

Discretization woes for NLEVPs

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Joint work with
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(Cornell)



Nonlinear spectral problems (NEPs)

Many* NEPs are set in infinite-dimensional spaces.

Infinite-dimensional
Hilbert space

$$T(\lambda): \mathcal{D}(T) \mapsto \mathcal{H}, \quad \lambda \in \Omega \subset \mathbb{C}$$

$$\lambda \rightarrow T(\lambda)u \quad \text{holomorphic for all} \quad u \in \mathcal{D}(T)$$

$$\text{Sp}(T) = \{\lambda \in \Omega : T(\lambda) \text{ is not invertible}\}$$

$$\text{Sp}_d(T) = \{\lambda \in \text{Sp}(T) : \lambda \text{ isolated, } T(\lambda) \text{ Fredholm}\}$$

$$\text{Sp}_{\text{ess}}(T) = \text{Sp}(T) \setminus \text{Sp}_d(T)$$

* 25/52 problems from NLEVP collection are discretized infinite-dimensional problems.

* A vast majority of applications of NEPs involve differential operators.

- Güttel, Tisseur, "The nonlinear eigenvalue problem," *Acta Numerica*, 2017.
- Betcke, Higham, Mehrmann, Schröder, Tisseur, "NLEVP: A collection of nonlinear eigenvalue problems," *ACM Trans. Math. Soft.*, 2013.

Discretization woes (examples later)

Often, we discretize to a matrix NEP

$$\lambda \mapsto F(\lambda) \in \mathbb{C}^{n \times n}, \quad \lambda \in \Omega \subset \mathbb{C}$$

But can cause serious issues:

- Spectral pollution (spurious eigenvalues).
- Spectral invisibility.
- Super-slow convergence (nonlinearity can make this even worse!)
- Ill-conditioning, even if $T(\lambda)$ is well-conditioned.
- Essential spectra, accumulating eigenvalues etc.
- Ghost essential spectra.



WARNING: Some inf-dim comp. spec. problems cannot be solved, regardless of computational power, time or model.

Computational tool #1: Pseudospectra

$$\mathcal{A}(\varepsilon) = \left\{ E: \Omega \rightarrow \mathcal{B}(\mathcal{H}) \text{ holomorphic: } \sup_{\lambda \in \Omega} \|E(\lambda)\| < \varepsilon \right\}$$

$$\text{Sp}_\varepsilon(T) = \bigcup_{E \in \mathcal{A}(\varepsilon)} \text{Sp}(T + E) = \{\lambda \in \Omega: \|T(\lambda)^{-1}\|^{-1} < \varepsilon\}$$



Stability of spectrum



Characterization through resolvent

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FACT: $\|T(\lambda)^{-1}\|^{-1} = \min\{\sigma_{\inf}(T(\lambda)), \sigma_{\inf}(T(\lambda)^*)\}$

$$\sigma_{\inf}(A) = \inf\{\|Av\|: v \in \mathcal{D}(A), \|v\| = 1\}$$

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Rectangular sections
 $\sigma_{\inf}(\mathcal{P}_{f(n)} T(\lambda) \mathcal{P}_n^*)$



Folding
 $\sqrt{\sigma_{\inf}(\mathcal{P}_n T(\lambda)^* T(\lambda) \mathcal{P}_n^*)}$

- C., Hansen, “The foundations of spectral computations via the solvability complexity index hierarchy,” **J. Eur. Math. Soc.**, 2022.
- C., Townsend, “Rigorous data-driven computation of spectral properties of Koopman operators for dynamical systems,” **CPAM**, to appear.

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THEOREM: Let $\Gamma_n(T, \varepsilon) = \{\lambda \in \Omega: \gamma_n(\lambda) < \varepsilon\}$, then (in the Attouch-Wets metric)

$$\lim_{n \rightarrow \infty} \Gamma_n(T, \varepsilon) = \text{Sp}_\varepsilon(T), \quad \Gamma_n(T, \varepsilon) \subset \text{Sp}_\varepsilon(T).$$

$$\sigma_{\inf}(A) = \inf\{\|Av\|: v \in \mathcal{D}(A), \|v\| = 1\}$$

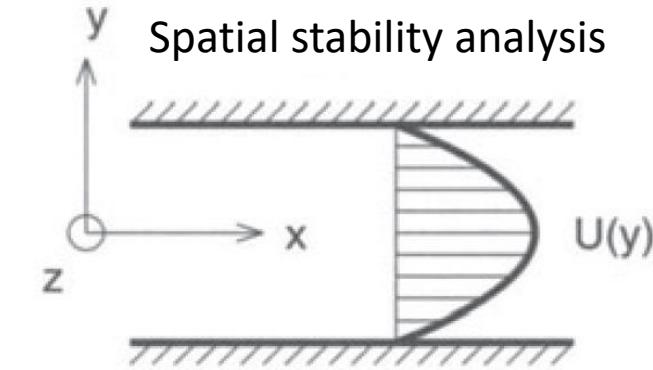
Example of verification: Orr-Sommerfeld

Poiseuille flow: $U(y) = 1 - y^2, y \in [-1,1]$

$R = 5772.22, \omega = 0.264002$

$$A(\lambda)\phi = \left[\frac{1}{R} B(\lambda)^2 + i(\lambda U(y) - \omega)B(\lambda) + i\lambda U''(y) \right] \phi$$

$$B(\lambda)\phi = -\frac{d^2\phi}{dy^2} + \lambda^2\phi, \quad \langle \phi, \psi \rangle = \int_{-1}^1 \phi \bar{\psi} + \frac{d\phi}{dy} \frac{d\bar{\psi}}{dy} dy, \quad T(\lambda) = B(\lambda)^{-1} A(\lambda)$$



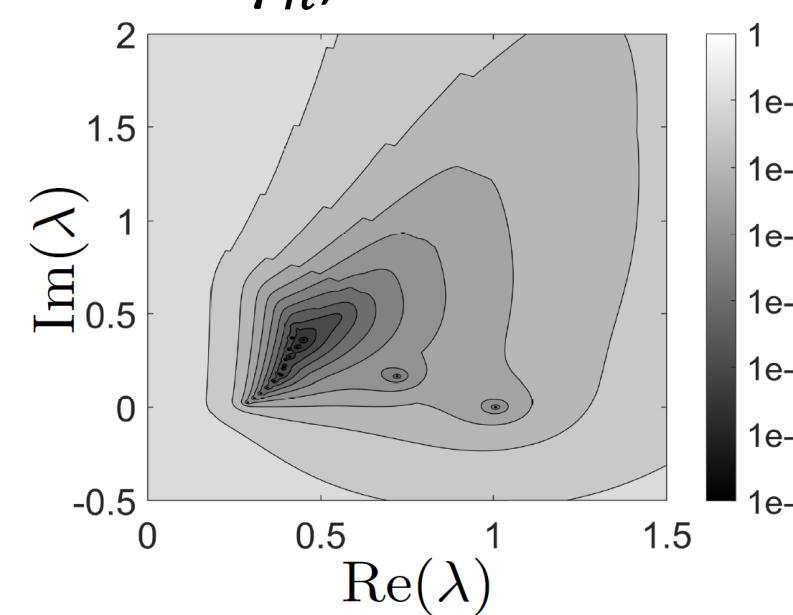
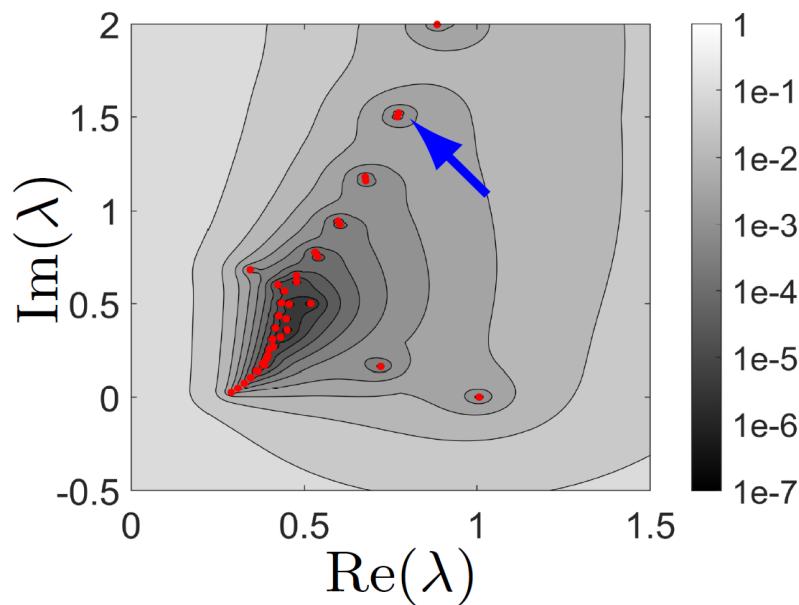
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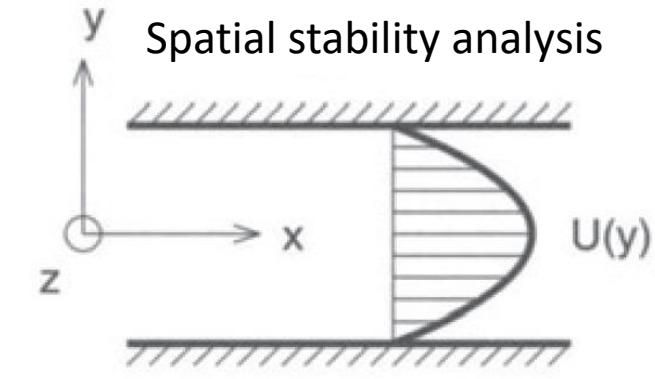
$$T(\lambda) = B(\lambda)^{-1}A(\lambda)$$

Cheb. Col., $n = 64$



$$\{\lambda \in \Omega : \gamma_n(\lambda) < \varepsilon\} \subset \text{Sp}_\varepsilon(T)$$

$$\gamma_n, n = 64$$



Which do we trust?

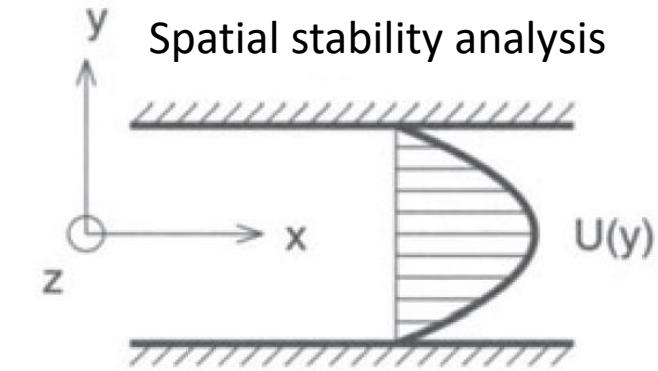
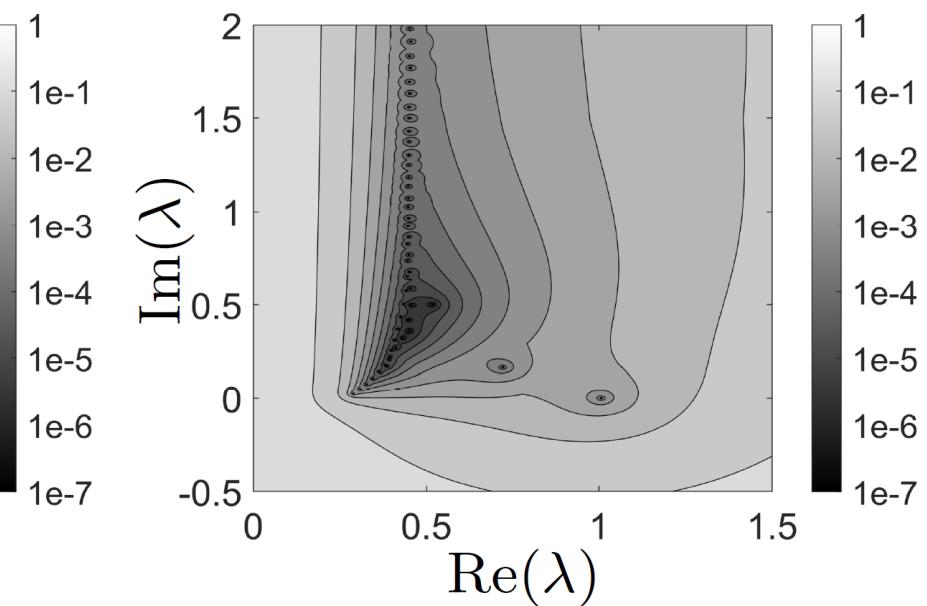
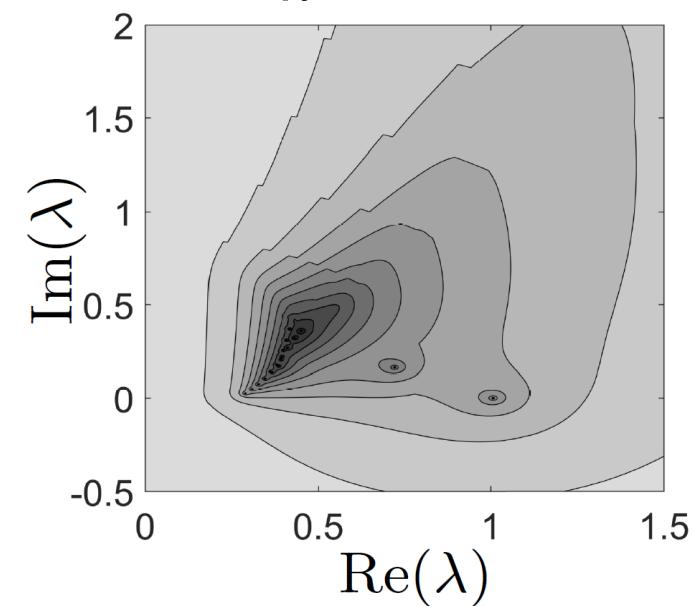
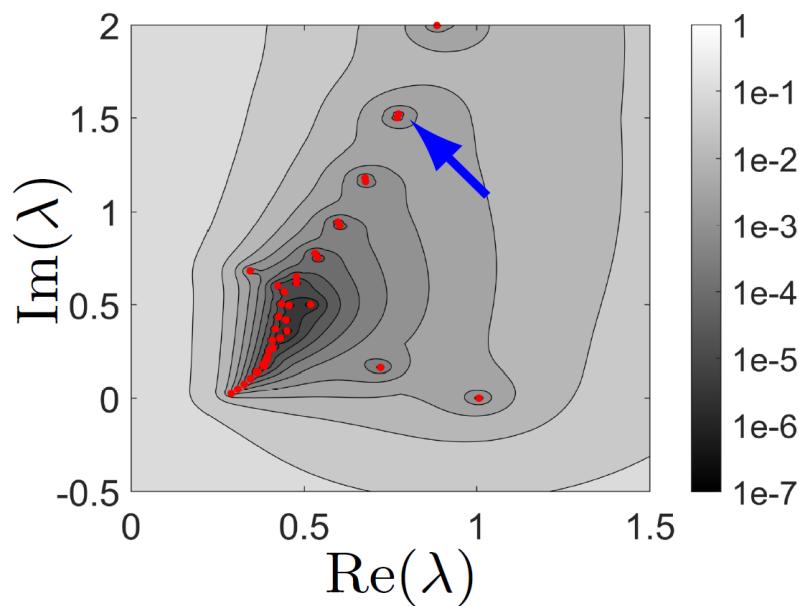
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Example of verification: Orr-Sommerfeld

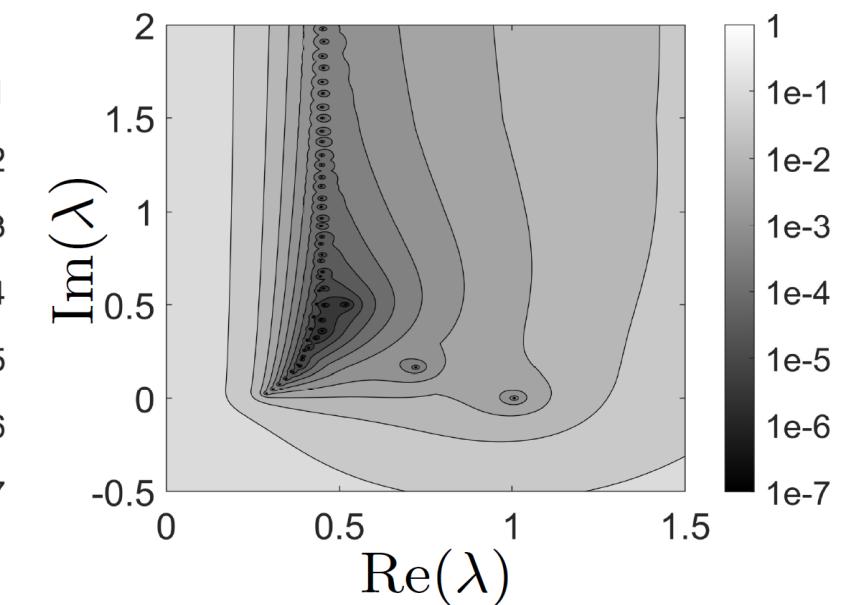
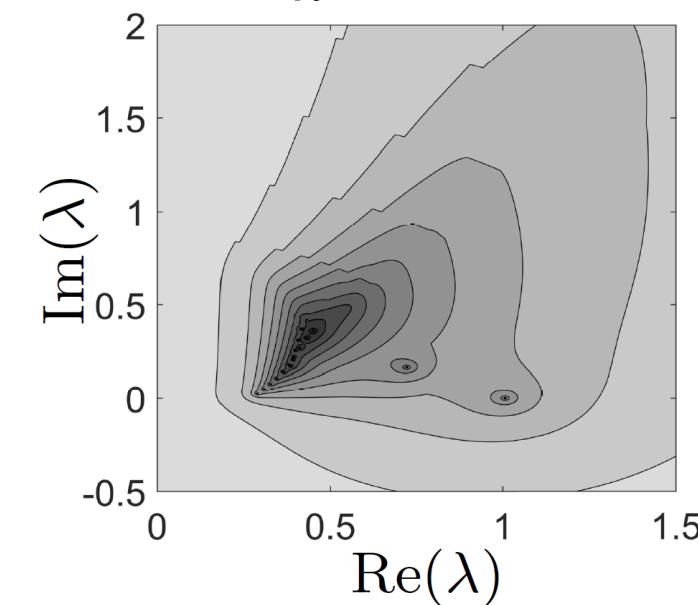
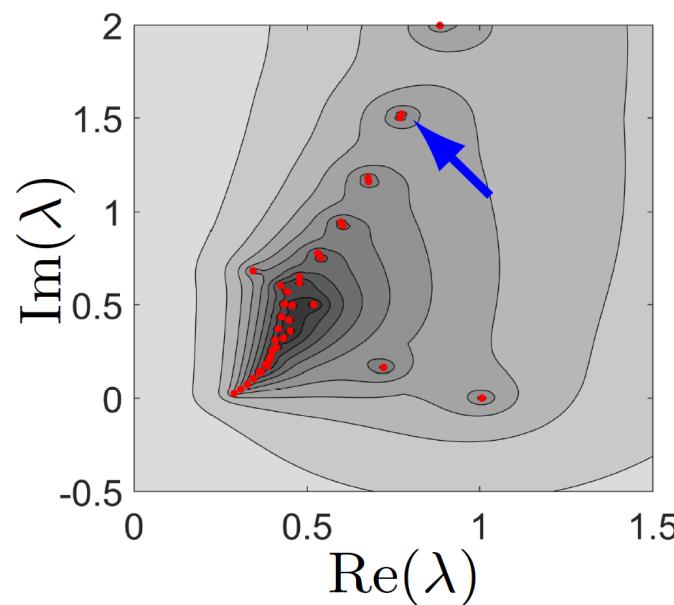
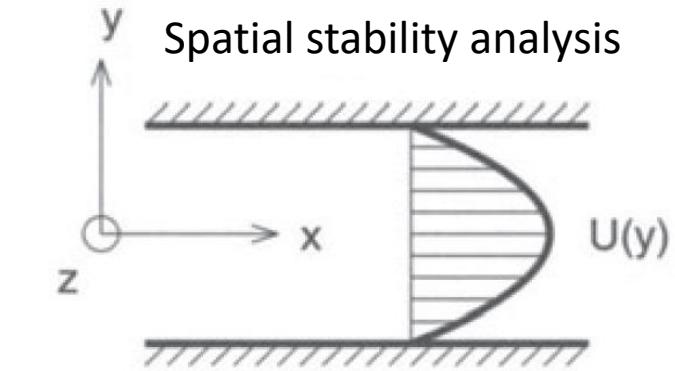
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$$T(\lambda) = B(\lambda)^{-1}A(\lambda)$$

Cheb. Col., $n = 64$

$$\{\lambda \in \Omega : \gamma_n(\lambda) < \varepsilon\} \subset \text{Sp}_\varepsilon(T)$$



Converged

NB: Standard method converges in this case but doesn't have verification.

Computational tool #2: Contour methods

KELDYSH's THEOREM: Suppose $\text{Sp}_{\text{ess}}(T) \cap \Omega = \emptyset$. Then for $z \in \Omega \setminus \text{Sp}(T)$

$$T(z)^{-1} = V(z - J)^{-1}W^* + R(z)$$

- m is sum of all algebraic multiplicities of eigenvalues inside Ω .
- V & W are quasimatrices with m cols of right & left generalized eigenvectors.
- J consists of Jordan blocks.
- $R(z)$ is a bounded holomorphic remainder.

⇒ use contour integration to convert to a linear pencil...

-
- Keldysh, “On the characteristic values and characteristic functions of certain classes of non-self-adjoint equations,” **Dokl. Akad. Nauk**, 1951.
 - Keldysh, “On the completeness of the eigenfunctions of some classes of non-self-adjoint linear operators,” **UMN**, 1971.

InfBeyn algorithm

Let $\Gamma \subset \Omega$ be a contour enclosing m eigenvalues (and not touching $\text{Sp}(T)$).

$$A_0 = \frac{1}{2\pi i} \int_{\Gamma} T(z)^{-1} \mathcal{V} dz, \quad A_1 = \frac{1}{2\pi i} \int_{\Gamma} z T(z)^{-1} \mathcal{V} dz$$

Random vectors drawn from a Gaussian process

Computed with adaptive discretization sizes (e.g., ultraspherical spectral method)

Approximate through quadrature to obtain \tilde{A}_0 and \tilde{A}_1 .

Truncated SVD: $\tilde{A}_0 \approx \tilde{\mathcal{U}} \Sigma_0 \tilde{\mathcal{V}}_0^*$.

Form the linear pencil: $\tilde{F}(z) = \tilde{\mathcal{U}}^* \tilde{A}_1 \tilde{\mathcal{V}}_0 - z \tilde{\mathcal{U}}^* \tilde{A}_0 \tilde{\mathcal{V}}_0 \in \mathbb{C}^{m \times m}$.

NB: $m = \text{Trace} \left(\frac{1}{2\pi i} \int_{\Gamma} T'(z) T(z)^{-1} dz \right)$ can compute this (another story).

- Beyn, “An integral method for solving nonlinear eigenvalue problems,” *Linear Algebra Appl.*, 2012.
- C. Townsend, “Avoiding discretization issues for nonlinear eigenvalue problem”, preprint.

Stability and convergence result

Keldysh: $T(z)^{-1} = V(z - J)^{-1}W^* + R(z)$, let $M = \sup_{z \in \Omega} \|R(z)\|$.

Suppose that $\|\tilde{A}_j - A_j\| \leq \varepsilon$.

THEOREM: For sufficiently oversampled \mathcal{V} , with overwhelming probability,

$$|\sigma_{\inf}(F(z)) - \sigma_{\inf}(\tilde{F}(z))| \leq 2(\varepsilon + \|VJW^*\|\varepsilon/\sigma_m(VW^*) + |z|\varepsilon) \text{ (quad. err.)}$$

$$\text{Sp}_{\frac{\varepsilon}{\|VW^*\|\|VW^*\mathcal{V}\|+M\varepsilon}}(T) \subset \text{Sp}_{\varepsilon}(F) \subset \text{Sp}_{\frac{\varepsilon}{\sigma_m(VW^*)\sigma_m(VW^*\mathcal{V})-M\varepsilon}}(T).$$

⇒ **converges**
no spectral pollution
no spectral invisibility
method is stable

NOT a statement on computing $\text{Sp}_{\varepsilon}(T)$
(the other algorithm does that!)

- C., Townsend, "Avoiding discretization issues for nonlinear eigenvalue problem", preprint.
- Horning, Townsend, "FEAST for differential eigenvalue problems," *SIAM J. Math. Anal.*, 2020.
- C., "Computing semigroups with error control," *SIAM J. Math. Anal.*, 2022.

Stability bound

How to control quad error

Proof sketch

Keldysh: $T(z)^{-1} = V(z - J)^{-1}W^* + R(z)$, let $M = \sup_{z \in \Omega} \|R(z)\|$.

Introduce: $L_1 = (VW^*)^\dagger$, $L_2 = (VW^*\mathcal{V}V_0)^\dagger$.

$$T(z)^{-1}L_1F(z) = -VW^*\mathcal{V}V_0 + R(z)L_1F(z)$$

$$\sigma_{\inf}(F(z)) < \varepsilon \Rightarrow \|T(z)^{-1}\| > \frac{\sigma_m(VW^*)\sigma_m(VW^*\mathcal{V})}{\varepsilon} - M$$

$$F(z)L_2[T(z)^{-1} - R(z)] = -VW^*$$

$$\|T(z)^{-1}\| > \varepsilon \Rightarrow \sigma_{\inf}(F(z)) < \frac{\|VW^*\| \|VW^*\mathcal{V}\|}{1 - M\varepsilon} \varepsilon$$

Use results from inf dim randomized NLA to bound terms with a \mathcal{V} .

Example 1: One-dimensional acoustic wave

acoustic_wave_1d from NLEVP collection.

$$\frac{d^2p}{dx^2} + 4\pi^2\lambda^2 p = 0, \quad p(0) = 0, \quad \chi p'(1) + 2\pi i \lambda p(1) = 0$$

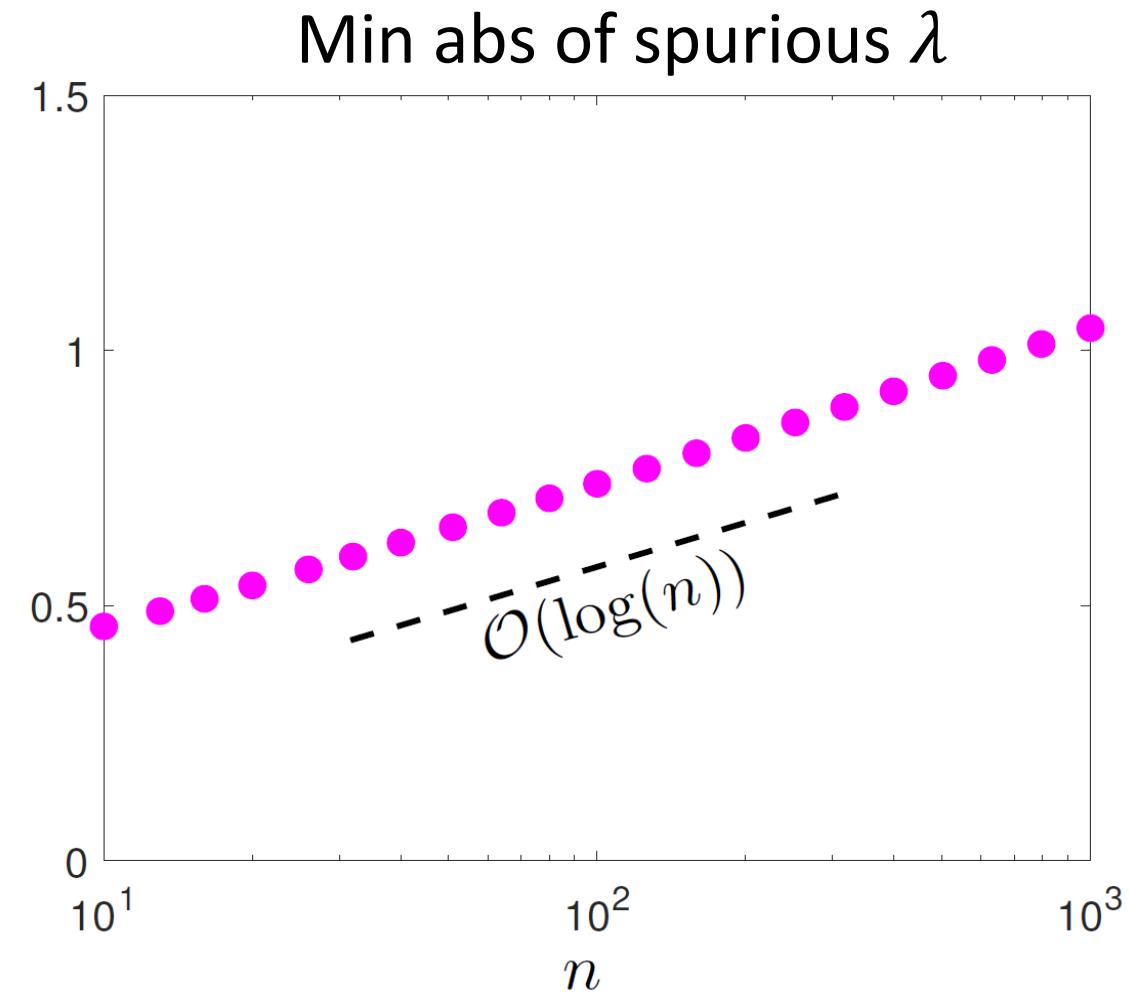
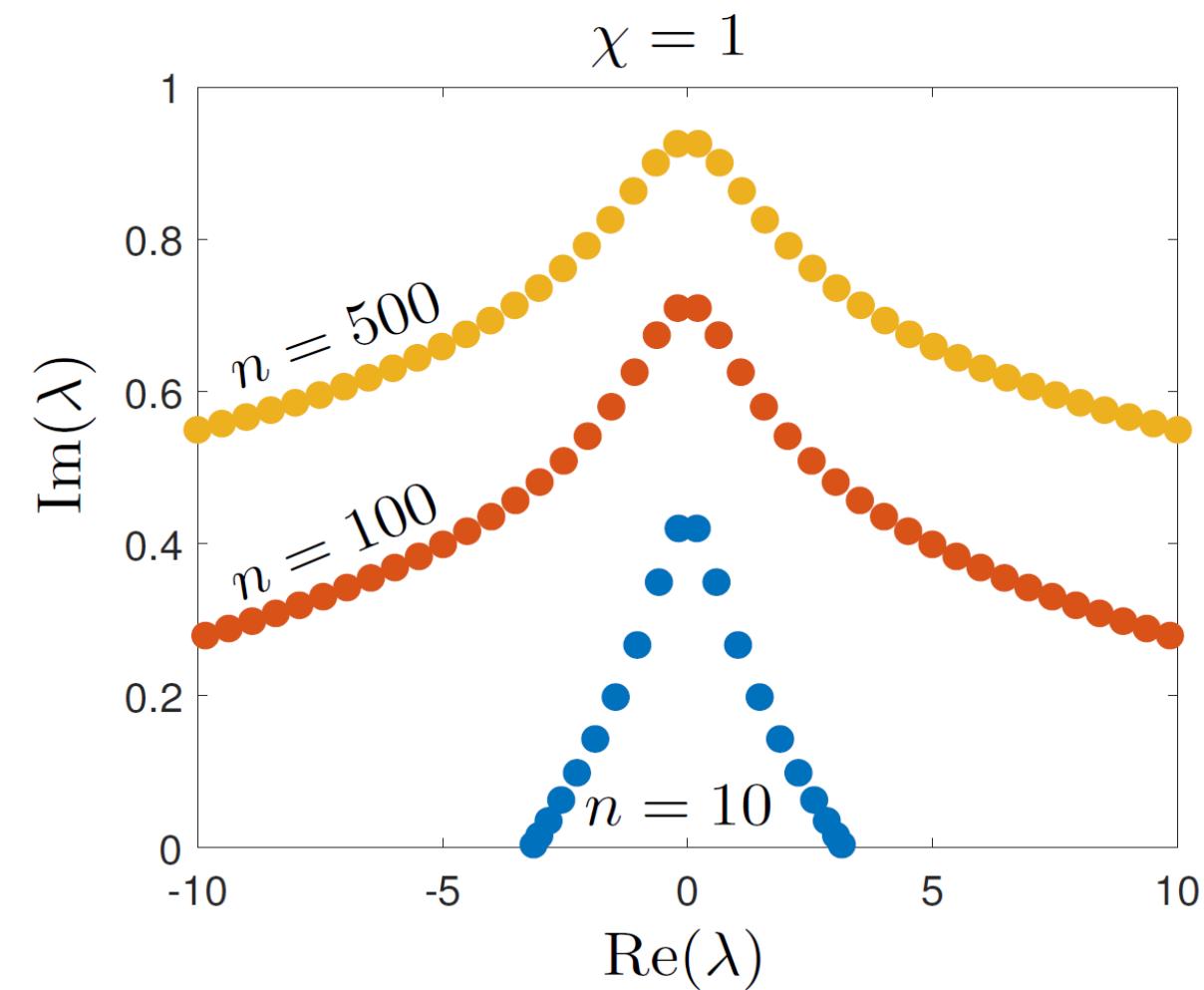
p corresponds to acoustic pressure.

Resonant frequencies: $\lambda_k = \frac{\tan^{-1}(i\chi)}{2\pi} + \frac{k}{2}, \quad k \in \mathbb{Z}$

Discretized using FEM (n = discretization size)

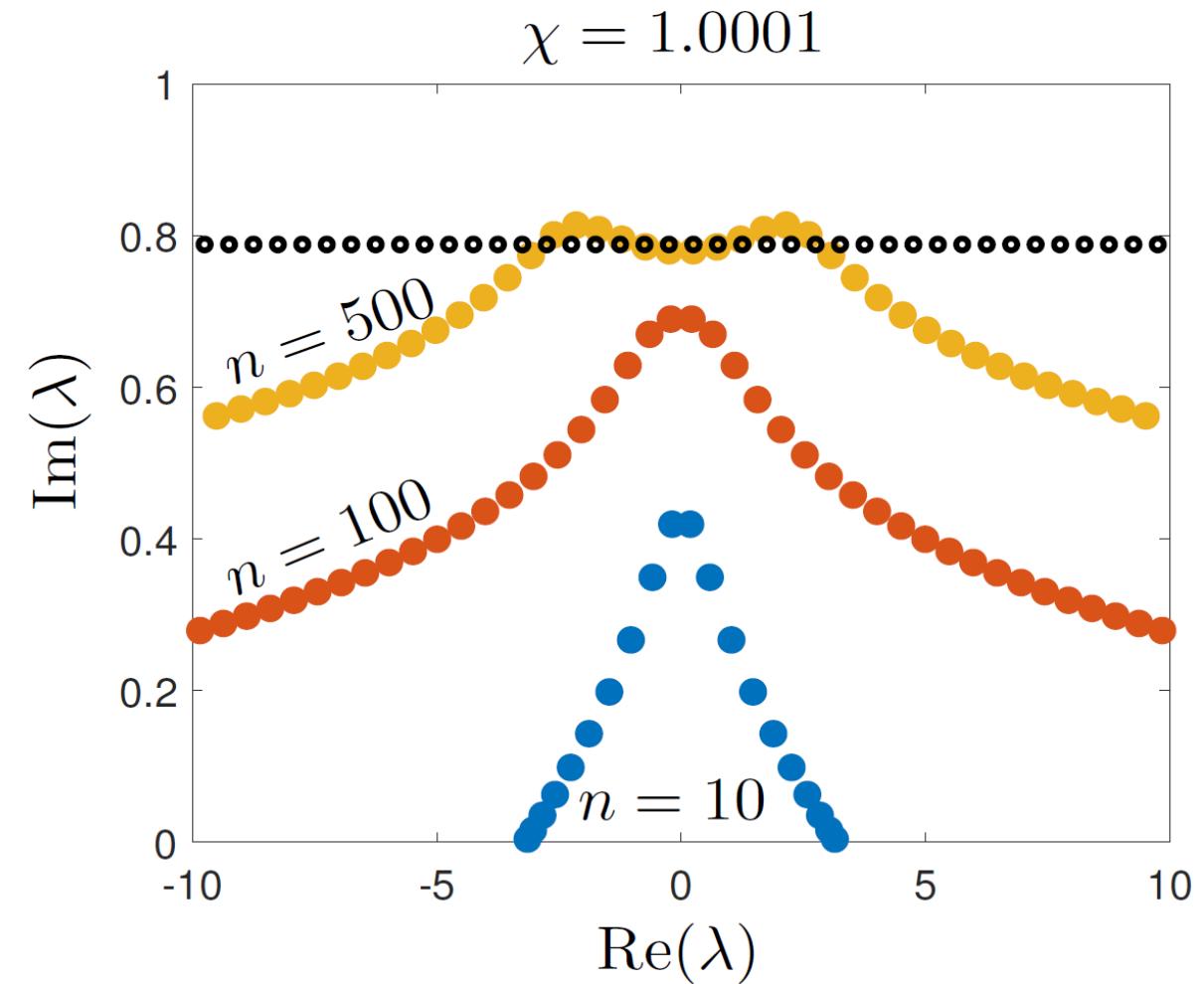
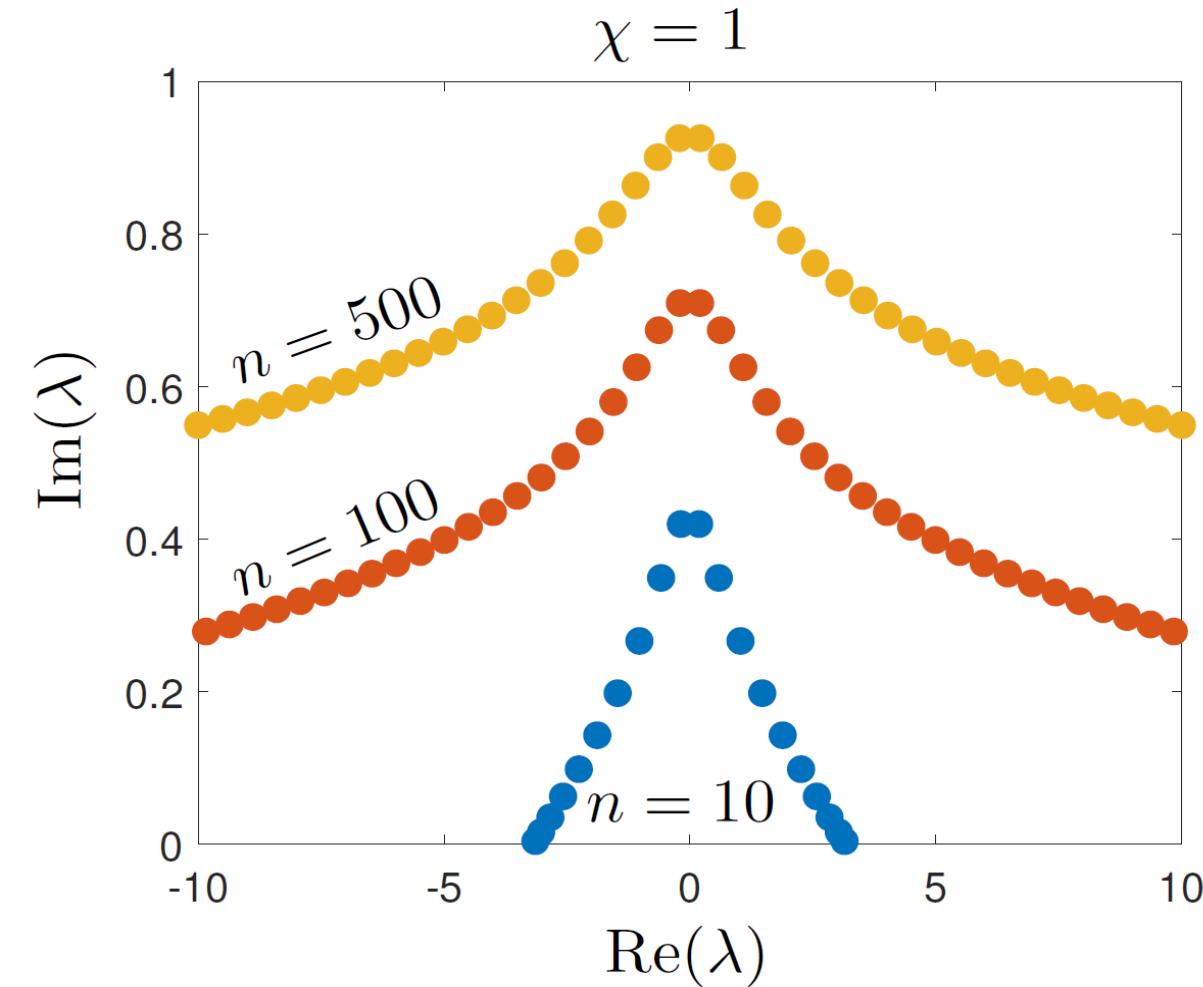
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butterfly from NLEVP collection

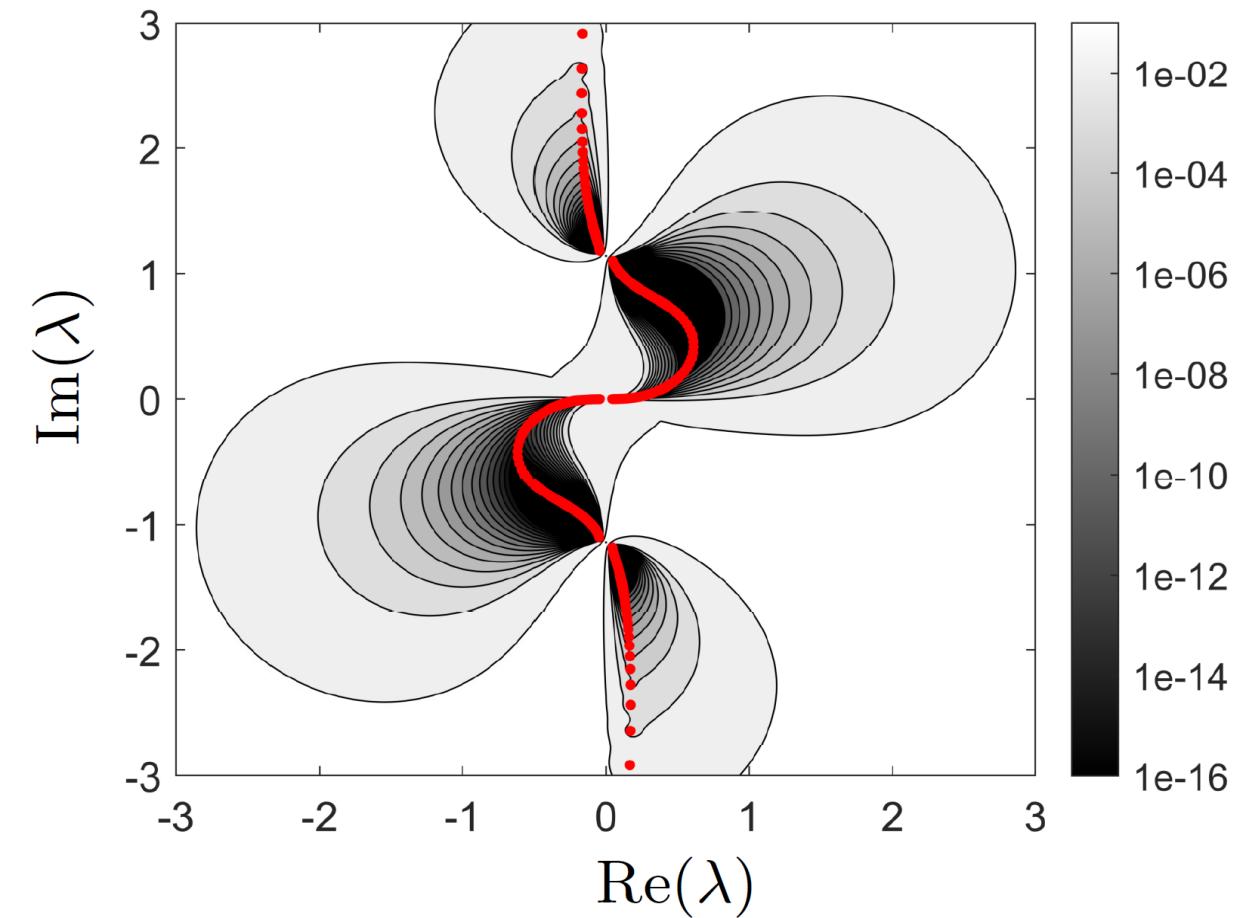
$$T(\lambda) = F(\lambda, S)$$

S bilateral shift on $l^2(\mathbb{Z})$

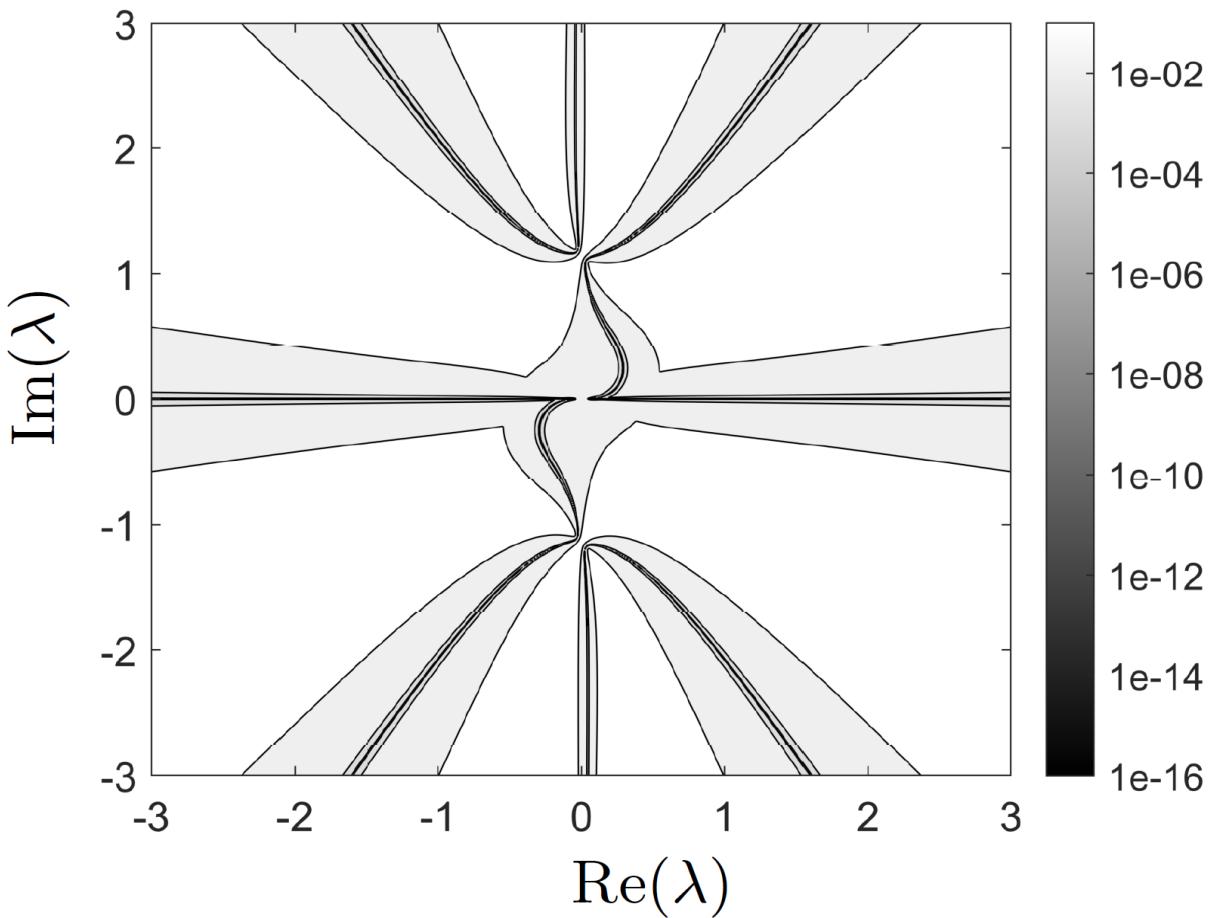
F a rational function

Example 2: Butterfly

Discretized $\mathcal{P}_n T(\lambda) \mathcal{P}_n^*$ ($n = 500$)



Method based on γ_n

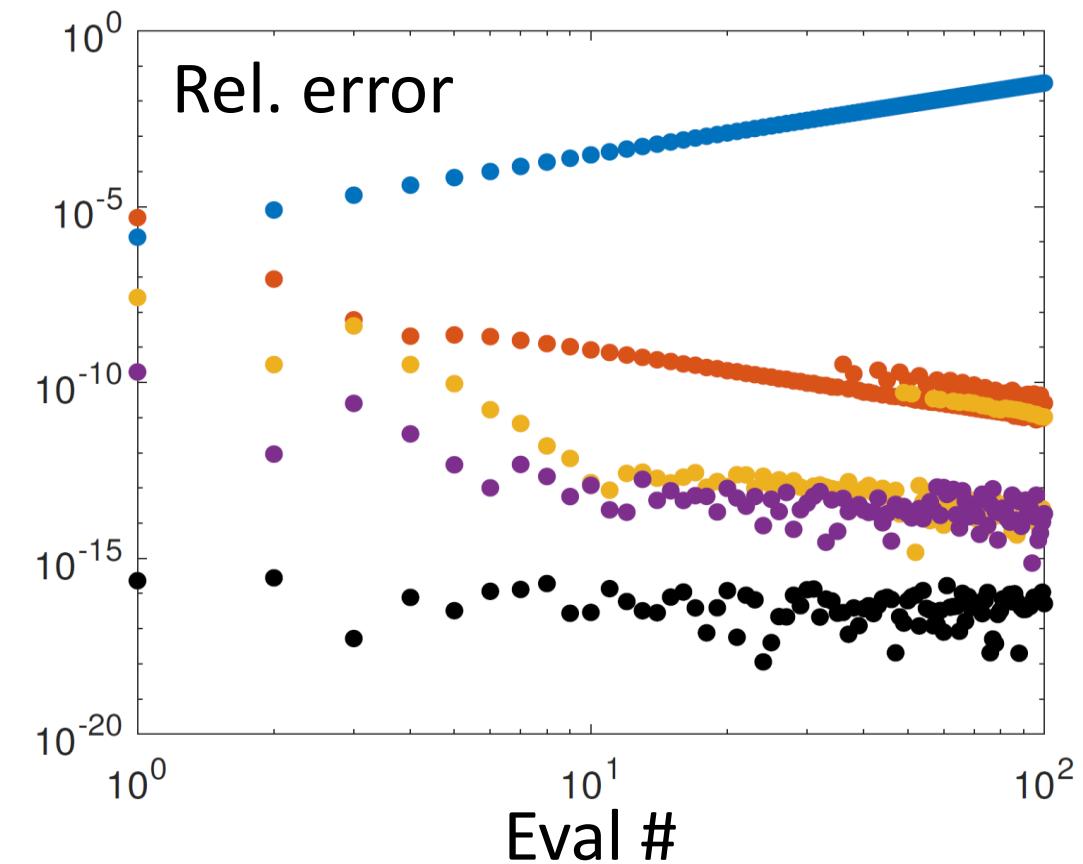
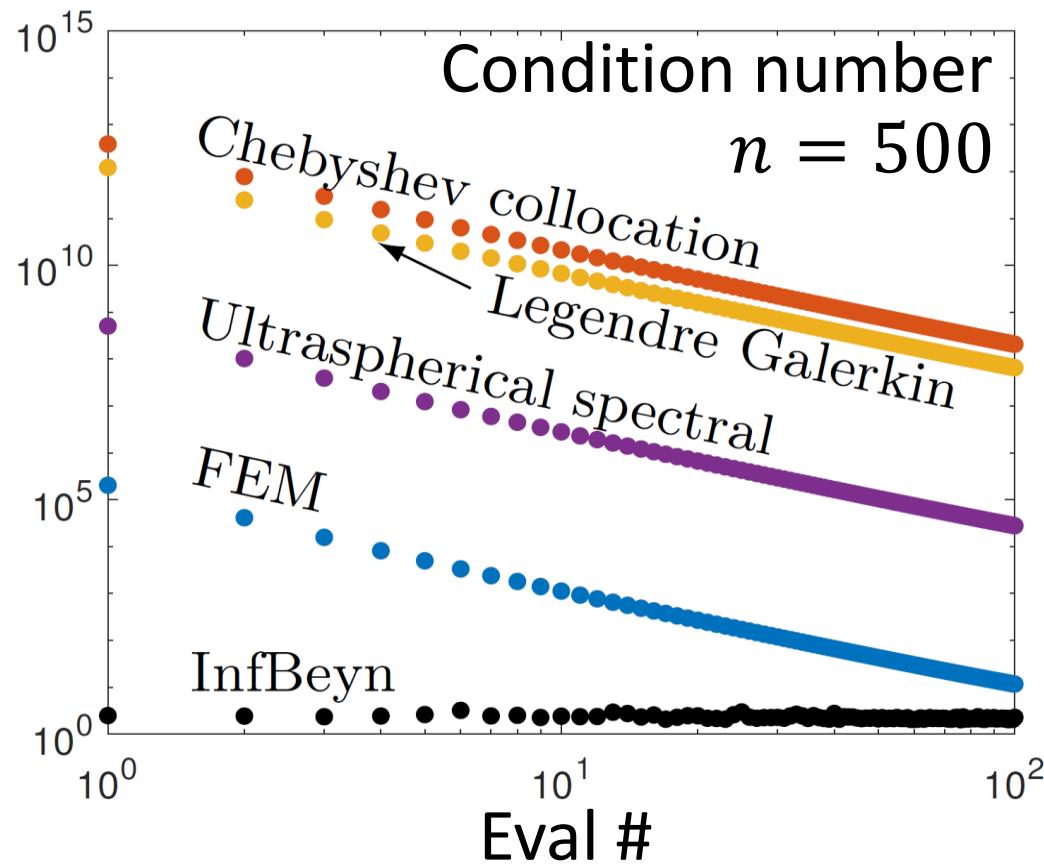


Example 3: Loaded string

damped_beam from NLEVP collection.

$$-\frac{d^2u}{dx^2} = \lambda u, \quad u(0) = 0,$$

$$u'(1) + \frac{\lambda}{\lambda - 1} u(1) = 0.$$



Example 4: Planar waveguide

planar_waveguide from NLEVP collection.

$$\frac{d^2\phi}{dx^2} + k^2(\eta^2 - \mu(\lambda))\phi = 0$$

$$\mu(\lambda) = \frac{\delta_+}{k^2} + \frac{\delta_-}{8k^2\lambda^2} + \frac{\lambda^2}{k^2}$$

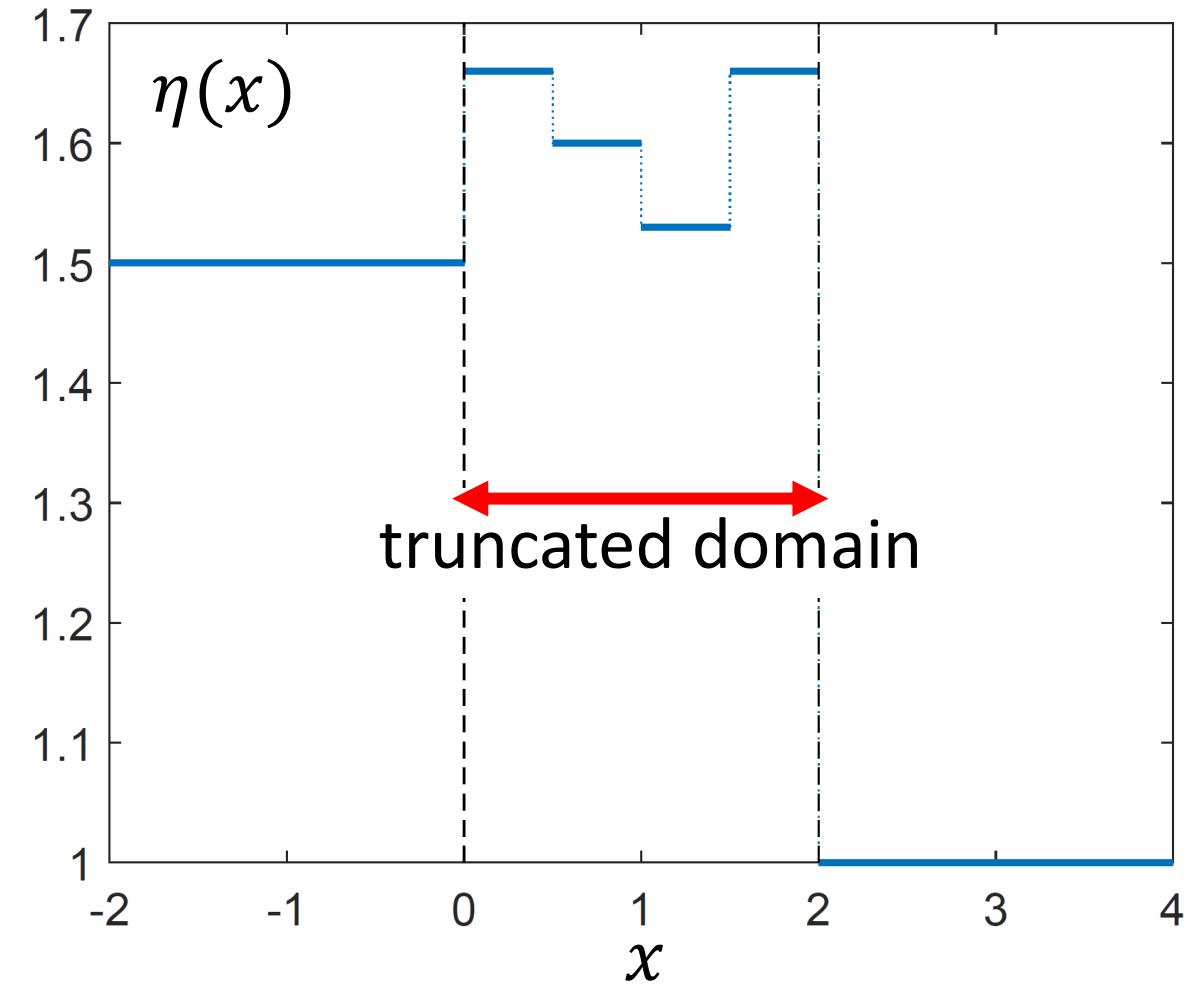
$$\frac{d\phi}{dx}(0) + \left(\frac{\delta_-}{2\lambda} - \lambda\right)\phi(0) = 0$$

$$\frac{d\phi}{dx}(2) + \left(\frac{\delta_-}{2\lambda} + \lambda\right)\phi(2) = 0$$

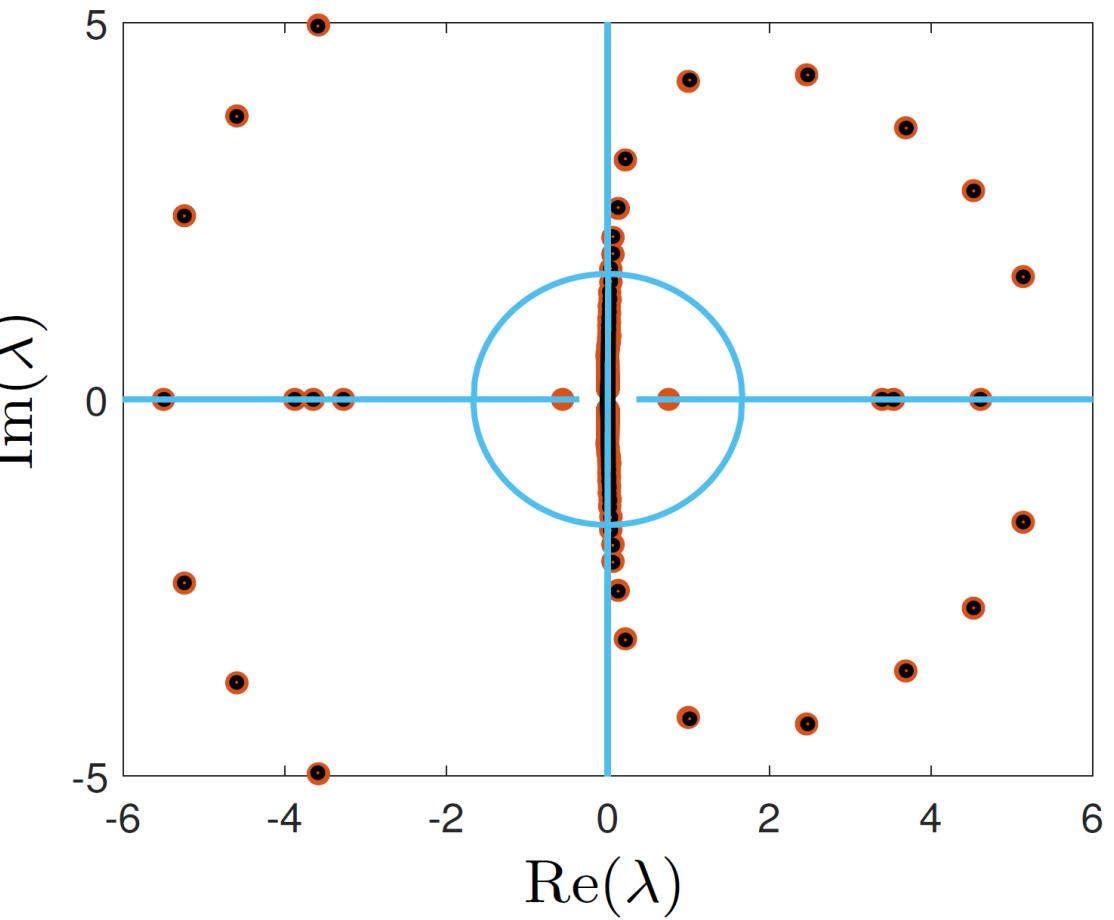
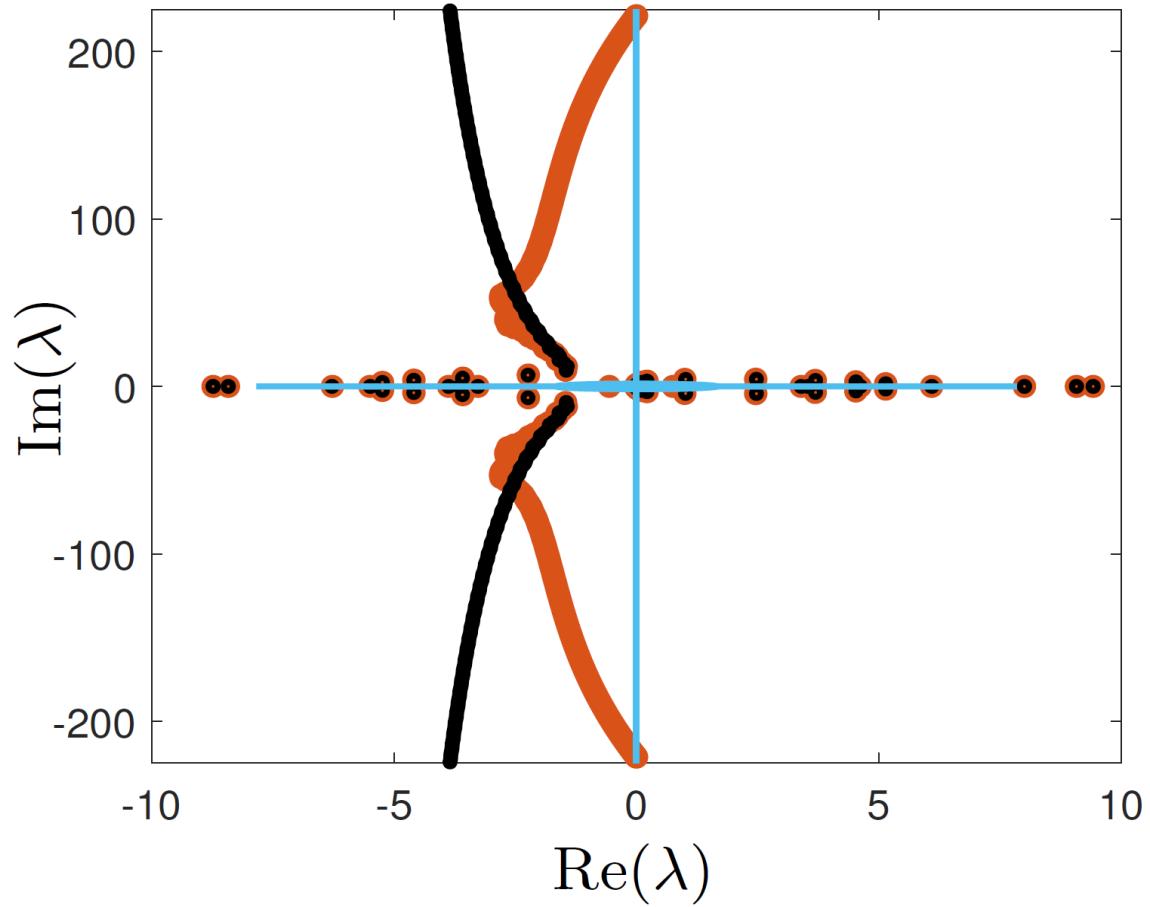
η corresponds to refractive index.

λ correspond to guided and leaky modes.

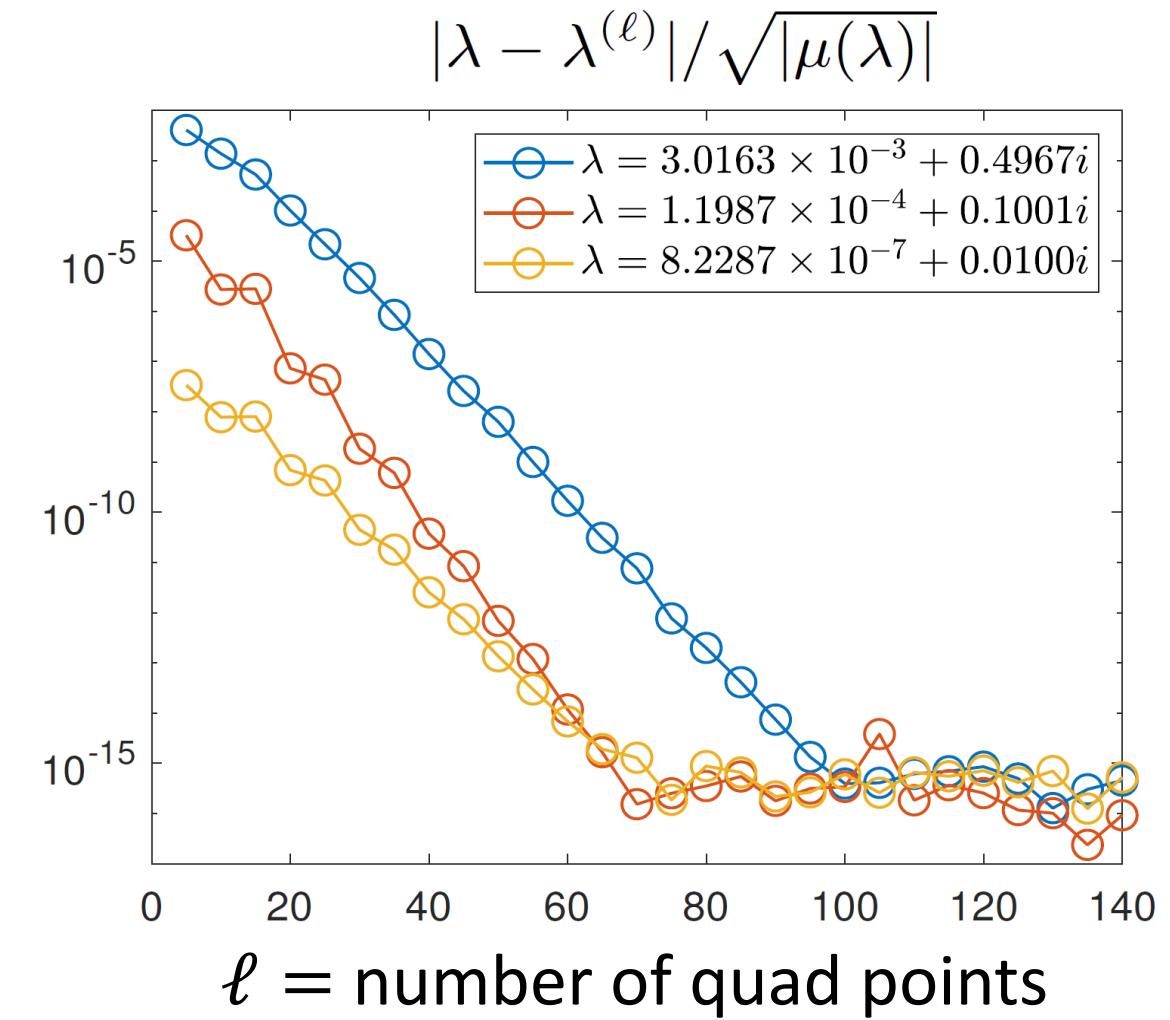
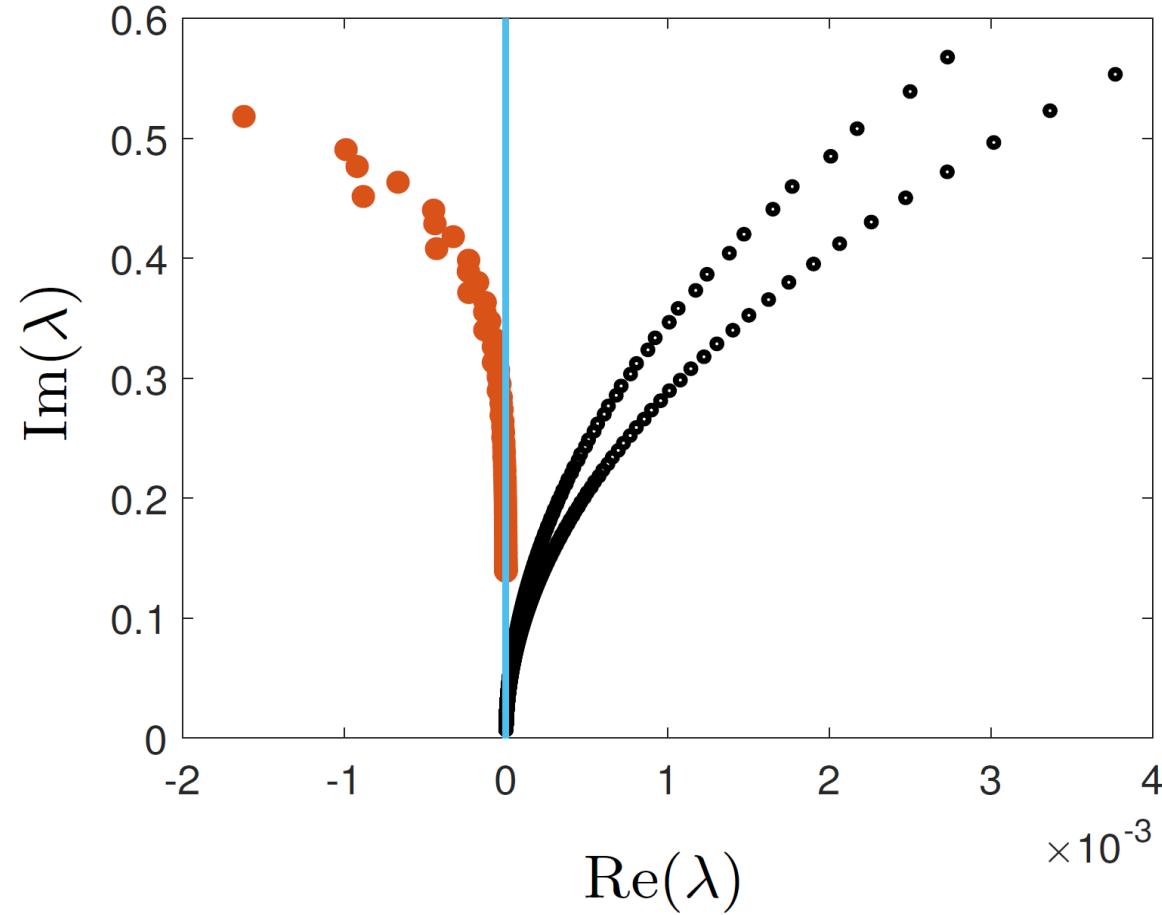
Discretized using FEM ($n = 129$, default)



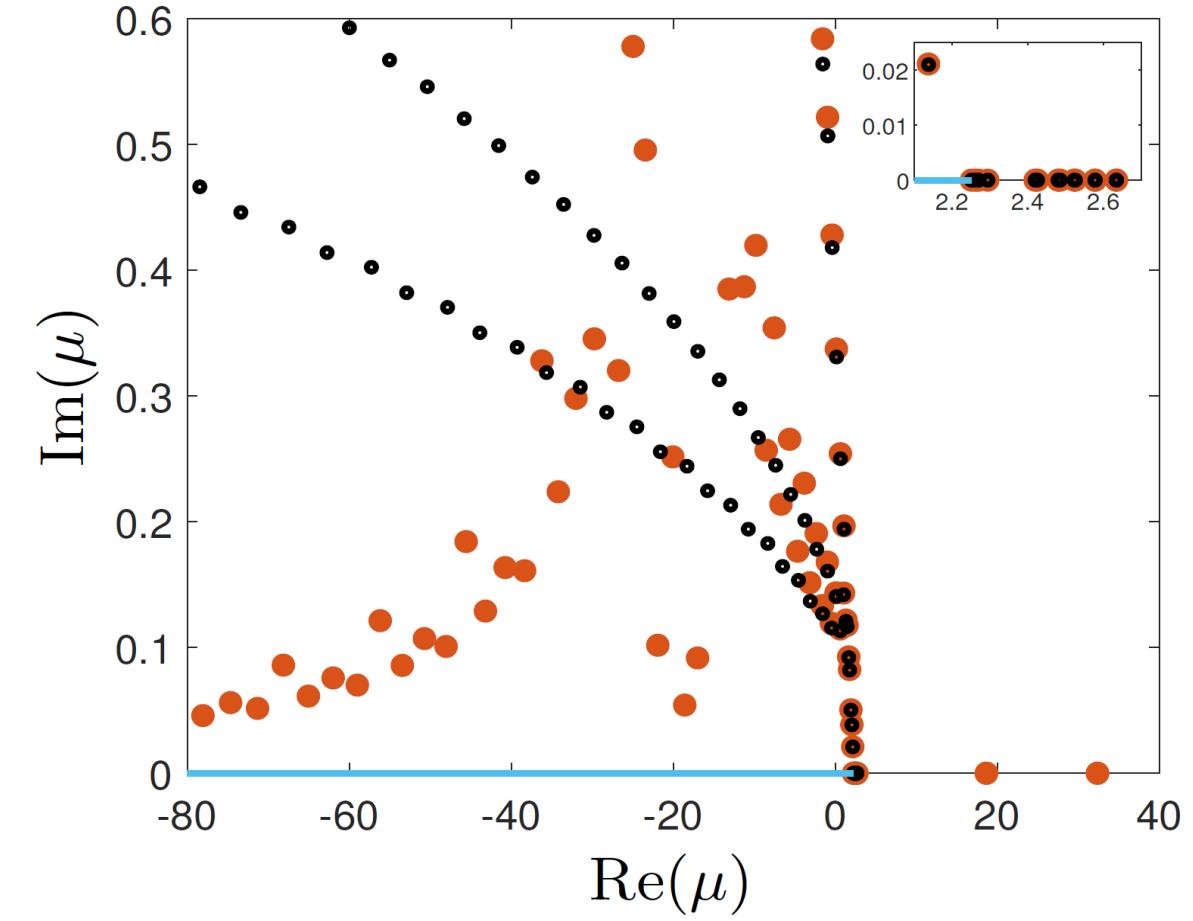
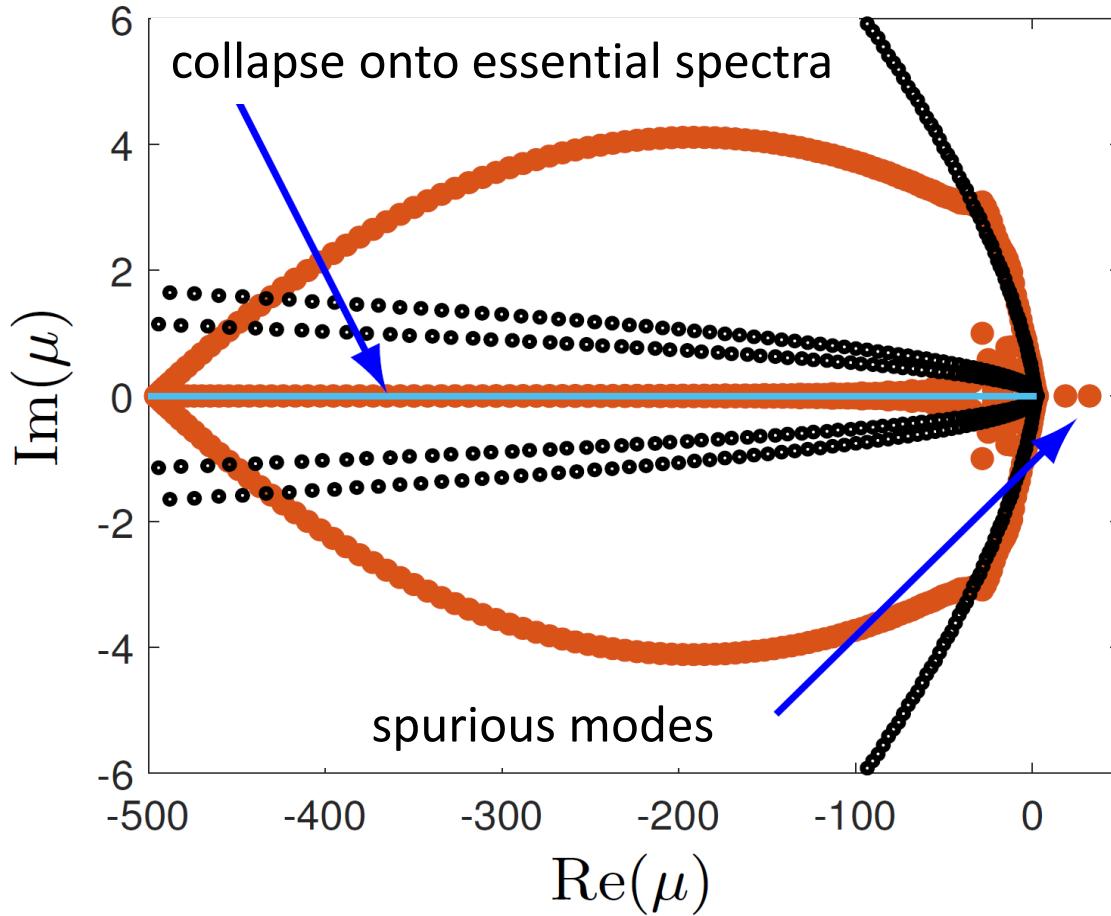
Example 4: Planar waveguide



Example 4: Planar waveguide



Example 4: Planar waveguide



Bigger picture

- **Foundations:** Classify difficulty of computational problems.
 - Prove that algorithms are optimal (in any given computational model).
 - Find assumptions and methods for computational goals.
- A new suite of “infinite-dimensional” algorithms. **Solve-then-discretize.**
 - **Methods built on** $\sigma_{\inf}(T)$, e.g., compute $\sigma_{\inf}(T\mathcal{P}_n^*)$ or $\sqrt{\sigma_{\inf}(\mathcal{P}_n T^* T \mathcal{P}_n^*)}$
 - Spectra with error control (including essential spectrum).
 - Pseudospectra, stability bounds etc.
 - More exotic features such as fractal dimensions.
 - **Methods built on adaptively computing** $(A - zI)^{-1}$ or $T(z)^{-1}$
 - Contour methods: discrete spectra for linear and nonlinear pencils.
 - Convolution methods: spectral measures of self-adjoint and unitary operators.
 - Functions of operators with error control.

Summary for NEPs

- Discretization can cause serious issues.
- **InfBeyn** overcomes these in regions of discrete spectra: **convergent, stable, efficient**.
- Compute pseudospectra (of generic pencils) with explicit **error control**



Example	Observed discretization woes
acoustic_wave_1d	spurious eigenvalues slow convergence
acoustic_wave_2d	spurious eigenvalues wrong multiplicity
butterfly	spectral pollution missed spectra wrong pseudospectra
damped_beam	slow convergence resolved eigenfunctions with inaccurate eigenvalues
loaded_string	ill-conditioning from discretization
planar_waveguide	collapse onto ghost essential spectrum failure for accumulating eigenvalues spectral pollution

More on this program: www.damtp.cam.ac.uk/user/mjc249/home.html

Code: <https://github.com/MColbrook/infNEP>

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