8 Subgradient method

In this lecture we look at the problem of minimizing a general nonsmooth convex function f(x).

Subgradient method The subgradient method to minimize f(x) works as follows. Choose $x_0 \in \mathbb{R}^n$ and iterate, for $k \geq 0$:

$$x_{k+1} = x_k - t_k q_k$$

where $g_k \in \partial f(x_k)$ is a subgradient of f at x_k and $t_k > 0$ is the step size.

Note: A negative subgradient is not necessarily a descent direction, i.e., it is possible that f(x-tg) > f(x) for all t > 0 (small enough). For example f(x) = |x|, x = 0 and $g = -1 \in \partial f(0)$. Convergence analysis of subgradient method:

$$||x_{k+1} - x^*||_2^2 = ||x_k - t_k g_k - x^*||_2^2$$

$$= ||x_k - x^*||_2^2 - 2t_k \langle g_k, x_k - x^* \rangle + t_k^2 ||g_k||_2^2$$

$$\leq ||x_k - x^*||_2^2 + t_k^2 ||g_k||_2^2 + 2t_k (f^* - f(x_k))$$
(1)

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where in the last line we used the fact that $g_k \in \partial f(x_k)$. Applying this inequality recursively to $||x_k - x^*||_2^2$, we get at the end:

$$||x_{k+1} - x^*||_2^2 \le ||x_0 - x^*||_2^2 + \sum_{i=0}^k t_i^2 ||g_i||_2^2 + 2\sum_{i=0}^k t_i (f^* - f(x_i))$$
(2)

which after rearranging, and using $||x_{k+1} - x^*||_2^2 \ge 0$, gives us

$$\sum_{i=0}^{k} t_i(f(x_i) - f^*) \le \frac{\|x_0 - x^*\|_2^2}{2} + \frac{1}{2} \sum_{i=0}^{k} t_i^2 \|g_i\|_2^2.$$

Let $f_{\text{best},k} = \min \{f(x_0), \dots, f(x_k)\}$. Since $t_i \ge 0$ we get

$$f_{\text{best},k} - f^* \le \frac{1}{\sum t_i} \sum_{i=0}^k t_i (f(x_i) - f^*) \le \frac{\|x_0 - x^*\|_2^2}{2\sum_{i=0}^k t_i} + \frac{\sum_{i=0}^k t_i^2 \|g_i\|_2^2}{2\sum_{i=0}^k t_i}$$

$$\le \frac{\|x_0 - x^*\|_2}{2\sum_{i=0}^k t_i} + \frac{G^2 \sum_{i=0}^k t_i^2}{2\sum_{i=0}^k t_i}.$$

$$(3)$$

where in the last equation we assumed that f is G-Lipschitz, so that $||g_i||_2 \leq G$ (see Exercise sheet 2).

• Constant step size: If $t_k = t$ and f is G-Lipschitz then we get

$$f_{\text{best},k} - f^* \le \frac{\|x_0 - x^*\|_2^2}{2(k+1)t} + \frac{G^2 t}{2}.$$
 (4)

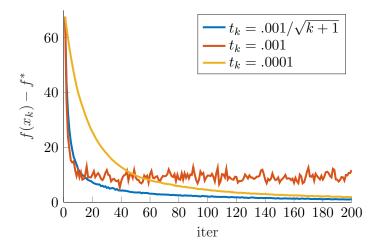
In this case we do not guarantee convergence: we only guarantee that $f_{\text{best},k}$ will be at most $G^2t/2$ sub-optimal, in the limit $k \to \infty$.

Assume that k is fixed a priori (i.e., we have a certain number of iterations that we are going to run). What is the choice of t that minimizes the right-hand side of (4)? The choice of t is the one that will make the two terms equal, namely $||x_0 - x^*||_2^2/(k+1) = G^2t^2$, i.e., $t = ||x_0 - x^*||_2/(G\sqrt{k+1})$ and the corresponding bound we get with this choice of t is

$$t = \frac{\|x_0 - x^*\|_2}{G\sqrt{k+1}} \quad \Rightarrow \quad f_{\text{best},k} - f^* \le \frac{G\|x_0 - x^*\|_2}{\sqrt{k+1}}.$$

• Diminishing step size: consider the choice $t_i \sim 1/\sqrt{i}$. Then $\sum_0^k t_i \approx \sqrt{k}$, $\sum_0^k t_i^2 \approx \ln(k)$, and so we get a convergence like $\ln(k)/\sqrt{k}$. In fact, one can get rid of the log term by recursing the inequality (1) only up to iterate k/2 (instead of all the way back to the first iterate), and use the fact that $\sum_{k/2}^k 1/i \leq \text{constant}$.

Illustration The figure below shows the subgradient method applied to the problem of minimizing the nonsmooth function $f(x) = ||Ax - b||_1$ where $A \in \mathbb{R}^{m \times n}$ with m > n, and $b \in \mathbb{R}^m$. We see that with a constant step size, the method does not converge to f^* , but only to a neighborhood of the optimal value.



Optimality of subgradient method One can show that the convergence rate of $1/\sqrt{k}$ is the best possible one can get on the class of nonsmooth convex Lipschitz functions. More precisely, fix k, G, and R > 0. For any algorithm where the k'th iterate satisfies

$$x_k \in x_0 + \operatorname{span}\{g_0, \dots, g_{k-1}\}\$$

where $g_i \in \partial f(x_i)$ and x_0 is the starting point, there is a convex function f that is G-Lipschitz on $\{x : \|x - x_0\|_2 \le R\}$ such that after k iterations of the algorithm we have

$$f_{\text{best},k} - f^* \gtrsim \frac{GR}{\sqrt{k+1}}.$$

See Exercise sheet 2 for a proof.