

$$1. \quad C_t = D(C^p C_x)_x \quad C = \frac{M^{2/(2+p)}}{(Dt)^{1/(2+p)}} F(\xi) \quad \xi = \frac{x}{(M^p Dt)^{1/(2+p)}} \quad (1)$$

$$\int C(x,t) dx = M \quad C_x(0,t) = 0 \quad C(x \rightarrow \infty, t) \rightarrow 0$$

$$C_t = -\frac{1}{(2+p)} \frac{M^{2/(2+p)}}{(Dt)^{1/(2+p)}} \cdot t F(\xi) + \frac{M^{2/(2+p)}}{(Dt)^{1/(2+p)}} F'(\xi) \cdot \left(-\frac{1}{(2+p)} \frac{\xi}{t}\right)$$

$$= \frac{M^{2/(2+p)}}{(Dt)^{1/(2+p)}} \cdot \frac{1}{t} \left\{ -\frac{1}{(2+p)} \xi F' - \frac{1}{(2+p)} F \right\} = \boxed{-\frac{M^{2/(2+p)}}{(Dt)^{1/(2+p)} t (2+p)} (\xi F)'}$$

$$C^p C_x = \frac{M^{2p/(2+p)}}{(Dt)^{p/(2+p)}} F^p \frac{M^{2/(2+p)}}{(Dt)^{1/(2+p)}} \cdot \frac{1}{(M^p Dt)^{1/(2+p)}} F' = \boxed{\frac{M}{Dt} F^p F'}$$

$$\rightarrow D(C^p C_x)_x = \cancel{D} \frac{M}{Dt} (F^p F')' \cdot \frac{1}{(M^p Dt)^{1/(2+p)}}$$

$$\therefore \frac{M^{2/(2+p)}}{t (Dt)^{1/(2+p)}} (F^p F')' = -\frac{M^{2/(2+p)}}{(Dt)^{1/(2+p)} t (2+p)} (\xi F)' \Rightarrow \boxed{(F^p F')' = -\frac{1}{(2+p)} (\xi F)'}$$

hence $F^p F' = -\frac{1}{(2+p)} \xi F + \text{const}$: by the boundary conditions at $\xi=0$ const = 0

$$\Rightarrow \boxed{F^p F' = -\frac{1}{(2+p)} \xi F}$$

note the normalization

$$\int C dx = \frac{M^{2/(2+p)}}{(Dt)^{1/(2+p)}} \int \underbrace{d\xi F(\xi) \cdot \frac{(M^p Dt)^{1/(2+p)}}{(M^p Dt)^{1/(2+p)}}}_{d\xi} = M \int d\xi F(\xi)$$

so we take F normalized to unity.

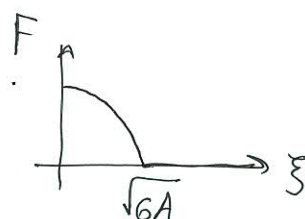
solving the last boxed eqn. $F^p F' = -\frac{1}{(2+p)} \xi F \Rightarrow dF \cdot F^{p-1} = -\frac{1}{(2+p)} \xi d\xi$ (2)

$$\frac{F^p}{p} = -\frac{\xi^2}{2(2+p)} + \text{const} \quad \text{or} \quad F(\xi) = \left[A - \frac{p}{2(2+p)} \xi^2 \right]^{1/p}$$

special case of $p=1$

$$F(\xi) = A - \frac{1}{6} \xi^2 \quad 0 \leq \xi \leq \sqrt{6A}$$

= 0 outside



normalization $\int_0^{\sqrt{6A}} (A - \frac{1}{6} \xi^2) d\xi = 1 = A\sqrt{6A} - \frac{1}{18} (6A)^{3/2} = A^{3/2} \cdot \frac{2}{3} \sqrt{6} = A^{3/2} \cdot \frac{2\sqrt{2}}{\sqrt{3}}$

$$\therefore A = \left(\frac{\sqrt{3}}{2\sqrt{2}} \right)^{2/3} = \left(\frac{3}{8} \right)^{1/3}$$

2.i) Homogeneous fixed point

1

$$\left. \begin{aligned} u(1-u)(u-a) + v &= 0 \\ bu - cv &= 0 \end{aligned} \right\} v = \frac{b}{c}u \quad \text{so } u = 0 \text{ or } (1-u)(u-a) + \frac{b}{c} = 0$$

$$u^2 - (1+a)u + a - \frac{b}{c} = 0$$

$$u^* = \frac{1+a \pm \sqrt{(1+a)^2 - 4a + 4b/c}}{2} = \frac{1+a \pm \sqrt{(1-a)^2 + 4b/c}}{2}$$

$$v^* = \frac{b}{c} u^*$$

choose + solution so $u^* > 0$

stability matrix

$$J = \begin{pmatrix} ? & 1 \\ b & -c \end{pmatrix}$$

$$J_{11} = (1-u)(u-a) + u(1-u) - u(u-a) \quad \text{at } u^*$$

$$= -3u^2 + 2u + 2ua - a$$

$$\text{but } u^2 = \frac{b}{c} - a + (1+a)u$$

$$\text{so } J_{11} = -\frac{3b}{c} + 2a - u(1+a) \quad \text{after some algebra}$$

$$\text{now, } u^* > \frac{1+a}{2} \quad \text{so } 2a - u^*(1+a) < 2a - \frac{(1+a)^2}{2}$$

$$< -\frac{1}{2}(1-a)^2 < 0$$

thus

$$J = \begin{pmatrix} - & + \\ + & - \end{pmatrix}$$

$$\text{tr } J < 0$$

$$\text{and since } J_{11} < -\frac{b}{c} \quad \text{so } \det > 0$$

} stable fixed point.

$$\text{ii) } u_t = -\gamma \phi \quad u_{xx} = \ddot{\phi} \quad v_t = -\gamma \psi \quad \bullet = \frac{d}{dt} \quad \xi = x - \gamma t$$

$$\left\{ \begin{aligned} -\gamma \dot{\phi} &= \ddot{\phi} + \phi(1-\phi)(\phi-a) + \psi \\ -\gamma \dot{\psi} &= b\phi - c\psi \end{aligned} \right.$$

↓

ii) if $b=c=0$ $\dot{\psi}=0 \Rightarrow \psi = \text{const} = 0$ by statement of problem

(2)

$$\Rightarrow -\gamma \dot{\phi} = \ddot{\phi} + \phi(1-\phi)(\phi-a)$$

set $\phi = \frac{1}{1+e^{-\alpha \xi}}$ $\dot{\phi} = \frac{\alpha e^{-\alpha \xi}}{(1+e^{-\alpha \xi})^2} = \alpha(\phi - \phi^2)$ (useful trick!)

$$\ddot{\phi} = \alpha \dot{\phi}(1-2\phi)$$

$$\Rightarrow \boxed{-\gamma \dot{\phi} = \alpha \dot{\phi}(1-2\phi) + \frac{\dot{\phi}}{\alpha}(\phi-a)}$$

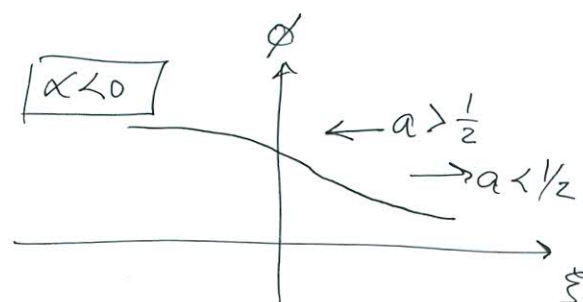
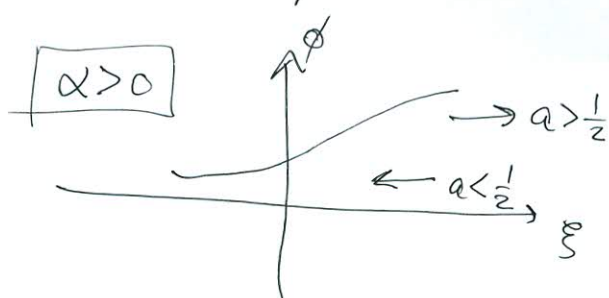
either $\dot{\phi}=0$ or $\phi(1-2\alpha^2) + (\alpha^2 + \gamma\alpha - a) = 0$

holds $\forall \xi$ if $1-2\alpha^2=0$ $\alpha = \pm \frac{1}{\sqrt{2}}$

and $\alpha^2 + \gamma\alpha - a = 0$

$$\gamma = \pm \sqrt{2} \left(a - \frac{1}{2} \right)$$

direction? depends on γ



3. set $u = \phi(\xi)$ $v = \psi(\xi)$ $\xi = x - ct$

$$-c\dot{\phi} = \ddot{\phi} + \phi(1-\phi-r\psi)$$

$$-c\dot{\psi} = d\ddot{\psi} - b\phi\psi$$

$$(u,v) \rightarrow (0,1) \quad x \rightarrow \infty$$

$$\rightarrow (1,0) \quad x \rightarrow -\infty$$

given asymptotic limits let's

look at $\boxed{v = 1 - u}$

$$u_t = u_{xx} + u(1-u-r(1-u))$$

$$= u_{xx} + (1-r)u(1-u)$$

$$-u_t = -d u_{xx} - b u(1-u)$$

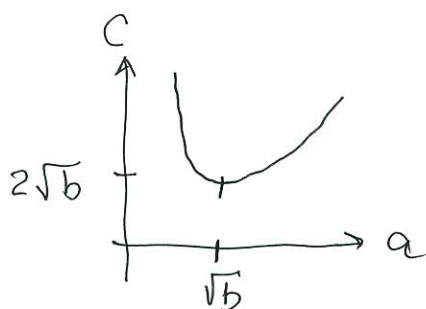
$$u_t = d u_{xx} + b u(1-u)$$

$$d=1 \Rightarrow \boxed{b=1-r}$$

to determine wave speeds, we look
at the leading edge of front and linearize:

$$u_t \approx u_{xx} + bu + \dots \quad ca = b + a^2$$

$$c(a) = \frac{b}{a} + a$$



note: front will move at smallest $c(a)$
with $a < a_{\text{critical}}$

can see easily: if we bound by e^{-ax} then stays bounded

can always bound an exponential by a shallower one (smaller a)

front can only be pulled down to shallower

if initial $a > \sqrt{b}$ then heads to $\sqrt{b}$, if $< \sqrt{b}$ stays put

$$c = \begin{cases} a + \frac{b}{a} & a \leq \sqrt{b} \\ 2\sqrt{b} & a \geq \sqrt{b} \end{cases}$$

4. $n_t = D n_{xx} + b n (1 - \frac{n}{n_0}) - \partial_x (X(a) n a_x)_x$ (1)

$$a_t = D_A a_{xx} + h n - h a$$

clearly set $u = n/n_0$ let $T = b t$ $\frac{\partial}{\partial t} = b \frac{\partial}{\partial T}$ k^{-1} is a time so set

diffusive scalings $x = \sqrt{D b^{-1}} X$ $a = h n_0 k^{-1} v$

$$\partial_x = \frac{1}{\sqrt{D b^{-1}}} \partial_X \text{ etc.}$$

algebra

$$\Rightarrow \beta = \frac{X_0 K h}{D h n_0}$$

$$\alpha = \frac{K h}{h n_0}$$

$$\gamma = k/b$$

$$\delta = D_A/D$$

$$\left\{ \begin{array}{l} \dot{u} = u'' + u(1-u) - \beta \left[\frac{u v'}{(\alpha + v)^2} \right]' \\ \dot{v} = \delta v'' + \gamma(u-v) \end{array} \right.$$

homogeneous steady state $u=v=1$ by inspection

stability matrix

$$J = \begin{pmatrix} -1 & 0 \\ \gamma & -\gamma \end{pmatrix}$$

$\text{tr} < 0$
 $\text{det} > 0$ } hence stable

now allow spatial instability e^{ikx}

$$J = \begin{pmatrix} -1 & 0 \\ \gamma & -\gamma \end{pmatrix} + \begin{pmatrix} -k^2 & 0 \\ 0 & -\delta k^2 \end{pmatrix} + \begin{pmatrix} 0 & \hat{\beta} k^2 \\ 0 & 0 \end{pmatrix}$$

$$\hat{\beta} = \frac{\beta}{(1+\alpha)^2}$$

$$= \begin{pmatrix} -(1+k^2) & \hat{\beta} k^2 \\ \gamma & -(\gamma + \delta k^2) \end{pmatrix}$$

$\text{tr} < 0$ always as usual

$$\text{det} = (1+k^2)(\gamma + \delta k^2) - \gamma \hat{\beta} k^2 = \underbrace{\delta (k^2)^2}_{\text{"a"}} + \underbrace{(\gamma + \delta - \gamma \hat{\beta}) k^2}_{\text{"b"}} + \underbrace{\gamma}_{\text{"c"}} *$$

can (*) ever be negative for $k^2 > 0$?

(2)

if so, need $\gamma + \delta - \gamma \hat{\beta} < 0$ "b"

and $(\gamma + \delta - \gamma \hat{\beta})^2 - 4\gamma\delta > 0$ " $b^2 - 4ac$ "

$$\text{i.e. } -(\gamma + \delta - \gamma \hat{\beta}) > 2\sqrt{\delta}\sqrt{\gamma}$$

$$\text{or } \gamma \hat{\beta} > \gamma + 2\sqrt{\delta}\sqrt{\gamma} + \delta = (\sqrt{\gamma} + \sqrt{\delta})^2$$

$$\left[\frac{\gamma\beta}{(1+\alpha)^2} > (\sqrt{\gamma} + \sqrt{\delta})^2 \right] \text{ as required (*)}$$

$$k_c^2 = \frac{-b}{2a} = -\frac{\gamma - \delta + \gamma \hat{\beta}}{2\delta} = \frac{\gamma\beta - (\gamma + \delta)(1 + \alpha)^2}{2\delta(1 + \alpha)^2}$$

$$k_c = \frac{2\pi}{\lambda_c} \leftarrow \text{wavelength} \quad \text{if } \alpha = \gamma = \delta = 1$$

$$k_c^2 = \frac{\beta - 8}{8}$$

$$\lambda_c = 2\pi \sqrt{\frac{8}{\beta - 8}}$$

and note that * gives $\beta > 16$

5.

$$u_t = u_{xx} + \frac{u^2}{v} - bu$$

$$v_t = d v_{xx} + u^2 - v$$

homogeneous fixed point

$$\frac{u^2}{v} - bu = 0 \quad u^2 - v = 0$$

$$\Rightarrow \boxed{u^* = b^{-1} \quad v^* = b^{-2}}$$

$$J|_{u^*, v^*} = \begin{pmatrix} b & -b^2 \\ 2b^{-1} & -1 \end{pmatrix}$$

$$\det = b$$

$$\text{tr} = b - 1$$

$$\text{so } \boxed{0 < b < 1 \text{ stable}}$$

Spatial instability $\sim e^{ikx}$

$$J = \begin{pmatrix} b - k^2 & -b^2 \\ 2b^{-1} & -1 - dk^2 \end{pmatrix}$$

tr < 0 of course

$$\begin{aligned} \det &= (b - k^2)(-1 - dk^2) + 2b \\ &= d(k^2)^2 + (1 - bd)k^2 + b \end{aligned}$$

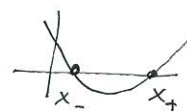
can this be negative for any $k^2 > 0$?need $1 - bd < 0$ i.e. $bd > 1$

$$\text{also } (1 - bd)^2 > 4bd$$

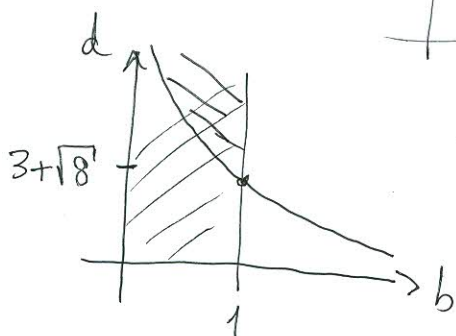
$$\text{so } \boxed{bd > 3 + \sqrt{8}}$$

$$1 - 2x + x^2 > 4x$$

$$x^2 - 6x + 1 > 0$$



$$x_{\pm} = 3 \pm \sqrt{8}$$

 x_+ relevant

/// = homog. stability
 $\equiv$ Turing instability.

critical wavenumber

$$k_c^2 = -\frac{(1 - bd)}{2d} = \frac{1 + \sqrt{2}}{d}$$

$$\lambda_c = 2\pi \sqrt{\frac{d}{1 + \sqrt{2}}}$$

$$6. \quad u_t = u_{xx} + u(1+u-\gamma v)$$

want $u, v > 0$ only

①

$$v_t = d v_{xx} + v(\beta u - v)$$

fixed point:

$$u_0 = \frac{1}{\beta\gamma - 1} \quad v_0 = \beta u_0 = \frac{\beta}{\beta\gamma - 1}$$

clearly $\beta\gamma > 1$

stability

$$J = u_0 \begin{pmatrix} 1 & -\gamma \\ \beta^2 & -\beta \end{pmatrix}$$

$$\det = u_0^2 \beta (\gamma\beta - 1) > 0 \quad \checkmark$$

$$\text{tr} = u_0 (1 - \beta) < 0 \Leftrightarrow \boxed{\beta > 1}$$

again, with perturbations $\sim e^{ikx}$

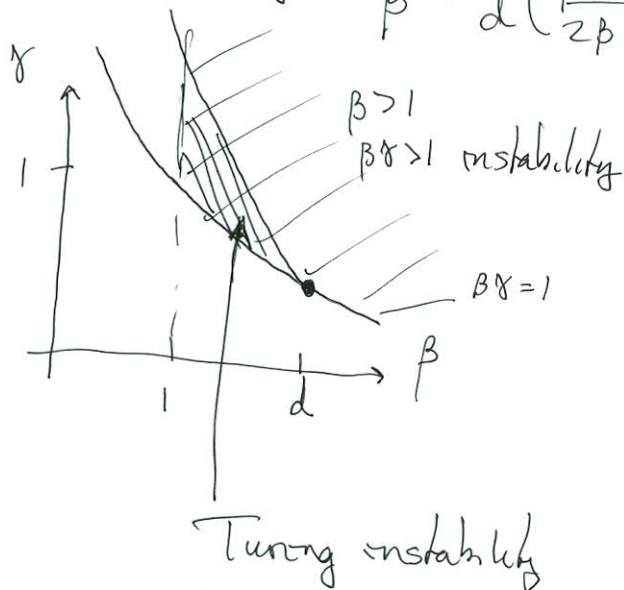
$$J = u_0 \begin{pmatrix} 1 & -\gamma \\ \beta^2 & -\beta \end{pmatrix} - k^2 \begin{pmatrix} 1 & 0 \\ 0 & d \end{pmatrix}$$

so $\text{tr} < 0$ still and $\det = d(k^2)^2 + (\beta - d)u_0 k^2 + \beta(\gamma\beta - 1)u_0^2$

for Turing instability, need this < 0 for some $k^2 > 0$

i.e. need $\boxed{d > \beta}$ and $\boxed{(\beta - d)^2 > 4\beta d(\gamma\beta - 1)}$

i.e. $\gamma < \frac{1}{\beta} + \frac{1}{d} \left(\frac{\beta - d}{2\beta} \right)^2 = \frac{1}{d} \left(\frac{\beta + d}{2\beta} \right)^2$ and this $> \frac{1}{\beta}$



$$k_c^2 = \frac{d - \beta}{2d} = \sqrt{\frac{\beta(\gamma\beta - 1)}{d}}$$

but $\Rightarrow \beta < \frac{d}{2\sqrt{d} - 1}$

$$\text{so } k_c^2 = \frac{\sqrt{d} - 1}{2\sqrt{d} - 1}$$