

14 Douglas Rachford

The Douglas-Rachford method to minimize the sum of two convex functions $f(x) + h(x)$ is given by the following iterates:

$$\begin{cases} x_{k+1} &= \mathbf{prox}_f(y_k - z_k) \\ y_{k+1} &= \mathbf{prox}_h(x_{k+1} + z_k) \\ z_{k+1} &= z_k + (x_{k+1} - y_{k+1}). \end{cases} \quad (1)$$

It is not hard to show that if we let $w_{k+1} = x_{k+1} + z_k$, then the Douglas-Rachford algorithm is equivalent to

$$w_{k+1} = T(w_k)$$

where T is the Douglas-Rachford operator:

$$T(w) = \mathbf{prox}_f(2 \mathbf{prox}_h(w) - w) + w - \mathbf{prox}_h(w). \quad (2)$$

To prove the convergence of the DR algorithm, we will prove that T is a *firmly nonexpansive* map.

Definition 14.1. A map $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ is *firmly nonexpansive* if

$$\|T(w) - T(w')\|_2^2 \leq \langle w - w', T(w) - T(w') \rangle \quad \forall w, w' \in \mathbb{R}^n.$$

We have already seen (lecture 10) that proximal operators of convex functions are firmly nonexpansive. This allows us to prove that the Douglas-Rachford operator in (2) is firmly nonexpansive. Indeed, let $w, w' \in \mathbb{R}^n$ and let $y = \mathbf{prox}_h(w)$ and $x = \mathbf{prox}_f(2y - w)$, so that $T(w) = x + w - y$. Since \mathbf{prox}_f and \mathbf{prox}_h are firmly nonexpansive, we have:

$$\begin{cases} \|y - y'\|_2^2 &\leq \langle y - y', w - w' \rangle \\ \|x - x'\|_2^2 &\leq \langle x - x', 2(y - y') - (w - w') \rangle. \end{cases}$$

Now we can write

$$\begin{aligned} \|T(w) - T(w')\|_2^2 &= \|x - x' + w - w' - (y - y')\|_2^2 \\ &= \|x - x'\|_2^2 + \|w - w'\|_2^2 + \|y - y'\|_2^2 \\ &\quad + 2 \langle x - x', w - w' \rangle - 2 \langle x - x', y - y' \rangle - 2 \langle y - y', w - w' \rangle \\ &\leq \langle x - x', w - w' \rangle + \|w - w'\|_2^2 - \langle y - y', w - w' \rangle \\ &= \langle (x + w - y) - (x' + w' - y'), w - w' \rangle = \langle T(w) - T(w'), w - w' \rangle. \end{aligned}$$

EXERCISE: Show that T is firmly nonexpansive, if, and only if, $T = (1/2)(I + U)$ where U is a nonexpansive map.

Now we prove a general convergence result about firmly nonexpansive iterations.

Theorem 14.1. Assume $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ is a firmly nonexpansive map that has at least one fixed point w^* . Then the iterates $w_{k+1} = T(w_k)$ converge to some fixed point of T , and furthermore

$$\min_{0 \leq j \leq k-1} \|w_j - T(w_j)\|_2^2 \leq \frac{\|w_0 - w^*\|_2^2}{k}.$$

The following lemma is easy to verify.

Lemma 1. *If T is firmly nonexpansive, then $G = I - T$ is also firmly nonexpansive.*

Proof. We have $\|Gw - Gw'\|_2^2 = \|w - w'\|_2^2 + \|Tw - Tw'\|_2^2 - 2\langle w - w', Tw - Tw' \rangle \leq \|w - w'\|_2^2 - \langle w - w', Tw - Tw' \rangle = \langle w - w', Gw - Gw' \rangle$ as desired. \square

We now prove the theorem.

Proof. Let w^* be any fixed point of T . Then for any w , we have

$$\begin{aligned} \|T(w) - w^*\|_2^2 - \|w - w^*\|_2^2 &\leq \langle w - w^*, T(w) - w^* \rangle - \|w - w^*\|_2^2 \\ &= \langle w - w^*, -G(w) \rangle \leq -\|G(w)\|_2^2 \end{aligned} \quad (3)$$

where we used the fact that G is firmly nonexpansive, and $G(w^*) = 0$. Thus, summing these inequalities and rearranging we get

$$\sum_{i=0}^{k-1} \|G(w_i)\|_2^2 \leq \|w_0 - w^*\|_2^2.$$

Let $r_{best,k} = \min\{\|G(w_0)\|_2^2, \dots, \|G(w_{k-1})\|_2^2\}$, we see that

$$r_{best,k} \leq \frac{1}{k} \sum_{i=0}^{k-1} \|G(w_i)\|_2^2 \leq \frac{\|w_0 - w^*\|_2^2}{k}.$$

and so $r_{best,k} \leq \|w_0 - w^*\|_2^2/k$.

It remains to show that (w_i) converges to a fixed point of T . The inequality (3) shows that $\|w_i - w^*\|_2$ is nonincreasing for any choice of fixed point w^* of T ; in particular (w_i) is bounded and so has a limit point \bar{w} . Let's show that $w_i \rightarrow \bar{w}$. First note that since $\|G(w_i)\|_2 \rightarrow 0$, and that G is continuous, we must have $G(\bar{w}) = 0$, i.e., \bar{w} is a fixed point for T . It follows that the sequence $\|w_i - \bar{w}\|_2^2$ is nonincreasing, and has 0 as a limit point. Thus it must be that $\lim_i \|w_i - \bar{w}\|_2 = 0$, i.e., $w_i \rightarrow \bar{w}$. \square

Convergence of ADMM We have now established the convergence of the Douglas-Rachford method for the minimization of $f(x) + h(x)$. Recall that the Douglas-Rachford method is a special case of the ADMM where $A = I$. Recall that the general ADMM method to minimize $f(x) + h(Ax)$ has the form:

$$\text{ADMM} \quad \begin{cases} x_{k+1} = \underset{x}{\operatorname{argmin}} \left\{ f(x) + z_k^T Ax + \frac{t}{2} \|Ax - y_k\|_2^2 \right\} \\ y_{k+1} = \underset{y}{\operatorname{argmin}} \left\{ h(y) - z_k^T y + \frac{t}{2} \|Ax_{k+1} - y\|_2^2 \right\} \\ z_{k+1} = z_k + t(Ax_{k+1} - y_{k+1}). \end{cases} \quad (4)$$

It turns out that one can directly obtain convergence of the ADMM method, by observing that the algorithm above is precisely the Douglas-Rachford method applied to the dual problem of minimizing $f^*(-A^T z) + h^*(z)$! More precisely, if we apply the DR method to the dual problem, we obtain the following iterates:

$$\begin{cases} \tilde{x}_{k+1} = \mathbf{prox}_{f^* \circ -A^T}(\tilde{y}_k - \tilde{z}_k) \\ \tilde{y}_{k+1} = \mathbf{prox}_{h^*}(\tilde{x}_{k+1} + \tilde{z}_k) \\ \tilde{z}_{k+1} = \tilde{z}_k + (\tilde{x}_{k+1} - \tilde{y}_{k+1}) \end{cases}$$

These equations can be simplified using Moreau's identity, and its generalization:

$$\mathbf{prox}_{f^* \circ A^T}(x) = x - A \underset{u}{\operatorname{argmin}} \{f(u) + (1/2)\|Au - x\|_2^2\}. \quad (5)$$

Using this identity, we get:

$$\begin{cases} \tilde{x}_{k+1} &= \tilde{y}_k - \tilde{z}_k + A \underset{x}{\operatorname{argmin}} \{f(x) + (1/2)\|Ax - (\tilde{z}_k - \tilde{y}_k)\|_2^2\} \\ \tilde{y}_{k+1} &= \tilde{x}_{k+1} + \tilde{z}_k - \underset{y}{\operatorname{argmin}} \{h(y) + (1/2)\|y - (\tilde{x}_{k+1} + \tilde{z}_k)\|_2^2\} \\ \tilde{z}_{k+1} &= \tilde{z}_k + (\tilde{x}_{k+1} - \tilde{y}_{k+1}). \end{cases}$$

By a suitable change of variables, the iterates can be shown to be equivalent to the ADMM method of (4). Indeed, by calling x_{k+1} the argmin in the first line, y_{k+1} the argmin in the second line, and $z_k = \tilde{y}_k$, we see that the iterations above can be written as (check!)

$$\begin{cases} x_{k+1} &= \underset{x}{\operatorname{argmin}} \{f(x) + (1/2)\|Ax - (y_k - z_k)\|_2^2\} \\ y_{k+1} &= \underset{y}{\operatorname{argmin}} \{h(y) + (1/2)\|y - (Ax_{k+1} + z_k)\|_2^2\} \\ x_{k+1} &= z_k + (Ax_{k+1} - y_{k+1}). \end{cases}$$

It is easy to see that these are the same as (4) with $t = 1$ (the case with general t can be obtained by appropriately scaling the functions f and h).

Historical note on the Douglas-Rachford algorithm The Douglas-Rachford algorithm was invented in the 1950s [DR56] as a method to solve the heat equation, i.e.,

$$\frac{\partial u}{\partial t} = \nabla_x^2 u + \nabla_y^2 u.$$

Let $A = -\nabla_x^2$ and $B = -\nabla_y^2$, so that the equation can be written as $u_t = -Au - Bu$. We assume we have discretized along space variables x and y using finite differences; as such, with a suitable ordering of the nodes, A and B are tridiagonal. If we use the backward Euler method to solve this problem we end up with the following scheme:

$$u^{n+1} = u^n + \lambda(-Au^{n+1} - Bu^{n+1})$$

i.e., $u^{n+1} = (I + \lambda(A + B))^{-1}u^n$ where $\lambda > 0$ is the time step. Solving a linear system with $I + \lambda(A + B)$ can be expensive, unlike solving linear systems with $I + \lambda A$ and $I + \lambda B$ which are much easier because the latter are tridiagonal after suitable permutation of the nodes (different for A and B). Splitting schemes have thus been developed to address this need. There are many possible splittings one can do:

- One possibility for splitting is the forward backward splitting where we use forward Euler on B , and backward Euler on A (or vice-versa):

$$u^{n+1} = u^n + \lambda(-Au^{n+1} - Bu^n)$$

This only requires solving a linear system involving $I + \lambda A$.

- Another possibility, proposed by Peaceman-Rachford, is to alternate the roles of A and B in forward-backward splitting, i.e.,

$$\begin{cases} u^{n+1/2} = u^n + \lambda(-Au^{n+1/2} - Bu^n) \\ u^{n+1} = u^{n+1/2} + \lambda(-Au^{n+1/2} - Bu^{n+1}) \end{cases}$$

This requires solving, at each time step, a linear system with $I + \lambda A$ and a linear system with $I + \lambda B$.

- The third one, proposed by Douglas-Rachford, proceeds as follows. Even though $(I + \lambda A + \lambda B)$ is difficult to invert, we can see that $(I + \lambda A + \lambda B + \lambda^2 AB)$ is actually easy to invert because the latter is simply $(I + \lambda A)(I + \lambda B)$. So this motivates us to consider the following altered backward difference formula:

$$u^{n+1} = u^n + \lambda(-Au^{n+1} - Bu^{n+1}) + \underbrace{\lambda^2 AB(u^n - u^{n+1})}.$$

This reduces to $(I + \lambda A)(I + \lambda B)u^{n+1} = u^n + \lambda^2 ABu^n$, which again only requires $(I + \lambda A)^{-1}$ and $(I + \lambda B)^{-1}$.

Extension to nonlinear operators The above applies to any positive linear operators A and B , and not just to the Laplacian. In fact, these methods were shown to be convergent for nonlinear *maximal monotone* operators A, B by Lions and Mercier in [LM79]. The latter Douglas-Rachford can be written as

$$u^{n+1} = Tu^n$$

where $T = (I + \lambda B)^{-1}(I + \lambda A)^{-1}(I + \lambda^2 AB)$. If we write $I + \lambda^2 AB = (I + \lambda A)\lambda B + I - \lambda B$, we get

$$T = (I + \lambda B)^{-1} [(I + \lambda A)^{-1}(I - \lambda B) + \lambda B]$$

Call $(I + \lambda B)^{-1}v^n = u^n$, then we get

$$\begin{aligned} v^{n+1} &= ((I + \lambda A)^{-1}(I - \lambda B) + \lambda B)(I + \lambda B)^{-1}v^n \\ &= [(I + \lambda A)^{-1}(2(I + \lambda B)^{-1} - I) + I - (I + \lambda B)^{-1}] v^n. \end{aligned} \tag{6}$$

where we used the fact that $(I - \lambda B)(I + \lambda B)^{-1} = 2(I + \lambda B)^{-1} - I$, and $\lambda B(I + \lambda B)^{-1} = I - (I + \lambda B)^{-1}$. If $A = \partial f$ and $B = \partial h$, then $(I + \lambda A)^{-1} = \mathbf{prox}_{\lambda f}$ and $(I + \lambda B)^{-1} = \mathbf{prox}_{\lambda h}$ and so the equation above is precisely the Douglas-Rachford iteration (2)! For a nice survey of monotone operator methods in optimization, see [RB16].

References

- [DR56] Jim Douglas and Henry H Rachford. On the numerical solution of heat conduction problems in two and three space variables. *Transactions of the American mathematical Society*, 82(2):421–439, 1956. [3](#)
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- [RB16] Ernest K Ryu and Stephen Boyd. Primer on monotone operator methods. *Appl. Comput. Math*, 15(1):3–43, 2016. [4](#)