

Microstructural studies for rheology

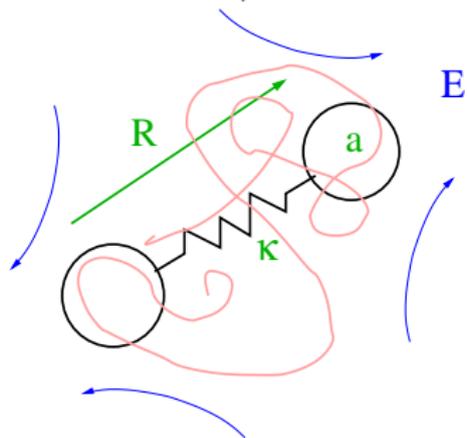
- ▶ Micro & macro views
- ▶ Einstein viscosity
- ▶ Rotations
- ▶ Deformations
- ▶ Interactions
- ▶ Polymers
- ▶ Others

Polymers

- ▶ Single polymer
 - ▶ Bead-and-spring model
 - ▶ Refinements
 - ▶ FENE-P constitutive equation
 - ▶ Unravelling a polymer chain
 - ▶ Kinks model
 - ▶ Brownian simulations
- ▶ Entangled polymers
 - ▶ rheology
 - ▶ Refinements
 - ▶ pom-pom

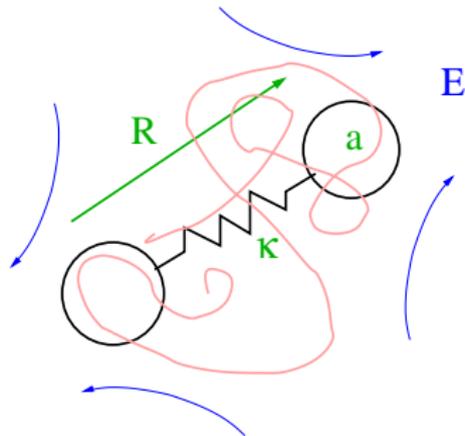
Bead-and-Spring model of isolated polymer chain

- simplest, only gross distortion, Kuhn & Kuhn 1945, Kramers 1946



Bead-and-Spring model of isolated polymer chain

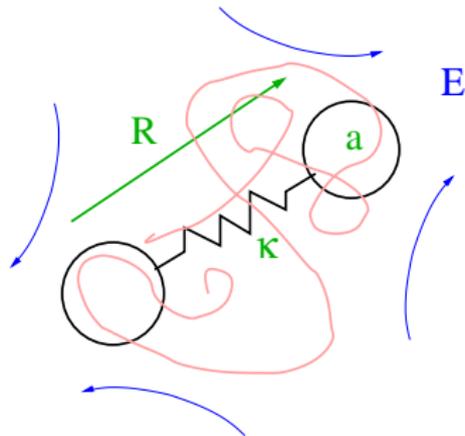
- simplest, only gross distortion, Kuhn & Kuhn 1945, Kramers 1946



- ▶ Flow distortion = Stokes drag = $6\pi\mu a(R \cdot \nabla U - \dot{R})$
 $a = \frac{1}{6}bN^{0.5} \rightarrow N^{0.6}$

Bead-and-Spring model of isolated polymer chain

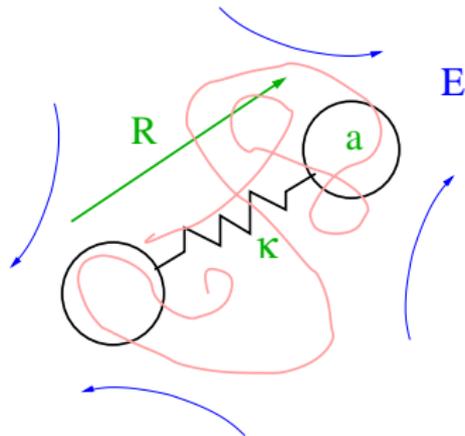
- simplest, only gross distortion, Kuhn & Kuhn 1945, Kramers 1946



- ▶ Flow distortion = Stokes drag = $6\pi\mu a(R \cdot \nabla U - \dot{R})$
 $a = \frac{1}{6}bN^{0.5} \rightarrow N^{0.6}$
- ▶ Resisted by entropic spring force = κR , $\kappa = \frac{3kT}{Nb^2}$

Bead-and-Spring model of isolated polymer chain

- simplest, only gross distortion, Kuhn & Kuhn 1945, Kramers 1946



- ▶ Flow distortion = Stokes drag = $6\pi\mu a(R \cdot \nabla U - \dot{R})$
 $a = \frac{1}{6}bN^{0.5} \rightarrow N^{0.6}$
- ▶ Resisted by entropic spring force = κR , $\kappa = \frac{3kT}{Nb^2}$

Hence

$$\dot{R} = R \cdot \nabla U - \frac{1}{2\tau} R \quad \text{with} \quad \tau = 0.8kT / \mu(N^{1/2}b)^3$$

Bead-and-Spring model of isolated polymer chain 2

- ▶ Adding Brownian motion of the beads: $A = \langle RR \rangle$

Bead-and-Spring model of isolated polymer chain 2

- ▶ Adding Brownian motion of the beads: $A = \langle RR \rangle$

$$\overset{\nabla}{A} \equiv \frac{DA}{Dt} - A \cdot \nabla U - \nabla U^T \cdot A = -\frac{1}{\tau} \left(A - \frac{Nb^2}{3} I \right)$$

Bead-and-Spring model of isolated polymer chain 2

- ▶ Adding Brownian motion of the beads: $A = \langle RR \rangle$

$$\overset{\nabla}{A} \equiv \frac{DA}{Dt} - A \cdot \nabla U - \nabla U^T \cdot A = -\frac{1}{\tau} \left(A - \frac{Nb^2}{3} I \right)$$

$$\sigma = -pI + 2\mu E + n\kappa A$$

with n number of chains per unit volume.

Bead-and-Spring model of isolated polymer chain 2

- ▶ Adding Brownian motion of the beads: $A = \langle RR \rangle$

$$\overset{\nabla}{A} \equiv \frac{DA}{Dt} - A \cdot \nabla U - \nabla U^T \cdot A = -\frac{1}{\tau} \left(A - \frac{Nb^2}{3} I \right)$$

$$\sigma = -pI + 2\mu E + n\kappa A$$

with n number of chains per unit volume.

- Oldroyd-B constitutive equation with UCD time derivative $\overset{\nabla}{A}$

Rheological properties

Rheological properties

Shear

- ▶ $\mu = \text{constant}$, $N_1 \propto \gamma^2$, $N_2 = 0$.

Rheological properties

Shear

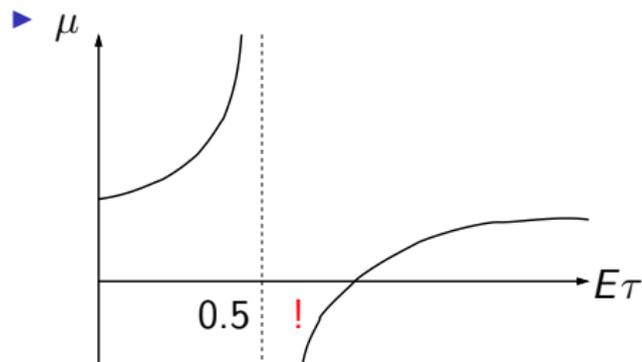
- ▶ $\mu = \text{constant}$, $N_1 \propto \gamma^2$, $N_2 = 0$.
- ▶ Distortion xy : $a\gamma\tau \times a$

Rheological properties

Shear

- ▶ $\mu = \text{constant}$, $N_1 \propto \gamma^2$, $N_2 = 0$.
- ▶ Distortion xy : $a\gamma\tau \times a$

Extension

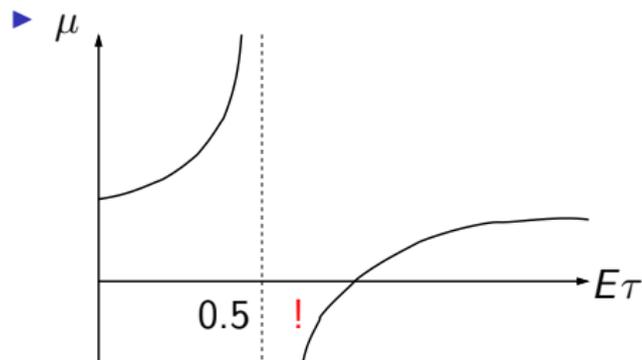


Rheological properties

Shear

- ▶ $\mu = \text{constant}$, $N_1 \propto \gamma^2$, $N_2 = 0$.
- ▶ Distortion xy : $a\gamma\tau \times a$

Extension



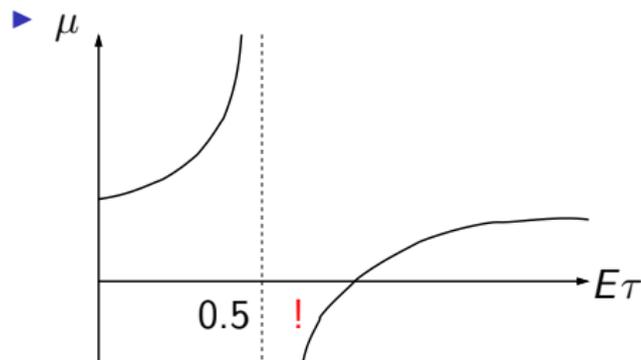
- ▶ Distortion $\propto e^{(2E - \frac{1}{\tau})t}$

Rheological properties

Shear

- ▶ $\mu = \text{constant}$, $N_1 \propto \gamma^2$, $N_2 = 0$.
- ▶ Distortion xy : $a\gamma\tau \times a$

Extension



- ▶ Distortion $\propto e^{(2E - \frac{1}{\tau})t}$
- ▶ For TDR: small shear and large extensional viscosities

Refinements

Refinements

1. (boring) **Spectrum** of internal modes: Rouse 53, Zimm 56 with pre-averaged hydrodynamics

Refinements

1. (boring) **Spectrum** of internal modes: Rouse 53, Zimm 56 with pre-averaged hydrodynamics
2. (boring) **Polydisperse** molecular weights

Refinements

1. (boring) **Spectrum** of internal modes: Rouse 53, Zimm 56 with pre-averaged hydrodynamics
2. (boring) **Polydisperse** molecular weights
3. (important) **Finite extensibility** – to stop infinite growth
 $\propto e^{(2E - \frac{1}{\tau})t}$

Refinements

1. (boring) **Spectrum** of internal modes: Rouse 53, Zimm 56 with pre-averaged hydrodynamics
2. (boring) **Polydisperse** molecular weights
3. (important) **Finite extensibility** – to stop infinite growth
 $\propto e^{(2E - \frac{1}{\tau})t}$
 - ▶ Nonlinear spring force – inverse Langevin law

$$F(R) = \frac{kT}{b} \mathcal{L}^{-1} \left(\frac{R}{Nb} \right) \quad \text{with} \quad \mathcal{L}(x) = \coth x - \frac{1}{x}$$

Refinements

1. (boring) **Spectrum** of internal modes: Rouse 53, Zimm 56 with pre-averaged hydrodynamics
2. (boring) **Polydisperse** molecular weights
3. (important) **Finite extensibility** – to stop infinite growth
 $\propto e^{(2E - \frac{1}{\tau})t}$

- ▶ Nonlinear spring force – inverse Langevin law

$$F(R) = \frac{kT}{b} \mathcal{L}^{-1} \left(\frac{R}{Nb} \right) \quad \text{with} \quad \mathcal{L}(x) = \coth x - \frac{1}{x}$$

- ▶ F.E.N.E approximation

$$F(R) = \frac{kT}{Nb^2} \frac{R}{1 - R^2/L^2} \quad \text{with} \quad \text{fully extended length} \quad L = Nb$$

Refinements

1. (boring) **Spectrum** of internal modes: Rouse 53, Zimm 56 with pre-averaged hydrodynamics
2. (boring) **Polydisperse** molecular weights
3. (important) **Finite extensibility** – to stop infinite growth
 $\propto e^{(2E - \frac{1}{\tau})t}$

- ▶ Nonlinear spring force – inverse Langevin law

$$F(R) = \frac{kT}{b} \mathcal{L}^{-1} \left(\frac{R}{Nb} \right) \quad \text{with} \quad \mathcal{L}(x) = \coth x - \frac{1}{x}$$

- ▶ F.E.N.E approximation

$$F(R) = \frac{kT}{Nb^2} \frac{R}{1 - R^2/L^2} \quad \text{with} \quad \text{fully extended length} \quad L = Nb$$

- ▶ FENE-P closure

$$\langle RR / (1 - R^2/L^2) \rangle = \langle RR \rangle / (1 - \langle R^2 \rangle / L^2)$$

Refinements

1. (boring) **Spectrum** of internal modes: Rouse 53, Zimm 56 with pre-averaged hydrodynamics
2. (boring) **Polydisperse** molecular weights
3. (important) **Finite extensibility** – to stop infinite growth
 $\propto e^{(2E - \frac{1}{\tau})t}$

- ▶ Nonlinear spring force – inverse Langevin law

$$F(R) = \frac{kT}{b} \mathcal{L}^{-1} \left(\frac{R}{Nb} \right) \quad \text{with} \quad \mathcal{L}(x) = \coth x - \frac{1}{x}$$

- ▶ F.E.N.E approximation

$$F(R) = \frac{kT}{Nb^2} \frac{R}{1 - R^2/L^2} \quad \text{with} \quad \text{fully extended length} \quad L = Nb$$

- ▶ FENE-P closure

$$\langle RR / (1 - R^2/L^2) \rangle = \langle RR \rangle / (1 - \langle R^2 \rangle / L^2)$$

but “molecular individualism”

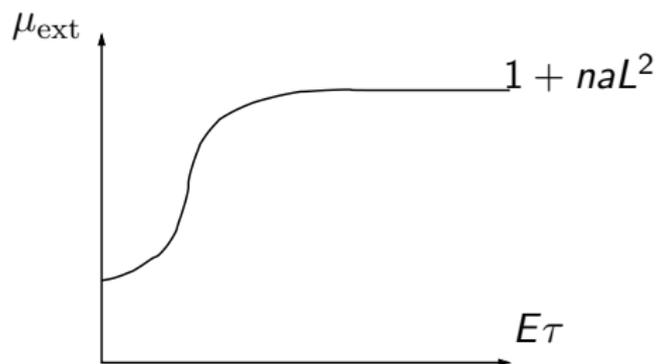
FENE-P constitutive equation

$$\begin{aligned}\nabla \cdot \mathbf{A} &= -\frac{1}{\tau} \frac{L^2}{L^2 - \text{trace } \mathbf{A}} \left(\mathbf{A} - \frac{a^2}{3} \mathbf{I} \right) \\ \sigma &= -p \mathbf{I} + 2\mu \mathbf{E} + n\kappa \frac{L^2}{L^2 - \text{trace } \mathbf{A}} \mathbf{A}\end{aligned}$$

FENE-P constitutive equation

$$\nabla \cdot \mathbf{A} = -\frac{1}{\tau} \frac{L^2}{L^2 - \text{trace } \mathbf{A}} \left(\mathbf{A} - \frac{a^2}{3} \mathbf{I} \right)$$

$$\boldsymbol{\sigma} = -p\mathbf{I} + 2\mu\mathbf{E} + n\kappa \frac{L^2}{L^2 - \text{trace } \mathbf{A}} \mathbf{A}$$



More refinements

4. Nonlinear bead friction

More refinements

4. Nonlinear bead friction

Hydrodynamic drag increase with size $6\pi\mu(a \rightarrow R)$

More refinements

4. Nonlinear bead friction

Hydrodynamic drag increase with size $6\pi\mu(a \rightarrow R)$

$$\mu_{\text{ext}} = 1 + nL^3 \quad \text{and hysteresis}$$

More refinements

4. Nonlinear bead friction

Hydrodynamic drag increase with size $6\pi\mu(a \rightarrow R)$

$$\mu_{\text{ext}} = 1 + nL^3 \quad \text{and hysteresis}$$

5. Rotation of the beads – simple shear not so simple

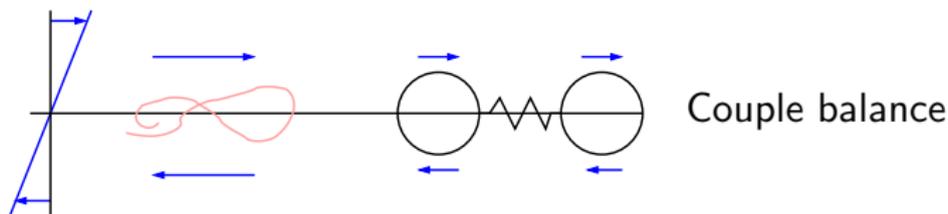
More refinements

4. Nonlinear bead friction

Hydrodynamic drag increase with size $6\pi\mu(a \rightarrow R)$

$$\mu_{\text{ext}} = 1 + nL^3 \quad \text{and hysteresis}$$

5. Rotation of the beads – simple shear not so simple



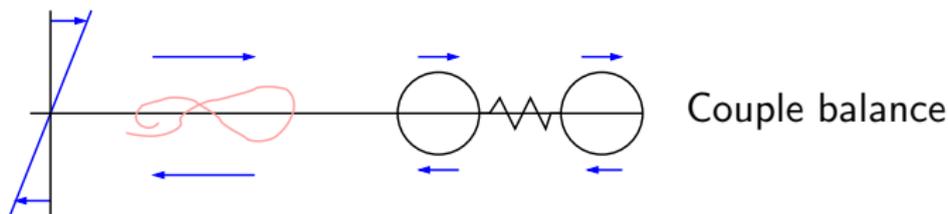
More refinements

4. Nonlinear bead friction

Hydrodynamic drag increase with size $6\pi\mu(a \rightarrow R)$

$$\mu_{\text{ext}} = 1 + nL^3 \quad \text{and hysteresis}$$

5. Rotation of the beads – simple shear not so simple



$$\text{Affine } \overset{\nabla}{\dot{A}} \rightarrow \text{non-affine } \overset{\circ}{\dot{A}} - \frac{\text{trace } A}{3 + \text{trace } A} (A \cdot E + E \cdot A)$$

inefficiency of straining

One more refinement

6. Dissipative stress – nonlinear internal modes

One more refinement

6. Dissipative stress – nonlinear internal modes

Simulations show growing stretched segments

$$\text{segment length} \propto \frac{R^2}{L}, \quad \text{number} \propto \frac{L^2}{R^2}, \quad \text{dissipation} \propto \frac{R^4}{L}$$

One more refinement

6. Dissipative stress – nonlinear internal modes

Simulations show growing stretched segments

$$\text{segment length} \propto \frac{R^2}{L}, \quad \text{number} \propto \frac{L^2}{R^2}, \quad \text{dissipation} \propto \frac{R^4}{L}$$

$$\sigma = -pl + 2\mu \left(1 + n \frac{(\text{trace } A)^2}{L} \right) E + n\kappa \frac{L^2}{L^2 - \text{trace } A} A$$

One more refinement

6. Dissipative stress – nonlinear internal modes

Simulations show growing stretched segments

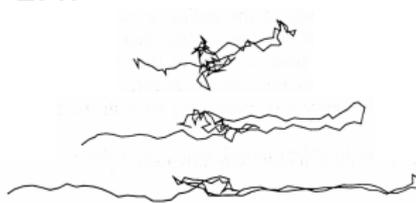
$$\text{segment length} \propto \frac{R^2}{L}, \quad \text{number} \propto \frac{L^2}{R^2}, \quad \text{dissipation} \propto \frac{R^4}{L}$$

$$\sigma = -pl + 2\mu \left(1 + n \frac{(\text{trace } A)^2}{L} \right) E + n\kappa \frac{L^2}{L^2 - \text{trace } A} A$$

Good for contraction flows

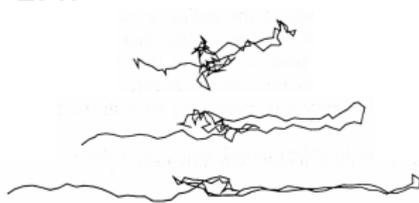
Unravelling a polymer chain in an extensional flow

Simulation of chain with $N = 100$ in uni-axial straining motion at strains $Et = 0.8, 1.6, 2.4$.



Unravelling a polymer chain in an extensional flow

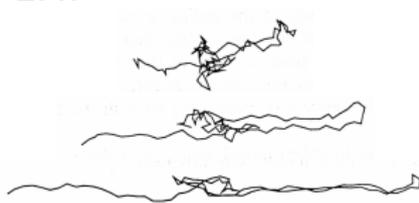
Simulation of chain with $N = 100$ in uni-axial straining motion at strains $Et = 0.8, 1.6, 2.4$.



- ▶ Growing stretched segments

Unravelling a polymer chain in an extensional flow

Simulation of chain with $N = 100$ in uni-axial straining motion at strains $Et = 0.8, 1.6, 2.4$.



- ▶ Growing stretched segments
- ▶ Two ends not on opposite sides

Simplified 1D 'kinks' model

Simplified 1D 'kinks' model

- ▶ $t = 0$: 1D random walk, N steps of ± 1

Simplified 1D 'kinks' model

- ▶ $t = 0$: 1D random walk, N steps of ± 1
- ▶ $t > 0$: floppy inextensible string in $u = Ex$

Simplified 1D 'kinks' model

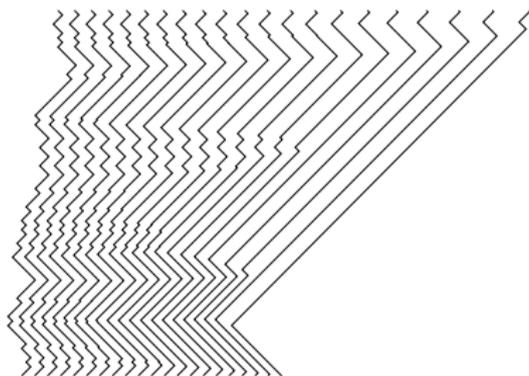
- ▶ $t = 0$: 1D random walk, N steps of ± 1
- ▶ $t > 0$: floppy inextensible string in $u = Ex$
- ▶ arc lengths satisfy

$$\dot{s}_i = \frac{1}{4}E(-s_{i+1} + 2s_i - s_{i-1})$$

Simplified 1D 'kinks' model

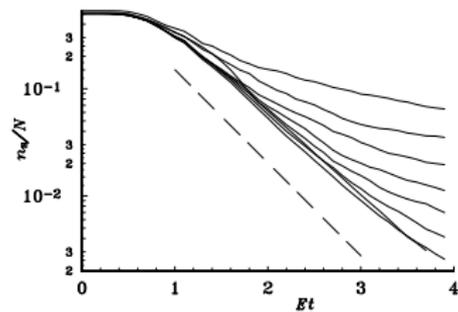
- ▶ $t = 0$: 1D random walk, N steps of ± 1
- ▶ $t > 0$: floppy inextensible string in $u = Ex$
- ▶ arc lengths satisfy

$$\dot{s}_i = \frac{1}{4}E(-s_{i+1} + 2s_i - s_{i-1})$$



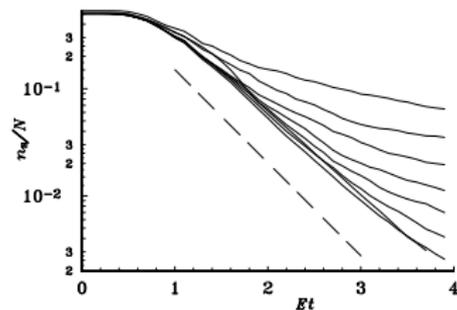
- ▶ Large gobble small

Kinks model 2

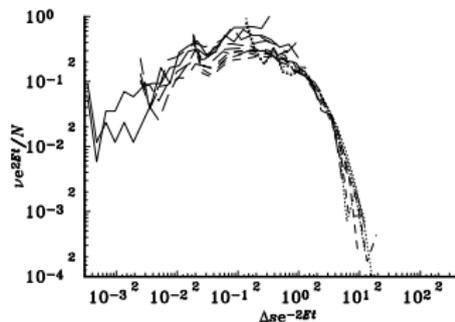


Number of segments $n(t)$

Kinks model 2

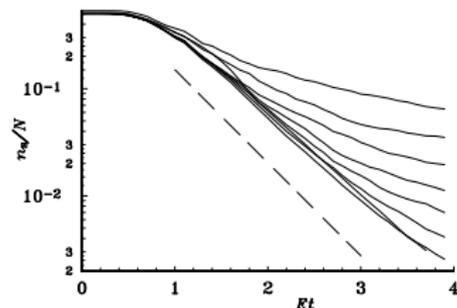


Number of segments $n(t)$

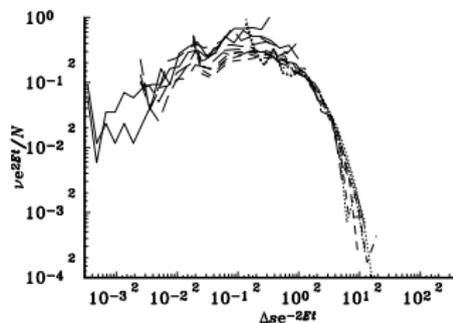


Distribution of lengths $l(t)$
scaled by e^{2Et}

Kinks model 2



Number of segments $n(t)$

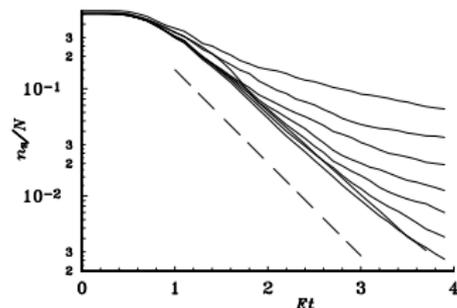


Distribution of lengths $l(t)$
scaled by e^{2Et}

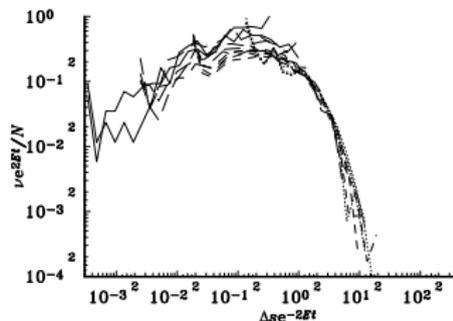
Scalings

$$\begin{cases} nl = N \\ \sqrt{nl} = R = \sqrt{Ne^{Et}} \end{cases} \longrightarrow$$

Kinks model 2



Number of segments $n(t)$



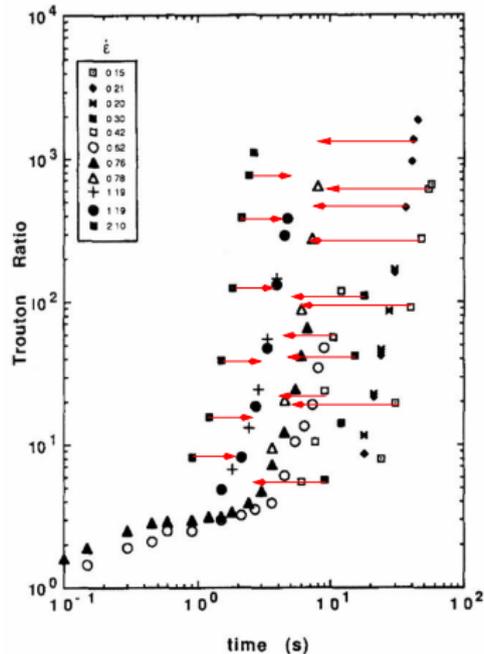
Distribution of lengths $l(t)$
scaled by e^{2Et}

Scalings

$$\begin{cases} nl = N \\ \sqrt{nl} = R = \sqrt{Ne^{Et}} \end{cases} \longrightarrow \begin{cases} n = Ne^{-2Et} \\ l = e^{2Et} \end{cases}$$

Evidence of a dissipative stress

Original data of Sridhar, Tirtaatmadja, Nguyen & Gupta 1991 plotted as viscosity as function of time



Replotted a function of strain = strain-rate \times time

Improved algorithms for Brownian simulations

1. Mid-point time-stepping avoids evaluating $\nabla \cdot \mathbf{D}$
Keep random force fixed in time-step, but vary friction

Improved algorithms for Brownian simulations

1. **Mid-point time-stepping** avoids evaluating $\nabla \cdot \mathbf{D}$
Keep random force fixed in time-step, but vary friction
2. **Replace very stiff (fast) bonds** with rigid + correction potential

$$-kT \nabla \ln \sqrt{\det M^{-1}} \quad \text{with} \quad M^{-1 ab} = \sum_{i \text{ beads}} m_i^{-1} \frac{\partial g^a}{\partial \mathbf{x}_i} \cdot \frac{\partial g^b}{\partial \mathbf{x}_i}$$

where rigid constraints are $g^a(\mathbf{x}_1, \dots, \mathbf{x}_N) = 0$ and stiff spring energy $\frac{1}{2} |\nabla g^a|^2$

Improved algorithms for Brownian simulations

1. **Mid-point time-stepping** avoids evaluating $\nabla \cdot \mathbf{D}$
Keep random force fixed in time-step, but vary friction
2. **Replace very stiff (fast) bonds** with rigid + correction potential

$$-kT \nabla \ln \sqrt{\det M^{-1}} \quad \text{with} \quad M^{-1 ab} = \sum_{i \text{ beads}} m_i^{-1} \frac{\partial g^a}{\partial \mathbf{x}_i} \cdot \frac{\partial g^b}{\partial \mathbf{x}_i}$$

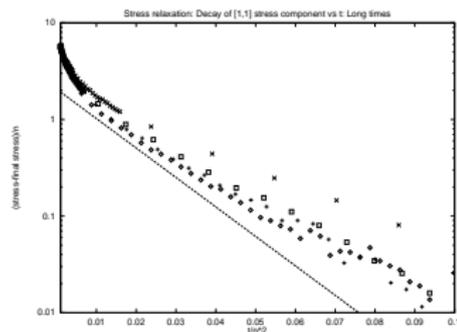
where rigid constraints are $g^a(\mathbf{x}_1, \dots, \mathbf{x}_N) = 0$ and stiff spring energy $\frac{1}{2} |\nabla g^a|^2$

3. **Stress by subtraction** of large $\Delta t^{-1/2}$ term with zero average

$$\frac{1}{2}(x^n + x^{n+1})f^n \longrightarrow \frac{1}{2}\Delta x^n f^n$$

Relaxation of fully stretched chain

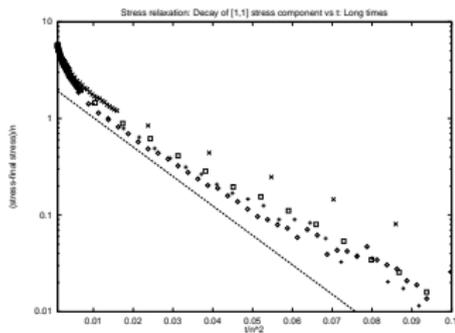
Long times - Rouse relaxation



$$\sigma/N \text{ vs } t/N^2 \text{ (Rouse)}$$

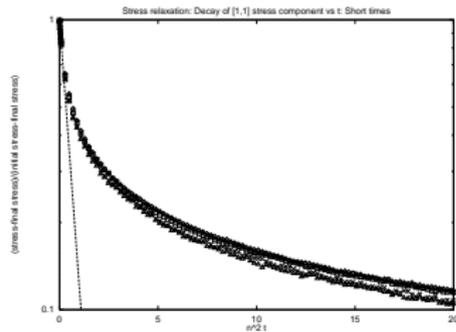
Relaxation of fully stretched chain

Long times - Rouse relaxation



σ/N vs t/N^2 (Rouse)

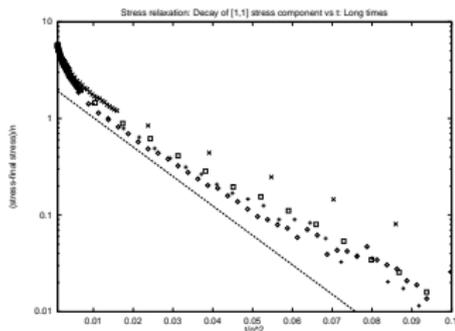
Short times finite



$\sigma/\frac{1}{3}N^3$ vs N^2t

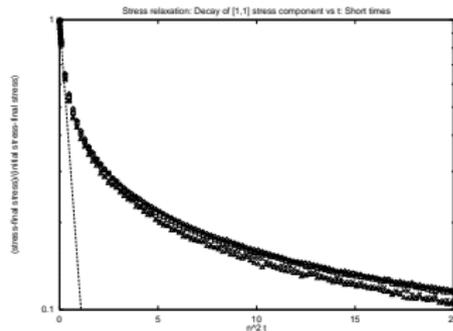
Relaxation of fully stretched chain

Long times - Rouse relaxation

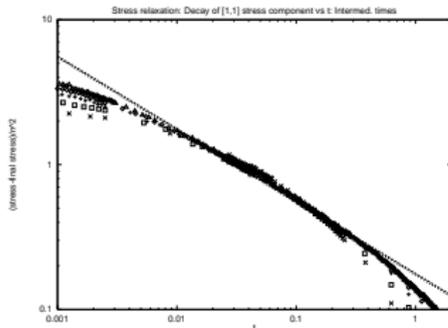


σ/N vs t/N^2 (Rouse)

Short times finite



$\sigma/\frac{1}{3}N^3$ vs N^2t



Intermediate times

$$\sigma \sim kTN^2t^{-1/2}$$

Constitutive equation – options

$$\begin{aligned}\nabla A &= -\frac{1}{h\tau} f(A - I) \\ \sigma &= -pI + 2\mu E + GfA\end{aligned}$$

Constitutive equation – options

$$\begin{aligned}\nabla A &= -\frac{1}{h\tau} f (A - I) \\ \sigma &= -pI + 2\mu E + GfA\end{aligned}$$

- ▶ Oldroyd B $f = 1$

Constitutive equation – options

$$\begin{aligned}\overset{\nabla}{A} &= -\frac{1}{h\tau} f (A - I) \\ \sigma &= -pI + 2\mu E + GfA\end{aligned}$$

- ▶ Oldroyd B $f = 1$
- ▶ FENE-P $f = L^2 / (L^2 - \text{trace } A)$

Constitutive equation – options

$$\begin{aligned}\nabla \cdot \mathbf{A} &= -\frac{1}{h\tau} f (\mathbf{A} - \mathbf{I}) \\ \boldsymbol{\sigma} &= -p\mathbf{I} + 2\mu\mathbf{E} + Gf\mathbf{A}\end{aligned}$$

- ▶ Oldroyd B $f = 1$
- ▶ FENE-P $f = L^2 / (L^2 - \text{trace } \mathbf{A})$
- ▶ Nonlinear bead friction $h = \sqrt{\text{trace } \mathbf{A} / 3}$

Constitutive equation – options

$$\begin{aligned}\nabla \cdot \mathbf{A} &= -\frac{1}{h\tau} f (\mathbf{A} - \mathbf{I}) \\ \sigma &= -p\mathbf{I} + 2\mu\mathbf{E} + Gf\mathbf{A}\end{aligned}$$

- ▶ Oldroyd B $f = 1$
- ▶ FENE-P $f = L^2 / (L^2 - \text{trace } \mathbf{A})$
- ▶ Nonlinear bead friction $h = \sqrt{\text{trace } \mathbf{A} / 3}$
- ▶ New form of stress

$$\sigma = -p\mathbf{I} + 2\mu\mathbf{E} + 2\mu_d(\mathbf{A} : \mathbf{E})\mathbf{A} + G\sqrt{\text{trace } \mathbf{A}}\mathbf{A}$$

Constitutive equation – options

$$\begin{aligned}\nabla \cdot \mathbf{A} &= -\frac{1}{h\tau} f(\mathbf{A} - \mathbf{I}) \\ \sigma &= -p\mathbf{I} + 2\mu\mathbf{E} + Gf\mathbf{A}\end{aligned}$$

- ▶ Oldroyd B $f = 1$
- ▶ FENE-P $f = L^2 / (L^2 - \text{trace } \mathbf{A})$
- ▶ Nonlinear bead friction $h = \sqrt{\text{trace } \mathbf{A} / 3}$
- ▶ New form of stress

$$\sigma = -p\mathbf{I} + 2\mu\mathbf{E} + 2\mu_d(\mathbf{A} : \mathbf{E})\mathbf{A} + G\sqrt{\text{trace } \mathbf{A}}\mathbf{A}$$

- ▶ Last term for finite stress when fully stretched

Constitutive equation – options

$$\begin{aligned}\nabla \cdot \mathbf{A} &= -\frac{1}{h\tau} f(\mathbf{A} - \mathbf{I}) \\ \boldsymbol{\sigma} &= -p\mathbf{I} + 2\mu\mathbf{E} + Gf\mathbf{A}\end{aligned}$$

- ▶ Oldroyd B $f = 1$
- ▶ FENE-P $f = L^2 / (L^2 - \text{trace } \mathbf{A})$
- ▶ Nonlinear bead friction $h = \sqrt{\text{trace } \mathbf{A} / 3}$
- ▶ New form of stress

$$\boldsymbol{\sigma} = -p\mathbf{I} + 2\mu\mathbf{E} + 2\mu_d(\mathbf{A} : \mathbf{E})\mathbf{A} + G\sqrt{\text{trace } \mathbf{A}}\mathbf{A}$$

- ▶ Last term for finite stress when fully stretched
- ▶ μ_d term ($\propto N^{-1/2}$) for enhanced dissipation

Constitutive equation – options

$$\nabla \cdot \mathbf{A} = -\frac{1}{h\tau} f (\mathbf{A} - \mathbf{I})$$
$$\boldsymbol{\sigma} = -p\mathbf{I} + 2\mu\mathbf{E} + Gf\mathbf{A}$$

- ▶ Oldroyd B $f = 1$
- ▶ FENE-P $f = L^2 / (L^2 - \text{trace } \mathbf{A})$
- ▶ Nonlinear bead friction $h = \sqrt{\text{trace } \mathbf{A} / 3}$
- ▶ New form of stress

$$\boldsymbol{\sigma} = -p\mathbf{I} + 2\mu\mathbf{E} + 2\mu_d(\mathbf{A} : \mathbf{E})\mathbf{A} + G\sqrt{\text{trace } \mathbf{A}}\mathbf{A}$$

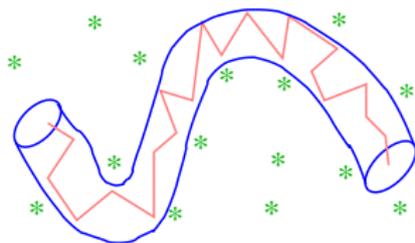
- ▶ Last term for finite stress when fully stretched
- ▶ μ_d term ($\propto N^{-1/2}$) for enhanced dissipation

Good for positive pressure drops and large upstream vortices in contraction flows.

Reptation model of De Gennes 1971 – often reformulated

Reptation model of De Gennes 1971 – often reformulated

Chain moves in tube defined by topological constraints from other chains.



Reptation model of De Gennes 1971 – often reformulated

Chain moves in tube defined by topological constraints from other chains.

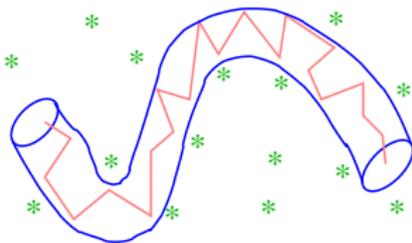


Chain disengages from tube by diffusing along its length

$$\tau_D = \frac{L^2}{D = kT/6\pi\mu L} \propto M^3$$

Reptation model of De Gennes 1971 – often reformulated

Chain moves in tube defined by topological constraints from other chains.



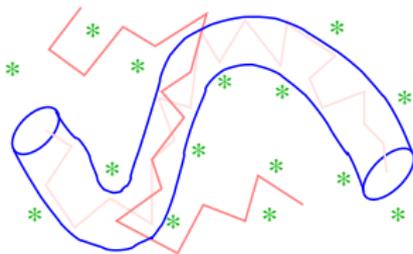
Chain disengages from tube by diffusing along its length

$$\tau_D = \frac{L^2}{D = kT/6\pi\mu L} \propto M^3$$

Modulus $G = nkT \rightarrow \mu^* = G\tau_D \propto M^3$ (expts $M^{3.4}$)

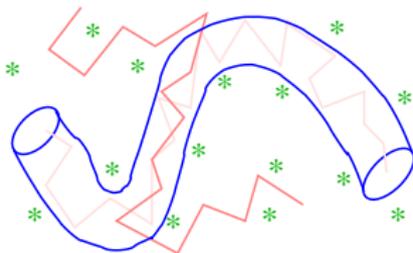
Diffusion out of tube

At later time:



Diffusion out of tube

At later time:



Fraction of original tube surviving

$$\sum_n \frac{1}{n^2} e^{-n^2 t / \tau_D}$$

Diffusion out of tube

At later time:



Fraction of original tube surviving

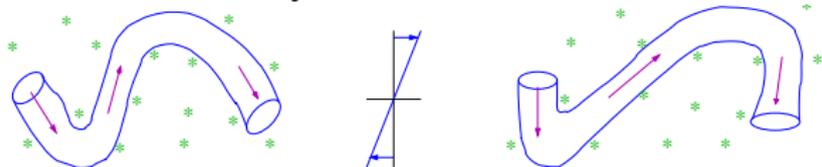
$$\sum_n \frac{1}{n^2} e^{-n^2 t / \tau_D}$$

Diffusion gives linear viscoelasticity $G' \propto \omega^{1/2}$

Doi-Edwards rheology 1978

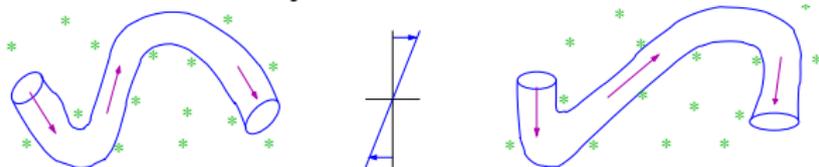
Doi-Edwards rheology 1978

Deformation of the tube by a shear flow.



Doi-Edwards rheology 1978

Deformation of the tube by a shear flow.

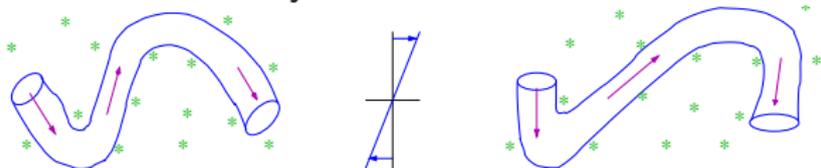


Unit segments of the tube \mathbf{u} aligned by flow:

$$\mathbf{u} \longrightarrow \mathbf{A}\mathbf{u} \quad \text{with Finger tensor } \mathbf{A}$$

Doi-Edwards rheology 1978

Deformation of the tube by a shear flow.



Unit segments of the tube \mathbf{u} aligned by flow:

$$\mathbf{u} \longrightarrow \mathbf{A}\mathbf{u} \quad \text{with Finger tensor } \mathbf{A}$$

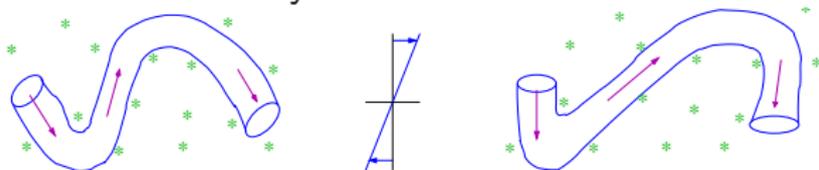
Stress

$$\sigma(t) = n \int_0^\infty \sum_p \frac{1}{p^2} e^{-p^2 s / \tau_D} \underbrace{N_{\text{segments}}}_{\text{surviving tube}} \underbrace{\frac{3kT}{a}}_{\text{segment tension}} a \left\langle \frac{\mathbf{A}^* \mathbf{u} \mathbf{A}^* \mathbf{u}}{|\mathbf{A}^* \mathbf{u}|^2} \right\rangle ds$$

with relative deformation $\mathbf{A}^* = \mathbf{A}(t)\mathbf{A}^{-1}(t-s)$.

Doi-Edwards rheology 1978

Deformation of the tube by a shear flow.



Unit segments of the tube \mathbf{u} aligned by flow:

$$\mathbf{u} \longrightarrow \mathbf{A}\mathbf{u} \quad \text{with Finger tensor } \mathbf{A}$$

Stress

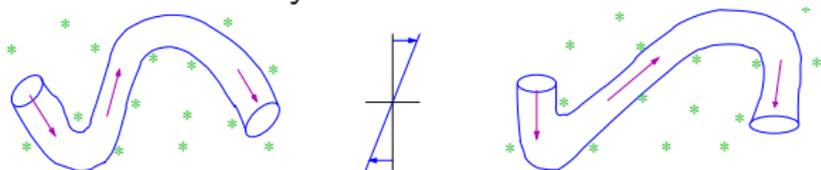
$$\sigma(t) = n \int_0^\infty \sum_p \frac{1}{p^2} e^{-p^2 s / \tau_D} \underbrace{N_{\text{segments}}}_{\text{surviving tube}} \underbrace{\frac{3kT}{a}}_{\text{segment tension}} a \left\langle \frac{\mathbf{A}^* \mathbf{u} \mathbf{A}^* \mathbf{u}}{|\mathbf{A}^* \mathbf{u}|^2} \right\rangle ds$$

with relative deformation $\mathbf{A}^* = \mathbf{A}(t)\mathbf{A}^{-1}(t-s)$.

A BKZ integral constitutive equation

Doi-Edwards rheology 1978

Deformation of the tube by a shear flow.



Unit segments of the tube \mathbf{u} aligned by flow:

$$\mathbf{u} \longrightarrow \mathbf{A}\mathbf{u} \quad \text{with Finger tensor } \mathbf{A}$$

Stress

$$\sigma(t) = n \int_0^\infty \sum_p \frac{1}{p^2} e^{-p^2 s / \tau_D} \underbrace{N_{\text{segments}}}_{\text{surviving tube}} \underbrace{\frac{3kT}{a}}_{\text{segment tension}} a \left\langle \frac{\mathbf{A}^* \mathbf{u} \mathbf{A}^* \mathbf{u}}{|\mathbf{A}^* \mathbf{u}|^2} \right\rangle ds$$

with relative deformation $\mathbf{A}^* = \mathbf{A}(t)\mathbf{A}^{-1}(t-s)$.

A BKZ integral constitutive equation

Problem maximum in shear stress

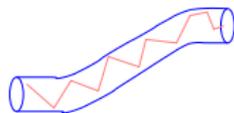
Refinements

Refinements

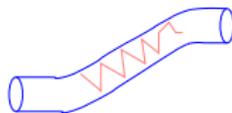
1. Chain retraction



deform \rightarrow

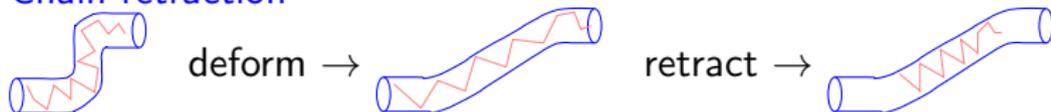


retract \rightarrow



Refinements

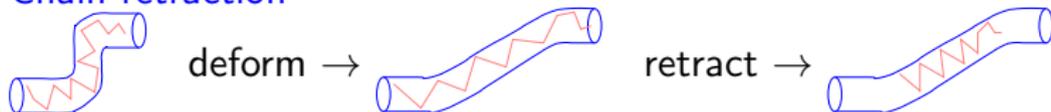
1. Chain retraction



Chain returns in Rouse time to natural length \rightarrow loss of segments

Refinements

1. Chain retraction

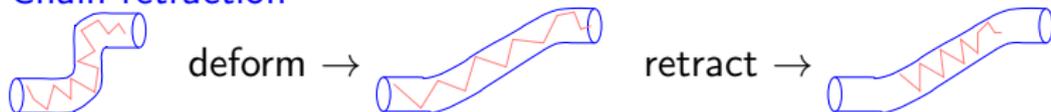


Chain returns in Rouse time to natural length \rightarrow loss of segments

2. Chain fluctuations

Refinements

1. Chain retraction



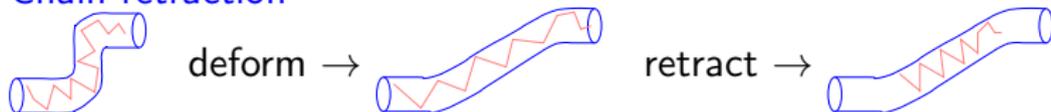
Chain returns in Rouse time to natural length \rightarrow loss of segments

2. Chain fluctuations

3. Other chains reptate \rightarrow release topological constraints
"Double reptation" of Des Cloiseaux 1990. bimodal blends

Refinements

1. Chain retraction



Chain returns in Rouse time to natural length \rightarrow loss of segments

2. Chain fluctuations

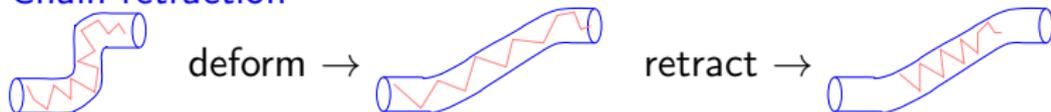
3. Other chains reptate \rightarrow release topological constraints

“Double reptation” of Des Cloiseaux 1990. bimodal blends

4. 2 & 3 give $\mu \propto M^{3.4}$

Refinements

1. Chain retraction



Chain returns in Rouse time to natural length \rightarrow loss of segments

2. Chain fluctuations

3. Other chains reptate \rightarrow release topological constraints

“Double reptation” of Des Cloiseaux 1990. bimodal blends

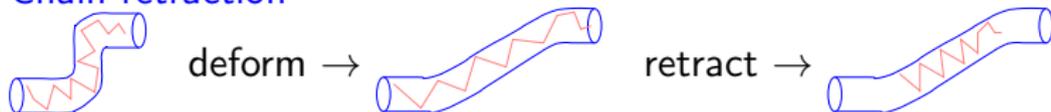
4. 2 & 3 give $\mu \propto M^{3.4}$

5. Advected constraint release Marrucci 1996

$$\frac{1}{\tau_D} \longrightarrow \frac{1}{\tau_D} + \beta \nabla u : \langle uu \rangle$$

Refinements

1. Chain retraction



Chain returns in Rouse time to natural length \rightarrow loss of segments

2. Chain fluctuations

3. Other chains reptate \rightarrow release topological constraints
“Double reptation” of Des Cloiseaux 1990. bimodal blends

4. 2 & 3 give $\mu \propto M^{3.4}$

5. Advected constraint release Marrucci 1996

$$\frac{1}{\tau_D} \longrightarrow \frac{1}{\tau_D} + \beta \nabla u : \langle uu \rangle$$

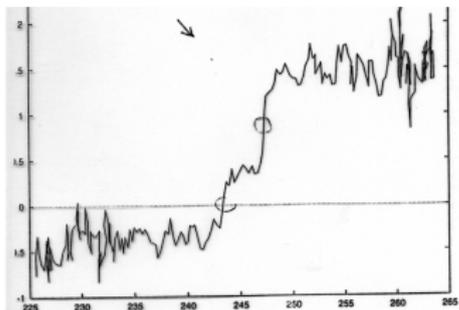
6. Flow changes tube volume or cross-section

Chain trapped in a fast shearing lattice

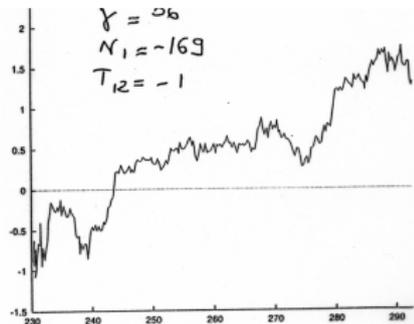
Lattice for other chains

Chain trapped in a fast shearing lattice

Lattice for other chains



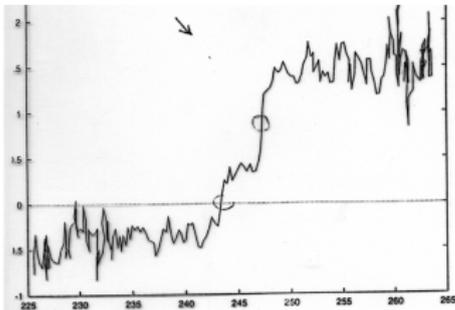
more shear \rightarrow



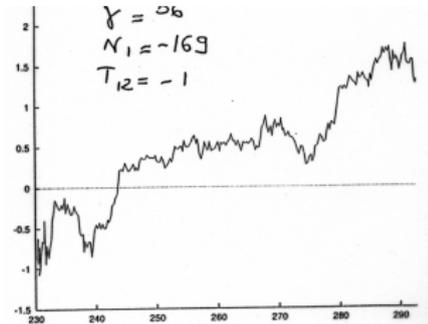
central section pulling chain out of arms

Chain trapped in a fast shearing lattice

Lattice for other chains



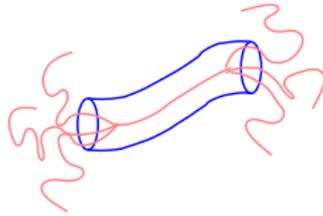
more shear \rightarrow



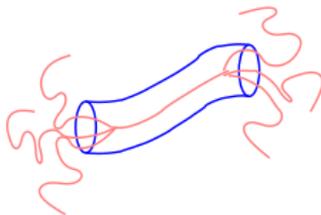
central section pulling chain out of arms \rightarrow high dissipative stresses

Ianniruberto, Marrucci & H 98

Branched polymers – typical in industry



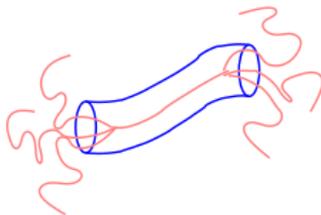
Branched polymers – typical in industry



Very difficult to pull branches into central tube

$$\mu \propto \exp(M_{\text{arm}}/M_{\text{entangle}})$$

Branched polymers – typical in industry

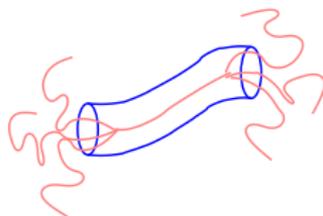


Very difficult to pull branches into central tube

$$\mu \propto \exp(M_{\text{arm}}/M_{\text{entangle}})$$

Pom-Pom model of Tom McLeish and Ron Larson 1999

Branched polymers – typical in industry



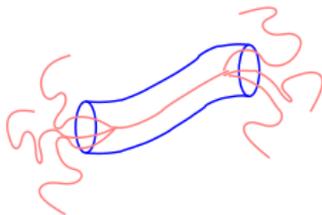
Very difficult to pull branches into central tube

$$\mu \propto \exp(M_{\text{arm}}/M_{\text{entangle}})$$

Pom-Pom model of Tom McLeish and Ron Larson 1999

$$\text{Stress: } \sigma = G\lambda^2\mathbf{S}$$

Branched polymers – typical in industry



Very difficult to pull branches into central tube

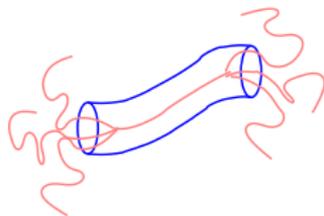
$$\mu \propto \exp(M_{\text{arm}}/M_{\text{entangle}})$$

Pom-Pom model of Tom McLeish and Ron Larson 1999

$$\text{Stress: } \sigma = G\lambda^2 \mathbf{S}$$

$$\text{Orientation: } \mathbf{S} = \mathbf{B}/\text{trace}\mathbf{B} \quad \overset{\nabla}{\mathbf{B}} = -\frac{1}{\tau_0}(\mathbf{B} - \mathbf{I})$$

Branched polymers – typical in industry



Very difficult to pull branches into central tube

$$\mu \propto \exp(M_{\text{arm}}/M_{\text{entangle}})$$

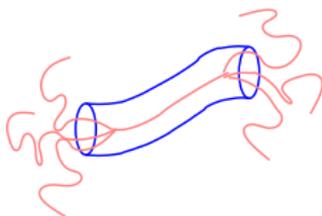
Pom-Pom model of Tom McLeish and Ron Larson 1999

$$\text{Stress: } \sigma = G\lambda^2 \mathbf{S}$$

$$\text{Orientation: } \mathbf{S} = \mathbf{B}/\text{trace}\mathbf{B} \quad \overset{\nabla}{\mathbf{B}} = -\frac{1}{\tau_0}(\mathbf{B} - \mathbf{I})$$

$$\text{Stretch: } \dot{\lambda} = \overset{\nabla}{u} : \mathbf{S} - \frac{1}{\tau_S}(\lambda - 1) \quad \text{while } \lambda < \lambda_{\text{max}}$$

Branched polymers – typical in industry



Very difficult to pull branches into central tube

$$\mu \propto \exp(M_{\text{arm}}/M_{\text{entangle}})$$

Pom-Pom model of Tom McLeish and Ron Larson 1999

$$\text{Stress: } \sigma = G\lambda^2 \mathbf{S}$$

$$\text{Orientation: } \mathbf{S} = \mathbf{B}/\text{trace}\mathbf{B} \quad \mathbf{B} = -\frac{1}{\tau_O}(\nabla \cdot \mathbf{B} - \mathbf{I})$$

$$\text{Stretch: } \dot{\lambda} = \nabla u : \mathbf{S} - \frac{1}{\tau_S}(\lambda - 1) \quad \text{while } \lambda < \lambda_{\max}$$

with $\tau_O = \tau_{\text{arm}}(M_C/M_E)^3$ and $\tau_S = \tau_{\text{arm}}(M_C/M_E)^2$ and

$\tau_{\text{arm}} \cong \exp(M_{\text{arm}}/M_E)$ where $M_C = M_{\text{crossbar}}$ and $M_E = M_{\text{entanglement}}$.

Fit: Linear Viscoelastic data and Steady Uni-axial Extension.

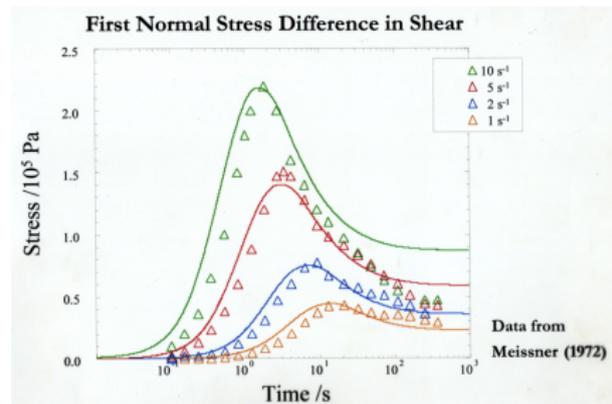
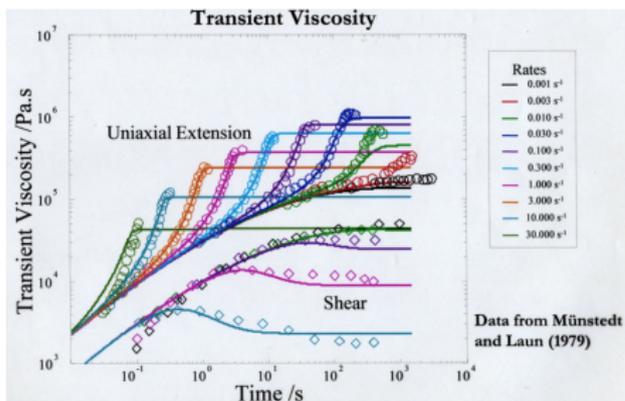
Test of Pom-Pom model – Blackwell 2002

Fit: Linear Viscoelastic data and Steady Uni-axial Extension.

Predict: Transient Shear and Transient Normal Stress

Test of Pom-Pom model – Blackwell 2002

Fit: Linear Viscoelastic data and Steady Uni-axial Extension.
Predict: Transient Shear and Transient Normal Stress



IUPAC-A data Münstedt & Laun (1979)

Polymers

- ▶ Single polymer
 - ▶ Bead-and-spring model
 - ▶ Refinements
 - ▶ FENE-P constitutive equation
 - ▶ Unravelling a polymer chain
 - ▶ Kinks model
 - ▶ Brownian simulations
- ▶ Entangled polymers
 - ▶ rheology
 - ▶ Refinements
 - ▶ pom-pom

Other microstructural studies

Other microstructural studies

- ▶ Electro- and Magneto- -rheological fluids

Other microstructural studies

- ▶ Electro- and Magneto- -rheological fluids
- ▶ Associating polymers

Other microstructural studies

- ▶ Electro- and Magneto- -rheological fluids
- ▶ Associating polymers
- ▶ Surfactants - micells

Other microstructural studies

- ▶ Electro- and Magneto- -rheological fluids
- ▶ Associating polymers
- ▶ Surfactants - micells
- ▶ Aging materials

Other microstructural studies

- ▶ Electro- and Magneto- -rheological fluids
- ▶ Associating polymers
- ▶ Surfactants - micells
- ▶ Aging materials
- ▶ GENERIC

Other microstructural studies

- ▶ Electro- and Magneto- -rheological fluids
- ▶ Associating polymers
- ▶ Surfactants - micells
- ▶ Aging materials
- ▶ GENERIC
- ▶ Modelling 'Molecular individualism' and closure problems

- ▶ Micro & macro views
- ▶ Einstein viscosity
- ▶ Rotations
- ▶ Deformations
- ▶ Interactions
- ▶ Polymers
- ▶ Others