac{\partial \psi^{(F)}}{\partial x_i} - \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \frac{\partial \psi^{(F)}}{\partial x_j} \right] \, \mathrm{d}V \\ &+ \iint \left[-pn_i + \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) n_j \right] \psi^{(F)} \, \mathrm{d}S_{\backslash S_f} \\ &+ \iint \left[-pn_i + \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) n_j \right] \psi^{(F)} \, \mathrm{d}S_f = 0 \end{split}$$

[Note: $\psi^{(F)} = 0$ on $S_{\backslash S_f}$]

Momentum:

$$\begin{split} &\iint \left[p \frac{\partial \psi^{(F)}}{\partial x_i} - \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \frac{\partial \psi^{(F)}}{\partial x_j} \right] \, \mathrm{d}V \\ &+ \iint \left[-pn_i + \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) n_j \right] \psi^{(F)} \, \mathrm{d}S_f = 0 \end{split}$$

[...use the traction boundary condition on the free surface S_f .]

Momentum:

$$\begin{split} \iiint \left[p \frac{\partial \psi^{(F)}}{\partial x_i} - \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \frac{\partial \psi^{(F)}}{\partial x_j} \right] \, \mathrm{d}V \\ - \iint \left[p_b + \frac{1}{\mathrm{Ca}} \kappa \right] \psi^{(F)} n_i \, \mathrm{d}S_f = 0 \end{split}$$

[...apply Weatherburn's surface divergence theorem to the surface integral.]

Momentum:

$$\begin{split} \iiint \left[p \frac{\partial \psi^{(F)}}{\partial x_i} - \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \frac{\partial \psi^{(F)}}{\partial x_j} \right] \, \mathrm{d}V \\ + \frac{1}{\mathrm{Ca}} \iint \frac{1}{g} \left[\mathbf{g}_1 \right]_i \left(g_{22} \frac{\partial \psi^{(F)}}{\partial \zeta_1} - g_{12} \frac{\partial \psi^{(F)}}{\partial \zeta_2} \right) + \frac{1}{g} \left[\mathbf{g}_2 \right]_i \left(g_{11} \frac{\partial \psi^{(F)}}{\partial \zeta_2} - g_{12} \frac{\partial \psi^{(F)}}{\partial \zeta_1} \right) \, \mathrm{d}S_f \\ - \iint p_b \psi^{(F)} n_i \, \mathrm{d}S_f - \frac{1}{\mathrm{Ca}} \oint \psi^{(F)} m_i \, \mathrm{d}s = 0 \end{split}$$

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$$\begin{split} \iiint \left[p \frac{\partial \psi^{(F)}}{\partial x_i} - \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \frac{\partial \psi^{(F)}}{\partial x_j} \right] \, \mathrm{d}V \\ + \frac{1}{\mathrm{Ca}} \iint \frac{1}{g} \left[g_1 \right]_i \left(g_{22} \frac{\partial \psi^{(F)}}{\partial \zeta_1} - g_{12} \frac{\partial \psi^{(F)}}{\partial \zeta_2} \right) + \frac{1}{g} \left[g_2 \right]_i \left(g_{11} \frac{\partial \psi^{(F)}}{\partial \zeta_2} - g_{12} \frac{\partial \psi^{(F)}}{\partial \zeta_1} \right) \, \mathrm{d}S_f \\ - \iint p_b \psi^{(F)} n_i \, \mathrm{d}S_f - \frac{1}{\mathrm{Ca}} \oint \psi^{(F)} m_i \, \mathrm{d}s = 0 \end{split}$$

Conservation of mass:

$$\iiint \frac{\partial u_i}{\partial x_i} \psi^{(P)} \, \mathrm{d} V = 0$$

Non-penetration on free surface:

$$\iint u_i n_i \psi^{(H)} \, \mathrm{d}S_f = 0$$

- Discretise using Taylor–Hood elements
- Solve matrix equations directly by frontal method (HSL 2000)



- Fully coupled discretisation of the free-surface Navier-Stokes equations and the equations of large-displacement shell theory.
- Solution by the Newton-Raphson method. Matthias Heil & Andrew L. Hazel, Department of Mathematics, University of Manchester, UK



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Self-excited oscillations during finite Reynolds number flow in a collapsible channel.

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