Variational principles: summary and problems

David Stuart

dmas2@cam.ac.uk

1 Introduction

Below is an expanded version of parts of the syllabus, intended to fix notation and terminology for doing the problems. It is not a complete summary. For learning all the material some combination of the lectures and the books

- Perfect Form, by Lemons (PUP), general
- Calculus of Variations, by Gelfand and Fomin (Dover) for calculus of variations
- Variational principles in dynamics and quantum theory, by Yourgrau and Mandelstam (Dover) for applications
- Convex optimization, Chapter 3, Boyd S., Vandneberghe L.(CUP) for convexity

should be used. (The last three books give much more detailed treatments than possible/necessary for this course.) The problems are at the end, starred problems being more difficult and not intended for supervision. Please send errors and corrections to the email address above.

2 Variational problems for functions on $\mathbb{R}^n$

$\mathbb{R}^n$ is the the vector space with typical element $\{\mathbf{x} = \sum_{i=1}^n x_i \mathbf{e}_i\}$ where $\mathbf{e}_1 = (1, 0, \dots, 0)$ etc.

2.1 Differentiability and first order conditions

If a function $f : \mathbb{R}^n \to \mathbb{R}$ has partial derivatives $\partial_i f(\mathbf{x}) = \lim_{t\to 0} t^{-1}(f(\mathbf{x} + t\mathbf{e}_i) - f(\mathbf{x}))$ which exist and are *continuous* on $\mathbb{R}^n$, it is a $C^1(\mathbb{R}^n)$ function, and is differentiable at every $\mathbf{x}$ in the sense that $f(\mathbf{x} + \mathbf{h}) - f(\mathbf{x}) - \nabla f(\mathbf{x}) \cdot \mathbf{h} = o(\|\mathbf{h}\|)$ as $\mathbf{h} \to 0$. This means it can be approximated linearly, and the derivative is the linear map on $\mathbb{R}^n$ given by $Df(\mathbf{x})(\mathbf{h}) = \nabla f(\mathbf{x}) \cdot \mathbf{h}$, which is linear in $\mathbf{h}$.

Lemma 2.1.1 (First order necessary condition) *A local minimum (or maximum) of a C^1 function is a stationary point, i.e. the derivative vanishes there.*

2.2 Second order conditions

If the partial derivatives up to order $r \in \mathbb{N}$ exist and are continuous the function lies in $C^r(\mathbb{R}^n)$. Write the second order partial derivatives $\partial^2_{ij} f = \frac{\partial^2 f}{\partial x_i \partial x_j}$. For a C^2 function $f(\mathbf{x} + \mathbf{h}) - f(\mathbf{x}) - \nabla f(\mathbf{x}) \cdot \mathbf{h} - \frac{1}{2}\sum_{ij} \partial^2_{ij} f(\mathbf{x}) h_i h_j = o(\|\mathbf{h}\|^2)$ as $\mathbf{h} \to 0$.

A real symmetric matrix is positive (resp. non-negative) if $\sum_{ij} A_{ij} v_i v_j > 0$ (resp. ≥ 0) for all non-zero vectors $\mathbf{v}$, or equivalently if all its eigenvalues are positive (resp. non-negative).

Lemma 2.2.1 (Second order necessary conditions) *If a stationary point $\mathbf{x}$ of a $f \in C^2(\mathbb{R}^n)$ is a local maximum (resp. minimum) then $\partial^2_{ij} f(\mathbf{x})$ is a non-positive (resp. non-negative) symmetric matrix.*

Lemma 2.2.2 (Second order sufficient conditions) *If $f \in C^2(\mathbb{R}^n)$ and $Df(\mathbf{x}) = 0$ and $\partial^2_{ij} f(\mathbf{x})$ is a positive (resp. negative) symmetric matrix then $\mathbf{x}$ is a strict local minimum (resp. maximum).*

2.3 Convexity

A subset $S \subset \mathbb{R}^n$ is *convex* if for any $\mathbf{x}, \mathbf{y}$ in S and any $t \in [0, 1]$ the point $(1-t)\mathbf{x} + t\mathbf{y} \in S$. A function $f : \mathbb{R}^n \to \mathbb{R}$ is *convex* if $f((1-t)\mathbf{x} + t\mathbf{y}) \le (1-t)f(\mathbf{x}) + tf(\mathbf{y})$ for any $\mathbf{x}, \mathbf{y}$ in $\mathbb{R}^n$ and any $t \in [0, 1]$ (or more generally it is convex on a convex subset S if this inequality holds for any $\mathbf{x}, \mathbf{y}$ in S and any $t \in [0, 1]$.) Further f is called *strictly convex* if the above inequality is strict whenever it can be i.e. for $0 < t < 1$ and $\mathbf{x} \neq \mathbf{y}$. *Affine* functions, i.e. functions of the form $f(\mathbf{x}) = a + \mathbf{b} \cdot \mathbf{x}$, are examples of functions which are convex but not strictly convex.

Lemma 2.3.1 (Convexity: first order conditions) *$f \in C^1(\mathbb{R}^n)$ convex $\iff$ $f(\mathbf{y}) \ge f(\mathbf{x}) + \nabla f(\mathbf{x}) \cdot (\mathbf{y} - \mathbf{x})$ for all $\mathbf{x}, \mathbf{y}$ $\iff$ $(\nabla f(\mathbf{x}) - \nabla f(\mathbf{y})) \cdot (\mathbf{x} - \mathbf{y}) \ge 0$, for all $\mathbf{x}, \mathbf{y}$.*

As a corollary, this implies that if $\mathbf{x}$ is a stationary point of a convex C^1 function then it is a global minimum.

Also this shows that C^1 convex functions lie above their tangent planes.

Lemma 2.3.2 (Strict convexity: first order conditions) *$f \in C^1(\mathbb{R}^n)$ strictly convex $\iff$ $f(\mathbf{y}) > f(\mathbf{x}) + \nabla f(\mathbf{x}) \cdot (\mathbf{y} - \mathbf{x})$ for all $\mathbf{x} \neq \mathbf{y}$, $\iff$ $(\nabla f(\mathbf{x}) - \nabla f(\mathbf{y})) \cdot (\mathbf{x} - \mathbf{y}) > 0$ for all $\mathbf{x} \neq \mathbf{y}$.*

As a corollary, this implies that if $f \in C^1(\mathbb{R}^n)$ is strictly convex, the equation $\nabla f(\mathbf{x}) = \mathbf{b}$ can have no more than one solution. In particular, stationary points for strictly convex functions are unique.

Lemma 2.3.3 (Convexity: necessary and sufficient second order condition) *$f \in C^2(\mathbb{R}^n)$ is convex $\iff$ $\partial^2 f_{ij}(\mathbf{x}) \ge 0 \; \forall \mathbf{x}$.*

Lemma 2.3.4 (Strict convexity: sufficient second order condition) *$f \in C^2(\mathbb{R}^n)$ is strictly convex if $\partial^2 f_{ij}(\mathbf{x}) > 0 \; \forall \mathbf{x}$.*

2.4 Lagrange multipliers

Consider a hypersurface $\mathcal{C} = \{\mathbf{x} \in \mathbb{R}^n : g(\mathbf{x}) = 0\}$ where $g \in C^2(\mathbb{R}^n)$ satisfies $\nabla g(\mathbf{x}) \neq 0$ for all $\mathbf{x}$. The vector $\mathbf{n}(\mathbf{x}) = \nabla g(\mathbf{x}) / \|\nabla g(\mathbf{x})\|$ is everywhere normal to $\mathcal{C}$.

Lemma 2.4.1 *Let $f \in C^2(\mathbb{R}^n)$. Then if $f\big|_{\mathcal{C}}$ has a maximum (resp. minimum) at $\mathbf{x} \in \mathcal{C}$ then there exists $\lambda \in \mathbb{R}$ such that $\nabla h(\mathbf{x}, \lambda) = 0$ where $h(\mathbf{x}, \lambda) = f(\mathbf{x}) - \lambda g(\mathbf{x})$, and furthermore $\sum_{ij} \partial^2 h_{ij}(\mathbf{x}, \lambda) v_i v_j$ is ≤ 0 (resp. ≥ 0) for all vectors $\mathbf{v}$ such that $\mathbf{v} \cdot \mathbf{n} = 0$.*

The function h is the Lagrange augmented function. The number λ is called the Lagrange multiplier.

For problems with several constraints $\{g_\alpha\}_{\alpha=1}^{l}$, assume they are independent (in the sense that the matrix $\partial_i g_\alpha(\mathbf{x})$ has rank l) and consider $h(\mathbf{x}, \lambda) = f(\mathbf{x}) - \sum \lambda_\alpha g_\alpha(\mathbf{x})$, and the corresponding result holds.

2.5 Legendre Transform

Given $f : \mathbb{R}^n \to \mathbb{R}$ its Legendre transform $g = f^*$ is given by $g(\mathbf{p}) = \sup(\mathbf{p} \cdot \mathbf{x} - f(\mathbf{x}))$, defined only for $\mathbf{p}$ such that this supremum is finite. The Legendre transform is automatically convex, and the generalized Young inequality

$$f(\mathbf{x}) + g(\mathbf{p}) \ge \mathbf{p} \cdot \mathbf{x}$$

follows immediately from the definition of $g = f^*$. The inequality $xy \le a^{-1}x^a + b^{-1}y^b$ for $a^{-1} + b^{-1} = 1$ and $a > 1$ is a well-known special case (see exercises).

Theorem 2.5.1 *If f is convex $f^{**} = f$.*

This implies that a convex functions can always be expressed as a supremum of a family of affine functions. This fact also follows from lemma 2.3.1 - just take the family of affine functions to be those lying below the graph of f, and show that this family is non-empty (since it contains the tangent planes) and the supremum gives back f.

3 Variational problems for functionals

3.1 Generalities on functionals

Terminology: $C_0^\infty(a,b)$ is the space of smooth functions whose support is a closed bounded subset of the interval (a,b). The support of a function is the closure of the set where it is non-zero. A bump function in an interval $(x_0-\epsilon, x_0+\epsilon)$ is a function $b \in C_0^\infty(\mathbb{R})$ which is positive in $(x_0-\epsilon, x_0+\epsilon)$ and vanishes for $|x-x_0| \geq 0$. These can be constructed by translating and scaling the bump function on the interval $(-1,1)$ given by $e^{\frac{-1}{(1-x^2)^2}}$ for $x^2 < 1$ and extended with value zero outside the interval (exercise).

A functional is just a function on a set of functions. Since spaces of funtions can be topologized in many inequivalent ways, the continuity and differentiability of functionals is more subtle. For example the Dirac functional $\delta_0(\phi) = \phi(0)$ is continuous on $C(\mathbb{R})$ with the topology determined by the supremum (L^∞) norm $\|\phi\|_{L^\infty} = \max|\phi(x)|$, but not with respect to that determined by the L^2 norm (defined by $\|\phi\|_{L^2}^2 = \int |\phi(x)|^2 dx$). In contrast all norms on finite dimensional vector spaces define equivalent topologies. For this reason we will study differentiability of functionals only one direction at a time, i.e. will consider directional derivatives. The following lemma is useful:

Lemma 3.1.1 *Let $g \in C([a,b])$ have the property that $\int_a^b g(x)\phi(x)dx = 0$ for all $\phi \in C_0^\infty(a,b)$. Then g vanishes identically throughout the interval.*

Proof This follows using continuity and bump functions (exercise).

A slight variation on this lemma states that if $\int_a^b g(x)\phi'(x)dx = 0$ for all $\phi \in C_0^\infty(a,b)$ (notice the prime on ϕ) then g is a constant.

3.2 Directional derivatives of functionals

Let $f : \mathbb{R}^3 \to \mathbb{R}$ be smooth and consider the functional $I[y] = \int_a^b f(x,y,y')dx$ as a function on the space V of C^1 functions with $y(a) = \alpha$ and $y(b) = \beta$. Assume $I[y] = \min_{w\in V} I[w]$ then the function $i(\epsilon) = I[y+\epsilon\phi]$ has a minimum at $\epsilon = 0$ for all $\phi \in C_0^\infty(a,b)$, so that $i'(0) = DI[y](\phi) = \int_a^b (f_y\phi + f_{y'}\phi')dx$ vanishes for each such ϕ. The quantity $DI[y](\phi)$ is called the directional derivative of the functional I along ϕ. Assume further that $y \in C^2(a,b)$, then integration by parts gives, for $\phi \in C_0^\infty(a,b)$:

$$DI[y](\phi) = \int_a^b \big(f_y - \frac{d}{dx}(f_{y'})\big)\phi dx$$

and by lemma 3.1.1, we deduce that

$$\frac{\delta I}{\delta y} = \big(f_y - \frac{d}{dx}(f_{y'})\big) = 0$$

for y a C^2 minimizer. The quantity $\frac{\delta I}{\delta y}$ is sometimes known as the functional derivative, and the mapping $DI[y] : \phi \mapsto DI[y](\phi)$ is called the first variation, and sometimes written δI. The equation

$$\frac{d}{dx}(f_{y'}) - f_y = 0$$

is the Euler-Lagrange equation associated to I. In fact it holds in integrated form $f_{y'} - \int_a^x f_y = constant$ even for C^1 minimizers - this can be deduced using the variation on lemma 3.1.1 mentioned above and an integration by parts trick.

4 Applications

4.1 Fermat principle

Light rays follows paths γ which minimize (or make stationary) the time $T = \int_\gamma \frac{1}{c} ds$, where $ds = \|\dot{\gamma}(t)\| dt$ is the element of arclength along γ and c is the speed of light, which may depend on position.

4.2 Geodesics

A (smooth) Riemannian metric on an open subset $U \subset \mathbb{R}^n$ is a (smooth) function $\mathbf{x} \mapsto g_{ij}(\mathbf{x})$ from U into the space of real positive symmetric $n \times n$ matrices. The geodesics are C^2 curves which are stationary points for the length functional $l[\mathbf{x}] = \int (g_{ij}\dot{x}_i\dot{x}_j)^{\frac{1}{2}} dt$, (where summation convention is understood.) They solve the equation

$$\frac{d}{dt}\Big(\frac{g_{ij}\dot{x}_j}{\sqrt{g_{lm}\dot{x}_l\dot{x}_m}}\Big) - \frac{1}{2}\frac{\partial g_{jk}}{\partial x_i}\frac{\dot{x}_j\dot{x}_k}{\sqrt{g_{lm}\dot{x}_l\dot{x}_m}} = 0.$$

Since the length functional is parametrization invariant, it is possible to choose the parameter t to be the arclength so that $g_{ij}\dot{x}_i\dot{x}_j = 1$, in which case the equation simplifies to

$$\frac{d}{dt}\Big(g_{ij}\dot{x}_j\Big) - \frac{1}{2}\frac{\partial g_{jk}}{\partial x_i}\dot{x}_j\dot{x}_k = 0.$$

This equation is the Euler-Lagrange equation associated to the "kinetic energy integral" $I[\mathbf{x}] = \int g_{ij}\dot{x}_i\dot{x}_j \, dt$, so that an alternative definition of geodesic is a C^2 curve for which I is stationary- this definition automatically gives geodesics with a parametrization for which $g_{ij}\dot{x}_i\dot{x}_j = constant$, by the second conservation law (Noether theorem).

4.3 Lagrangian and Hamiltonian mechanics

The equation

$$m\ddot{\mathbf{x}} + \nabla V = 0 \tag{4.1}$$

for a particle of mass $m > 0$ moving in a potential $V(\mathbf{x})$ can be derived as the Euler-Lagrangian associated to the action functional $S[\mathbf{x}] = \int L(\mathbf{x}, \dot{\mathbf{x}}) dt$, where $L(\mathbf{x}, \dot{\mathbf{x}}) = \frac{1}{2}m\|\dot{\mathbf{x}}\|^2 - V(\mathbf{x})$ is called the Lagrangian. This is the *Lagrangian formulation* of Newtonian mechanics. Since L is convex in $\dot{\mathbf{x}}$ the Legendre transformation in the velocity variables gives a function $H(\mathbf{x}, \mathbf{p}) = \sup_{\dot{\mathbf{x}}} (\mathbf{p} \cdot \dot{\mathbf{x}} - L(\mathbf{x}, \dot{\mathbf{x}}))$ from which L can be recovered just by applying the Legendre transform again. The function H is the Hamiltonian, and gives an equivalent formulation of (4.1) in *Hamiltonian form* :

$$\dot{x}_j = \frac{\partial H}{\partial p_j}, \quad \dot{p}_j = -\frac{\partial H}{\partial x_j}$$

Convexity of the Lagrangian in the velocity variables ensures the possibility of going back and forth between the two formulations. Notice that the supremum in the definition of H is attained at the unique $\dot{\mathbf{x}}$ given by $\mathbf{p} = m\dot{\mathbf{x}}$: this defines the *conjugate momentum.*

5 The second variation

Consider the functional $I[y] = \int_a^b f(x, y, y')dx$ on the space V of C^1 functions with $y(a) = \alpha$ and $y(b) = \beta$. Let V_0 be the vector space of C^1 functions with $y(a) = 0$ and $y(b) = 0$.

Definition 5.0.1 *A function $y \in V$ is a* weak *local minimizer for I if $I[y + \phi] \geq I[y]$ for all $\phi \in V_0$ with $\|\phi\|_{C^1} = \max_{[a,b]} |\phi(x)| + \max_{[a,b]} |\phi'(x)|$ sufficiently small. If the inequality is strict for such ϕ not identically zero, the minimum is strict. There is a corresponding definition for weak maximum.*

(There is also a corresponding notion of *strong* minimizer for I with the norm $\|\phi\|_{C^0} = \max_{[a,b]} |\phi(x)|$ used instead of $\|\phi\|_{C^1}$, see Chapter 6 in Gelfand and Fomin.)

Assuming, as always, that f is smooth, Taylor's theorm implies that $\forall \epsilon > 0 \, \exists \delta(\epsilon) > 0$ such that for all $x \in [a, b]$ and $\|\phi\|_{C^1} < \delta$:

$$|f(x, y + \phi, y' + \phi') - f(x, y, y') - \phi f_y(x, y, y') - \phi' f_{y'}(x, y, y') - Q| < \epsilon(|\phi|^2 + |\phi'|^2)$$

where Q is the quadratic part of the Taylor expansion

$$Q = \frac{1}{2}\big(\phi^2 f_{yy}(x, y, y') + 2\phi\phi' f_{yy'}(x, y, y') + \phi'^2 f_{y'y'}(x, y, y')\big).$$

Here ϕ, ϕ' are evaluated with argument x. From this follows a corresponding Taylor expansion for the functional I:

$$I[y + \phi] = I[y] + DI[y](\phi) + \frac{1}{2}D^2I[y](\phi) + \mathcal{R}$$

where $|\mathcal{R}| < \epsilon \int_a^b (|\phi|^2 + |\phi'|^2)dx$ for $\|\phi\|_{C^1} < \delta(\epsilon)$. The quadratic part

$$D^2I[y](\phi) = \int \big(\phi^2 f_{yy}(x, y, y') + 2\phi\phi' f_{yy'}(x, y, y') + \phi'^2 f_{y'y'}(x, y, y')\big)dx$$

is sometimes called the second variation, and denoted $\delta^2 I$. From this we can read off:

Lemma 5.0.2 (Necessary conditions) *If $y \in V$ is a weak minimum then $DI[y](\phi) = 0 \forall \phi \in V_0$ and the second variation $D^2I[y](\phi) \geq 0 \forall \phi \in V_0$.*

Lemma 5.0.3 (Sufficient conditions) *Assume $y \in V$ is such that $DI[y](\phi) = 0 \forall \phi \in V_0$ and the second variation satisfies, for some $c > 0$,*

$$D^2I[y](\phi) \geq c\int_a^b (|\phi|^2 + |\phi'|^2)dx \ \forall \phi \in V_0. \tag{5.2}$$

Then y is a weak local minimum.

Recall that if y is C^2 it solves the Euler-Lagrange equation if $DI[y](\phi) = 0 \forall \phi \in V_0$. The fact that $\phi(a) = 0 = \phi(b)$ means that in this case the formula for the second variation can be put into Sturm-Liouville form:

$$D^2I[y](\phi) = \int_a^b \big(p(x)\phi'^2 + q(x)\phi^2\big)dx$$

where $p(x) = f_{y'y'}(x, y(x), y'(x))$ and $q(x) = f_{yy}(x, y(x), y'(x)) - \frac{d}{dx}(f_{yy'}(x, y(x), y'(x))$. One explicit approach to determining whether (5.2) holds for some $c > 0$ is to calculate the eigenvalues of the Sturm-Liouville operator $L = -(p\phi')' + q\phi$. There are also general conditions which ensure (5.2): it is sufficient that $p(x) > 0$ on $[a, b]$ and that there are no conjugate points, i.e. there are no points $\tilde{a} \in (a, b]$ such that there is a non-trivial function h such that $Lh = 0$ and $h(a) = 0 = h(\tilde{a})$. This is proved in theorem 1 in section 26 of Gelfand and Fomin.

6 Example sheet 1

1. Prove that if $f \in C^1(\mathbb{R})$ has only one stationary point which is a local minimum, then it must be a global minimum. Give a counter-example to show this is false in $\mathbb{R}^2$.
2. * Prove that a real symmetric matrix A_{ij} is > 0, in the sense defined in §2.2, iff all its eigenvalues are positive.
3. * Prove, using the Bolzano-Weierstrass property, but without using diagonalizability, that if a real symmetric matrix $A_{ij} > 0$ then $\sum_{ij} A_{ij} v_i v_j \geq c\|\mathbf{v}\|^2$ for some $c > 0$. (After analysis II).
4. * Let $f \in C^2(\mathbb{R}^2)$ have a stationary point $\mathbf{x} = (x^1, x^2)$ and let $A_{ij} = \partial^2_{ij} f(\mathbf{x})$. Show that $A_{11} + A_{22} > 0$ and $A_{11}A_{22} - A_{12}^2 > 0$ implies $A_{ij} > 0$ so that $\mathbf{x}$ is a strict local minimum.
5. Given $f : \mathbb{R}^n \to \mathbb{R}$ define its epigraph to be $E_f = \{(\mathbf{x}, z) : z \geq f(\mathbf{x})\} \subset \mathbb{R}^{n+1}$. Show that f is a convex function iff E_f is convex subset.
6. Give an example of a function which is strictly convex but whose second derivative is not everywhere > 0.
7. Show that x^2/y is convex on the upper half plane $(x, y) : y > 0$. * Show that if $f \in C^2(\mathbb{R})$ is convex then the function $yf(y^{-1}x)$ is convex on $(x, y) : y > 0$.
8. Given a family $L^\alpha(\mathbf{x})$ of affine functions indexed by $\alpha \in \mathbb{N}$, (or in fact an arbitrary index set) show that $f(\mathbf{x}) = \sup_\alpha L^\alpha(\mathbf{x})$ is convex. * Show that all C^1 convex functions arise in this way.
9. * With L^α as in the previous question, show that the function $f(\mathbf{x}) = \inf_\alpha L^\alpha(\mathbf{x})$ is concave.
10. For A any real symmetric $n \times n$ matrix consider $\lambda(A) = \sup_{\mathbf{v} \in \mathbb{R}^n : \|\mathbf{v}\| = 1} \mathbf{v} \cdot (A\mathbf{v})$. Use Lagrange multipliers to show that $\lambda(A)$ is the largest eigenvalue of A. * Also prove that λ is a convex function of A. (Assume the fact from analysis II that a continuous function on the sphere $\{\mathbf{v} \in \mathbb{R}^n : \|\mathbf{v}\| = 1\}$ attains its supremum.)
11. The area A of a triangle with sides a, b, c is given by
$$A = \sqrt{[s(s-a)(s-b)(s-c)]}, \quad \text{where } s = \tfrac{1}{2}(a + b + c).$$
(i) Show that of all triangles of given perimeter $2s$, the triangle of largest area is equilateral.
(ii) Find (in terms of the perimeter) the largest possible area of a right-angled triangle of given perimeter.
12. Prove that the Legendre transform of a function is always convex.
13. Find the Legendre transform of $f(x) = e^x$, (giving its domain also). Find the Legendre transform of $f(x) = a^{-1}x^a, a > 1$ defined on $x > 0$, and deduce $xy \leq a^{-1}x^a + b^{-1}y^b$ for $a^{-1} + b^{-1} = 1$ (Young).
14. * Find the Legendre transform of $f(\mathbf{x}) = \frac{1}{2}\sum_{ij} A_{ij} x_i x_j$ where A_{ij} is a positive symmetric matrix.
15. For an ideal gas, the internal energy $U = U(S, V)$ as a function of entropy and volume is
$$U = U_0 + \alpha n R T_0 \Big[(\frac{V_0}{V})^{\frac{1}{\alpha}} e^{\frac{S - S_0}{\alpha n R}} - 1 \Big]$$
for some constants $U_0, T_0, V_0, S_0, \alpha, n, R$. Calculate the pressure and temperature (defined by $dU = TdS - pdV$), and verify that $pV = nRT$ (ideal gas equation of state). Calculate also the constant volume heat capacity $C_V = T\frac{\partial S}{\partial T}|_V$, and comment on the convexity of U as a function of S. Calculate the Helmholtz free energy $F = F(T, V)$ defined by $F(T, V) = \min_S(U(S, V) - TS)$. [*In this formula T is a fixed number - do not substitute for T from the formula you derived in the first part of the question!*]
16. * For black body radiation the internal energy $U = U(S, V)$ as a function of entropy and volume is
$$U(S, V) = \Big(\frac{3S}{4}\Big)^{\frac{4}{3}} \Big(\frac{1}{CV}\Big)^{\frac{1}{3}}$$
where C is a constant. Calculate P, T as in the previous question and verify that the energy density (i.e. the internal energy per unit volume) is CT^4 and that the value of the pressure is $\frac{1}{3}$ of the energy density. Calculate the Helmholtz free energy $F = F(T, V)$ defined by $F(T, V) = \min_S(U(S, V) - TS)$, and show that its value is $-\frac{1}{3}U$.

17. Show that the Euler-Lagrange equation of the functional

$$I[y] = \int_{x_1}^{x_2} f(y, y')dx = 0, \quad y(x_1) = y_1 \text{ and } y(x_2) = y_2 \text{ fixed}$$

has the first integral $f(y, y') - y' \frac{\partial}{\partial y'} f(y, y') =$ constant. The curve assumed by a uniform cable which is suspended between two points $(-a, b)$ and (a, b) minimises the potential energy

$$\int_{-a}^{a} y(1 + y'^2)^{1/2} dx$$

subject to the constraint that its length remains fixed,

$$\int_{-a}^{a} (1 + y'^2)^{1/2} dx = 2L,$$

where $L > a$. Using the Lagrange multiplier method, show that the curve is a catenary

$$y - y_0 = c \cosh \left(\frac{x - x_0}{c} \right),$$

where c, x_0 and y_0 are constants. * Find an equation for c, and show that it has a unique positive solution.

18. Write down the Euler-Lagrange equation for the functional

$$I[u] = \int_{-\infty}^{+\infty} \frac{1}{2} u'^2 + (1 - \cos u) dx$$

and find all solutions which satisfy $\lim_{x \to -\infty} u(x) = 0$ and $\lim_{x \to +\infty} u(x) = 2\pi$.
Show that if $u \in C^1(\mathbb{R})$ satisfies $\lim_{x \to -\infty} u(x) = 0$ and $\lim_{x \to +\infty} u(x) = 2\pi$

$$I[u] = \frac{1}{2} \int_{-\infty}^{+\infty} (u' - 2 \sin \frac{u}{2})^2 \, dx + 8.$$

Deduce that a lower bound for $I[u]$ amongst such functions is 8, and give a *first order* differential equation which u must satisfy in order to realize this lower bound. Show that any solution of this first order equation solves the Euler-Lagrange equation you derived in the first part of the question. Give all the functions satisfying $I[u] = 8$.

19. * The brachistochrone problem leads to the study of the functional $I[y] = \int_0^X \frac{\sqrt{(1+y'^2)}}{\sqrt{y}} dx$ for C^1 curves $y = y(x) > 0$ such that $y(0) = 0$ and $y(X) = Y > 0$. Make the change of variables $y = \phi^2$, and show that $J[\phi] = I[\phi^2] = \int_0^X (\phi^{-2} + 4\phi'^2)^{\frac{1}{2}} dx$. Show that the function $l(u, v) = (u^{-2} + 4v^2)^{\frac{1}{2}}$ is strictly convex on $\{(u, v) : u > 0\} \in \mathbb{R}^2$. (This can be used to prove the cycloid solution which we obtained as a solution of the Euler-Lagrange equation, which is only a necessary condition for a minimizer, actually does minimze I.) Write down the Euler-Lagrange equation for $J[\phi]$, solve for ϕ and show that the solutions are cycloids, as for the Euler-Lgrange equation for I.

20. Obtain the Euler-Lagrange equation for the function $x(t)$ that makes stationary the integral

$$\int_{t_1}^{t_2} f(t, x(t), \dot{x}(t), \ddot{x}(t)) dt$$

for fixed values of both $x(t)$ and $\dot{x}(t)$ at both $t = t_1$ and $t = t_2$.
Find the function $x(t)$ with $x(1) = 1, \dot{x}(1) = -2, x(2) = \frac{1}{4}$ and $\dot{x}(2) = -\frac{1}{4}$, that minimises $\int_1^2 t^4 [\ddot{x}(t)]^2 dt$, including a demonstration that it is a minimizer (not just a stationary point) for the integral.

7 Example sheet 2

1. Consider the problem of maximizing the area $\frac{1}{2}\int_0^{2\pi}(x\dot{y} - y\dot{x})dt$ enclosed by a *closed* curve of fixed length $l = \int_0^{2\pi}(\dot{x}^2 + \dot{y}^2)^{\frac{1}{2}}dt$. Write down and solve the Euler-Lagrange equations for this constrained problem in parametric form.
2. Consider the problem of minimizing $I[\psi] = \int_{-\infty}^{+\infty}\left(\psi'^2 + x^2\psi^2\right)dx$ amongst functions with $\int \psi^2 dx = 1$.
   (i) Write down the corresponding Euler-Lagrange equation for this constrained problem.
   (ii) Show that under the assumption $x\psi(x)^2 \to 0$ as $x \to +\infty$ it is possible to write $I[\psi] = 1 + \int_{-\infty}^{+\infty}(\psi' + x\psi)^2 dx$, and hence show that amongst such functions the minimum value of I is 1 and is attained on a function which should be given explicitly. Verify that this function satisfies the Euler-Lagrange equation you wrote down in (i), for an appropriate value of the Lagrange multiplier.
   (iii) * Use the method of power series solutions to solve the Euler-Lagrange equation in (i), and comment on the relation with the minimizing function you obtained in (ii). (Here you may find it useful to rewrite the Euler-Lagrange equation as an equation for $f = e^{\frac{x^2}{2}}\psi(x)$).
3. Obtain the Euler-Lagrange equations associated to the functionals
   (i) $I[u] = \int(\frac{1}{2}u_t^2 - F(u_x))dxdt$,
   (ii) * $I[u] = \frac{1}{2}\int(u_t^2 - c(u)^2u_x^2)dxdt$,
   where $u = u(t,x)$ is a function on $\mathbb{R}^2$, where F and c are given smooth functions.
4. Obtain the Euler-Lagrange equations associated to the functionals
   (i) $I[u] = \int(|\nabla u|^2 + e^{2u})dxdy$,
   where $u = u(x,y)$ is a function on $\mathbb{R}^2$, and
   (ii) * $I[u] = \int(\det Du)dxdy$,
   where $u : \mathbb{R}^2 \to \mathbb{R}^2$, and $\det Du$ means the Jacobian determinant. What is unusual about the second example?
5. Consider $I[y] = \int_{-1}^{+1}(xy')^2dx$ for $y(x)$ in the set S of C^1 functions such that $y(1) = 1$ and $y(-1) = -1$. By considering $y_\epsilon(x) = \frac{\arctan x/\epsilon}{\arctan 1/\epsilon}$ show that $\inf_{y\in S} I[y] = 0$. Show that this infimum is not attained in S.
6. Consider $I[y] = \int_{-1}^{1}(1 - y_x^2)^2dx$ with $y = y(x)$ lying in the set S' of *piecewise* C^1 functions such that $y(\pm 1) = 1$. By considering $y(x) = |x|$ show that the $\min_{y\in S'} I[y] = 0$. Does there exist a C^1 (not just piecewise C^1) function for which this value is attained?
7. The smooth functions $p(x), q(x)$ and $w(x) \geq 0$ are prescribed on $[a,b]$, with w not identically zero. Show that the following three conditions are equivalent for C^2 functions $y(x)$ satisfying $y(a) = 0 = y(b)$:
   (i) y satisfies: $(py')' - qy = -\lambda wy$;
   (ii) $I[u] = \int_a^b(pu'^2 + qu^2)dx$ is stationary at $u = y$ amongst C^1 functions satisfying the boundary conditions and subject to the constraint $\int_a^b wu^2dx =$ constant;
   (iii) $Q[u] = \int_a^b(pu'^2 + qu^2)dx/\int_a^b wu^2dx$, is stationary amongst C^1 functions satisfying the boundary conditions at $u = y$. What is the value of $Q[y]$?
   (Assume that y is not identically zero, and that $w > 0$ in (a,b) so that so that the denominator $\int_a^b wy^2dx$ in (iii) is non-zero.)
8. Let $\mathbf{x}(t) \in \mathbb{R}^3$ be a curve which is constrained to lie on the sphere $S^2 = \{\mathbf{x} : \|\mathbf{x}\| = 1\}$. Use the Lagrange multiplier function formalism to obtain the following Euler-Lagrange equation
$$\ddot{\mathbf{x}} + \|\dot{\mathbf{x}}\|^2\mathbf{x} = 0 \tag{7.3}$$
   for the problem of minimizing $I[\mathbf{x}] = \int\|\dot{\mathbf{x}}\|^2dt$ amongst curves satisfying the constraint $\mathbf{x}(t) \in S^2$. Show that the solutions of the Euler-Lagrange equation lie on a plane through the origin (they are great circles.)
9. * As an alternative approach to (7.3), let θ, ϕ be standard angles given by spherical coordinates, and assume the curve on S^2 is given as $\phi = \phi(\theta)$. Show that the length integral

is $l[\phi] = \int (1 + \sin^2\theta\phi'^2)^{\frac{1}{2}} d\theta$. Obtain the Euler-Lagrange equation associated to this functional, integrate it and show that the resulting solutions are great circles.

10. * Obtain (7.3) by considering variations of the curve $\mathbf{x}(t)$ of the form

$$\mathbf{x}^\epsilon(t) \equiv \frac{\mathbf{x}(t) + \epsilon\mathbf{z}(t)}{\|\mathbf{x}(t) + \epsilon\mathbf{z}(t)\|}$$

which lie on S^2 and requiring $\frac{d}{d\epsilon} I[\mathbf{x}^\epsilon] = 0$ at $\epsilon = 0$ for every smooth $\mathbf{z}(t)$.

11. * For the brachistochrone problem, show that the minimum travel time between two points at the same level and a distance l apart is $(2\pi l/g)^{1/2}$ (for a bead moving on a wire under the action of gravity without friction. The acceleration due to gravity is g.)
12. * For the brachistochrone problem, show that there is a unique arc of a cycloid (without a cusp) from the starting point $(0, 0)$ to a point (X, Y) below the starting point.
13. In an optical medium filling the region $0 < y < h$, the speed of light is

$$c(y) = \frac{c_0}{(1 - ky)^{1/2}} \quad (0 < k < 1/h).$$

Show that the paths of light rays in the medium are parabolic. Show also that, if a ray enters the medium at $(-x_0, 0)$ and leaves it at $(x_0, 0)$, then

$$(kx_0)^2 = 4ky_0(1 - ky_0),$$

where y_0 $(< h)$ is the greatest value of y attained on the ray path.

14. * Hamilton's Principle is applicable also to the *relativistic* dynamics of a charged particle in an electromagnetic field. The appropriate choice of Lagrangian $L[t, \mathbf{x}(t), \dot{\mathbf{x}}(t)]$ is

$$L = -m_0 c^2 \gamma^{-1} + qA_0 + q\mathbf{v} \cdot \mathbf{A},$$

with the Lorentz factor $\gamma = (1 - v^2/c^2)^{-1/2}$, and where $\mathbf{x}$ is the position and $\mathbf{v} = \dot{\mathbf{x}}(t)$ is the velocity of a particle of rest-mass m_0 and charge q in fields determined by a given scalar potential $A_0(\mathbf{x}, t)$ and a given vector potential $\mathbf{A}(\mathbf{x}, t)$. Verify that the Euler-Lagrange equations, with this choice of L, yield the equation of motion

$$\frac{d}{dt}(m_0\gamma\mathbf{v}) = q(\mathbf{E} + \mathbf{v} \times \mathbf{B}),$$

where the electric field $\mathbf{E} = \nabla A_0 - \frac{\partial \mathbf{A}}{\partial t}$ and the magnetic field $\mathbf{B} = \nabla \times \mathbf{A}$.

15. * With $\mathbf{E}$ and $\mathbf{B}$ as in the previous question, obtain the Euler-Lagrange equations associated to the functional $I[A] = \int (\mathbf{E}^2 - \mathbf{B}^2) dxdt$. (This gives two of Maxwell's equations).
16. For the length functional for curves in the plane $I[y] = \int_a^b (1 + y'^2)^{\frac{1}{2}} dx$, with $y(a) = \alpha$ and $y(b) = \beta$ show that the straight line $y = y_0(x)$ joining (a, α) to (b, β) solves the Euler-Lagrange equation. Compute the second variation of I at y_0 and show that it is positive.
17. For $I[y] = \int_a^b (y'^2 + y^4) dx$ with $y(a) = \alpha$, $y(b) = \beta$ find the Euler-Lagrange equation and the second variation. For the case $\alpha = 0 = \beta$ write down the solution of the Euler-Lagrange equation and the second variation explicitly, and show that the second variation is strictly positive.
18. For $I[y] = \int_0^1 \left(\frac{1}{2}y'^2 + F(y)\right) dx$ with $y(0) = 0 = y(1)$. Assume that $F \in C^2(\mathbb{R})$ satisfies $F'(0) = 0$. Write down the associated Euler-Lagrange equation, and show that $y_0(x) = 0$ is a solution. Find the second variation. Give (i) a condition on $F''(0)$ which ensures that the second variation is positive, and (ii) a condition which ensures the second variation has at least one negative eigenvalue.

8 Additional questions

1. The following questions from recent methods exams are good for practice with Lagrange multipliers, Euler-Lagrange equations etc: 2008 1/II/14D and 2/I/5D, 2007: 3/I/6E and 4/II/16E, 2006: 2/I/5A and 4/II/16B.
2. At how many points in R^3 does the function
$$\phi(x_1,x_2,x_3)=\tfrac{1}{4}(x_1^4+x_2^4+x_3^4)-x_2x_3-x_3x_1-x_1x_2$$
take its minimum value? Show that this least value is -3. Show also that ϕ has one saddle point, at which the surface of vanishing ϕ is tangent to a double cone of semi-angle $\tan^{-1}(\sqrt{2})$.
3. Find the maximum volume of a rectangular parallelopiped inscribed inside an ellipsoid $x^2/a^2+y^2/b^2+z^2/c^2=1$.
4. *Show that if $f:(a,b)\to\mathbb{R}$ is convex the one-sided difference quotients $\phi_x(h)=h^{-1}(f(x+h)-f(x))$, $h>0$ are non-decreasing i.e. $\phi_x(h)\le\phi_x(k)$ if $0<h\le k$. Deduce that the right derivative $D^+f(x)\equiv\lim_{h\to 0+,h>0}\phi_x(h)$ exists in $-\infty\cup\mathbb{R}$. By considering $\phi_{x-l}(l)$ for $l>0$ show that for any $x\in\mathbb{R}$ the $\phi_x(h)$ are bounded below for $h>0$ so that the right derivative $D^+f(x)$ just defined is finite for all x for a convex function with domain $\mathbb{R}$ like f. Show that if the domain of f is only an interval that the same is true for x an interior point of the interval. Give an example of a convex function defined only on $[0,\infty)$ for which the right derivative at $x=0$ is $-\infty$.
5. *Consider $I[y]=\int_a^b f(x,y,y')dx$ with $y(a)=\alpha, y(b)=\beta$, where f is a smooth function $f:\mathbb{R}^3\to\mathbb{R}$. Consider variations of the form $y^\epsilon(x)=y(x+\epsilon\phi(x))$ where $\phi\in C_0^\infty(a,b)$, and compute $\frac{d}{d\epsilon}I[y^\epsilon]|_{\epsilon=0}$; show that if y is such that this is zero for all such ϕ then the conservation law $y'f_{y'}-f=$ *constant* holds.
6. Consider the area of a surface obtained by rotating a curve $y=y(x)$ with $y(a)=\alpha$ and $y(b)=\beta$ about the y-axis. Write down an integral for the area, and solve the associated Euler-Lagrange equation.
7. Consider $I[y]=\int_a^b f(x,y,y')dx$ with $y(a)=\alpha$ but $y(b)$ is not fixed. As usual f is a smooth function $f:\mathbb{R}^3\to\mathbb{R}$. Show that if $y\in C^2$ minimizes I amongst C^1 functions with $y(a)=\alpha$ then as well as the Euler-Lagrange eqyation it satisfies the additional boundary condition $f_{y'}(b,y(b),y'(b))=0$. Together with the initial condition this gives the correct number of boundary conditions for the second order Euler-Lagrange equation. Boundary conditions which are a consequence of a variational problem in this way are called *natural.* What is the natural boundary condition for $I[u]=\int_B\big(\frac{1}{2}|\nabla u|^2-gu\big)dx$ where B is the unit ball in $\mathbb{R}^n$?
8. Find the Hamiltonian obtained via the Legendre transformation from the Lagrangian $L=\frac{1}{2}g_{ij}\dot{x}_i\dot{x}_j-V(\mathbf{x})$ (summation convention assumed).
9. Find the Hamiltonian for the relativistic dynamics of a charged particle by applying the Legendre transformation to the Lagrangian $L=-m_0c^2\gamma^{-1}-qA_0-q\mathbf{v}\cdot\mathbf{A}$, which appears in sheet II.
10. Write down the Euler-Lagrange equation associated to $I[u]=\int_{-\infty}^{+\infty}\frac{1}{2}u'^2+(1-\cos u)dx$ and show that $u(x)=4\arctan e^x$ is a solution with boundary conditions $\lim_{x\to-\infty}u(x)=0$ and $\lim_{x\to+\infty}u(x)=2\pi$. (i) Calculate the second variation, and (ii)* use the method of power series to find the eigenvalues of the associated Sturm-Liouville operator.
11. (i) Consider the functional $I[u]=\int_{-\pi}^{+\pi}\big(\frac{u_x^2}{2}-fu\big)dx$ where u and f are real 2π- periodic functions with zero mean: $\int_{-\pi}^{+\pi}u(x)dx=0=\int_{-\pi}^{+\pi}f(x)dx$. Write down the Euler-Lagrange equation.

   (ii) Now consider the case that u,f are given by finite sums of exponentials:
$$u(x)=\sum_{0<|n|\le N}u_ne^{inx},\quad f(x)=\sum_{0<|n|\le N}f_ne^{inx}$$
   with the reality conditions $\bar{u}_n=u_{-n},\bar{f}_n=f_{-n}$ and N any positive integer. Show that

$I[u] = 2\pi J_N[\underline{u}]$ where $\underline{u} = (u_1, u_2, \ldots u_n) \in \mathbb{C}^N$ and

$$J_N[\underline{u}] = \sum_{n=1}^{N} n^2|u_n|^2 - \bar{f}_n u_n - f_n \bar{u}_n$$

Use completion of the square to show that the minimum of J_N is attained for some unique $\underline{u}$, and show that the corresponding function u solves the Euler-Lagrange equation in (i).
(iii)* Use the direct method to prove the existence of a minimizer for J_N as follows. First show that J_N is bounded below, and let $\{\underline{u}^\alpha\}_{\alpha=1}^\infty$ be a sequence such that $J_N[\underline{u}^\alpha] \to \inf_{\underline{v}\in\mathbb{C}^N} J_N[\underline{v}]$ as $\alpha \to \infty$. Show that there is a subsequence which converges to a limit point $\underline{u}$ which is a minimizer , i.e. $J_N[\underline{u}] = \inf_{\underline{v}\in\mathbb{C}^N} J_N[\underline{v}]$. Finally, deduce by considering the stationary condition satisfied by minimizers for J_N, that this minimizer is the same as the one you obtained in (ii).
(iv)* [After Methods and Analysis II] Extend your argument in (iii) to the case $N = +\infty$ and show that amongst sequences such that $\sum_{n=1}^\infty n^2|u_n|^2 < \infty$ there is one that minimizes J_∞. Work under the assumption that f is given by an absolutely convergent Fourier series. (Hint: look up Cantor diagonalization.)