

On the Solvability Complexity Index hierarchy, the
computational spectral problem and computer assisted
proofs

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Outline

- Introduction
- Spectral Problems: Infinite Matrices
- Spectral Problems: Schrödinger Operators
- Numerical Examples
- Connections with Logic/Set Theory?
- Computer Assisted Proofs

Motivation

- Motivating example: spectra of infinite-dimensional operators. Many applications but W. Arveson (leading operator theorist U.C. Berkeley) pointed out in the early nineties, **“Unfortunately, there is a dearth of literature on this basic problem, and so far as we have been able to tell, there are no proven techniques.”** Situation was worse for the Schrödinger case!

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- Applications: can we present rigorous computations for the maths/science community and for computer assisted proofs?

Solvability Complexity Index (SCI) [1, Hansen, JAMS]

Ω is some set, called the *primary* set,

Λ is a set of complex valued functions on Ω , called the *evaluation* set,

\mathcal{M} is a metric space, where the thing we compute lives

Ξ is a mapping $\Omega \rightarrow \mathcal{M}$, called the *problem* function.

E.g. $\Omega = \mathcal{B}(\mathcal{H})$, problem function Ξ maps $A \mapsto \text{Sp}(A)$, (\mathcal{M}, d) set of all compact subsets of \mathbb{C} with Hausdorff metric and evaluation functions in Λ consist of $f_{i,j} : A \mapsto \langle Ae_j, e_i \rangle$, $i, j \in \mathbb{N}$, which provide the entries of the matrix representation of A w.r.t. an orthonormal basis $\{e_i\}_{i \in \mathbb{N}}$.

Definition 1 (General Algorithm)

Given a computational problem $\{\Xi, \Omega, \mathcal{M}, \Lambda\}$, a *general algorithm* is a mapping $\Gamma : \Omega \rightarrow \mathcal{M}$ such that for each $A \in \Omega$:

- (i) there exists a finite subset of evaluations $\Lambda_\Gamma(A) \subset \Lambda$,
- (ii) the action of Γ on A only depends on $\{A_f\}_{f \in \Lambda_\Gamma(A)}$ where $A_f := f(A)$,
- (iii) for every $B \in \Omega$ such that $B_f = A_f$ for every $f \in \Lambda_\Gamma(A)$, it holds that $\Lambda_\Gamma(B) = \Lambda_\Gamma(A)$.

No restrictions on the operations allowed (can consult any fixed oracle etc.). But can consider different types of towers. E.g. type-2 Turing machines, allow radicals, BSS model, ...

Definition 2 (Tower of algorithms)

Given $\{\Xi, \Omega, \mathcal{M}, \Lambda\}$, a *tower of algorithms of height k* for $\{\Xi, \Omega, \mathcal{M}, \Lambda\}$ is a collection of sequences of functions

$$\Gamma_{n_k} : \Omega \rightarrow \mathcal{M}, \quad \Gamma_{n_k, n_{k-1}} : \Omega \rightarrow \mathcal{M}, \dots, \Gamma_{n_k, \dots, n_1} : \Omega \rightarrow \mathcal{M},$$

where $n_k, \dots, n_1 \in \mathbb{N}$ and the functions Γ_{n_k, \dots, n_1} are general algorithms. Moreover, for every $A \in \Omega$,

$$\lim_{n_k \rightarrow \infty} \dots \lim_{n_1 \rightarrow \infty} \Gamma_{n_k, \dots, n_1}(A) = \Xi(A)$$

with convergence in metric space \mathcal{M} .

Definition 3 (Solvability Complexity Index)

$\{\Xi, \Omega, \mathcal{M}, \Lambda\}$ is said to have $\text{SCI}(\Xi, \Omega, \mathcal{M}, \Lambda)_\alpha = k$ with respect to a tower of algorithms of type α if k is the smallest integer for which there exists a tower of algorithms of type α of height k .

If no such tower exists then $\text{SCI}(\Xi, \Omega, \mathcal{M}, \Lambda)_\alpha = \infty$.

If there exists a tower $\{\Gamma_n\}_{n \in \mathbb{N}}$ of type α and height one such that $\Xi = \Gamma_{n_1}$ for some finite n_1 , then we define $\text{SCI}(\Xi, \Omega, \mathcal{M}, \Lambda)_\alpha = 0$.

Definition 4 (The Solvability Complexity Index Hierarchy)

Consider a collection \mathcal{C} of computational problems and let \mathcal{T} be the collection of all towers of algorithms of type α for the computational problems in \mathcal{C} . Define

$$\begin{aligned}\Delta_0^\alpha &:= \{\{\Xi, \Omega\} \in \mathcal{C} \mid \text{SCI}(\Xi, \Omega)_\alpha = 0\} \\ \Delta_{m+1}^\alpha &:= \{\{\Xi, \Omega\} \in \mathcal{C} \mid \text{SCI}(\Xi, \Omega)_\alpha \leq m\}, \quad m \in \mathbb{N},\end{aligned}$$

as well as

$$\Delta_1^\alpha := \{\{\Xi, \Omega\} \in \mathcal{C} \mid \exists \{\Gamma_n\}_{n \in \mathbb{N}} \in \mathcal{T} \text{ s.t. } \forall A \, d(\Gamma_n(A), \Xi(A)) \leq 2^{-n}\}.$$

Definition 5 (The SCI Hierarchy (totally ordered set))

Suppose \mathcal{M} is totally ordered. Define

$$\Sigma_0^\alpha = \Pi_0^\alpha = \Delta_0^\alpha,$$

$$\Sigma_1^\alpha = \{\{\Xi, \Omega\} \in \Delta_2 \mid \exists \Gamma_n \in \mathcal{T} \text{ s.t. } \Gamma_n(A) \nearrow \Xi(A) \ \forall A \in \Omega\},$$

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where \nearrow and \searrow denotes convergence from below and above respectively, as well as, for $m \in \mathbb{N}$,

$$\Sigma_{m+1}^\alpha = \{\{\Xi, \Omega\} \in \Delta_{m+2} \mid \exists \Gamma_{n_{m+1}, \dots, n_1} \in \mathcal{T} \text{ s.t. } \Gamma_{n_{m+1}}(A) \nearrow \Xi(A) \ \forall A \in \Omega\},$$

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Definition 6 (The SCI Hierarchy (Attouch-Wetts/Hausdorff metric))

Suppose \mathcal{M} is a metric space with the Attouch-Wetts or the Hausdorff metric induced by another metric space \mathcal{M}' . Define for $m \in \mathbb{N}$

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$$\Sigma_1^\alpha = \{\{\Xi, \Omega\} \in \Delta_2 \mid \exists \Gamma_n \in \mathcal{T} \text{ s.t. } \Gamma_n(A) \underset{\mathcal{M}'}{\subset} B_{2^{-n}}^{\mathcal{M}}(\Xi(A)) \quad \forall A \in \Omega\},$$

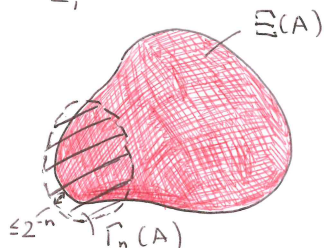
$$\Pi_1^\alpha = \{\{\Xi, \Omega\} \in \Delta_2 \mid \exists \Gamma_n \in \mathcal{T} \text{ s.t. } B_{2^{-n}}^{\mathcal{M}}(\Gamma_n(A)) \underset{\mathcal{M}'}{\supset} \Xi(A) \quad \forall A \in \Omega\}.$$

where $\underset{\mathcal{M}'}{\subset}$ means inclusion in the metric space \mathcal{M}' . Interpret $B_{2^{-n}}^{\mathcal{M}}(x)$ as the subset of \mathcal{M}' given by $\bigcup\{S \subset \mathcal{M}' \mid S \in \mathcal{M}, d_{\mathcal{M}}(S, x) \leq 2^{-n}\}$. Moreover,

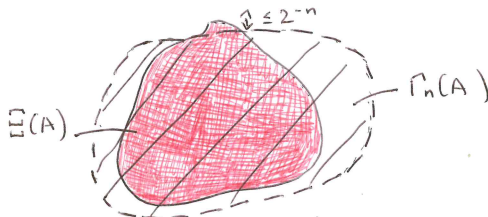
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What does this mean?

 $\Sigma_1 :$


Reliable but may not have everything yet.

 $\Pi_1 :$


Nearly have everything but may have too much!

Why do we care?

- Lower bounds for *general* algorithms provide lower bounds for any reasonable model of computation. But all constructed algorithms can be realised as type-2 Turing machines. Hence results are sharp in this sense - difficulty lies with infinite amount of data/information, not the model of computation.

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- Hence, the field of computational spectral theory is mostly concerned with non-computable problems. Numerical analysts could not solve the spectral problem because they couldn't see the connection with logic.
- Error control for scientific problems - computer assisted proofs?

Computing Spectra with Error Control

- Hilbert space $l^2(\mathbb{N})$ with $\|x\|_2 = \sqrt{\sum_{j=1}^{\infty} |x_j|^2}$, $\langle x, y \rangle = \sum_{j=1}^{\infty} x_j \bar{y}_j$
- Bounded linear operator $A : l^2(\mathbb{N}) \rightarrow l^2(\mathbb{N})$ realised as matrix

$$\begin{pmatrix} a_{11} & a_{12} & a_{13} & \dots \\ a_{21} & a_{22} & a_{23} & \dots \\ a_{31} & a_{32} & a_{33} & \dots \\ \vdots & \vdots & \vdots & \ddots \end{pmatrix}$$

- Want to compute spectrum (generalisation of eigenvalues)

$$\mathrm{Sp}(A) := \{z \in \mathbb{C} : A - zI \text{ not invertible}\}.$$

from the matrix elements.

- Also the pseudospectrum

$$\mathrm{Sp}_{\epsilon}(A) := \{z \in \mathbb{C} : \|(A - zI)^{-1}\|^{-1} \leq \epsilon\}.$$

Two Key Definitions

Definition 7 (Dispersion - off-diagonal decay)

We say that the dispersion of $A \in \mathcal{B}(l^2(\mathbb{N}))$ is bounded by the function $f : \mathbb{N} \rightarrow \mathbb{N}$ if

$$D_{f,m}(A) := \max\{\|(I - P_{f(m)})AP_m\|, \|P_m A(I - P_{f(m)})\|\} \rightarrow 0 \quad \text{as } m \rightarrow \infty.$$

Definition 8 (Controlled growth of the resolvent - well-conditioned)

Let $g : [0, \infty) \rightarrow [0, \infty)$ be a continuous function, vanishing only at $x = 0$ and tending to infinity as $x \rightarrow \infty$ with $g(x) \leq x$. We say that a closed operator A with non-empty spectrum on the Hilbert space \mathcal{H} has controlled growth of the resolvent by g if

$$\|(A - zI)^{-1}\|^{-1} \geq g(\text{dist}(z, \text{Sp}(A))) \quad \forall z \in \mathbb{C},$$

where we use the convention $\|B^{-1}\|^{-1} := 0$ if B has no bounded inverse.

What does this mean?

- Dispersion - think banded matrices.
- Controlled resolvent - g is a measure of the conditioning of the problem of computing $\text{Sp}(A)$ through the formula

$$\text{Sp}_\epsilon(A) = \bigcup_{\|B\| \leq \epsilon} \text{Sp}(A + B).$$

- Self-adjoint and normal operators (A commutes with A^*) have well conditioned spectral problems since

$$\|(A - zI)^{-1}\|^{-1} = \text{dist}(z, \text{Sp}(A)), \quad g(x) = x.$$

- Different classes have different classifications in hierarchy...

Example 1: We have both f and g . [2, C. et al.]

- By considering diagonal operators, clear the problem does not lie in Δ_1^G - algorithms can only read a finite amount of information. Hence we wish to show lies in Σ_1^A .

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- Introduce smallest singular value σ_1 (injection modulus) and

$$\begin{aligned}\gamma(z, A) &= \min\{\sigma_1(A - zI), \sigma_1(A^* - \bar{z}I)\} = \|(A - zI)^{-1}\|^{-1}, \\ \gamma_n(z, A) &= \min\{\sigma_1((A - zI)P_n), \sigma_1((A^* - \bar{z}I)P_n)\}.\end{aligned}$$

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- Can prove $\gamma_n \downarrow \gamma$ uniformly on compacts.

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- Given f, g and $D_{f,n}(A)$, we can gain an upper bound to $\text{dist}(z, \text{Sp}(A))$ that converges locally uniformly to the true distance. Can use this to build Σ_1^A algorithm.

Example 2: When we have only g , e.g. self-adjoint case.

- How to build Σ_2^A algorithm? Define

$$\gamma_{n_2, n_1}(z, A) = \min\{\sigma_1(P_{n_1}(A - zI)P_{n_2}), \sigma_1(P_{n_1}(A^* - \bar{z}I)P_{n_2})\}.$$

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- Assume for a contradiction that there is a sequence $\{\Gamma_k\}$ of general algorithms such that $\Gamma_k(A) \rightarrow \text{Sp}(A)$ for all $A \in \Omega_{\text{SA}}$, and consider operators of the type

$$A := \bigoplus_{r=1}^{\infty} A_{I_r} \text{ with } \{I_r\} \subset \mathbb{N} \text{ and } A_n := \begin{pmatrix} 1 & & & 1 \\ & 0 & & \\ & & \ddots & \\ & & & 0 \\ 1 & & & 1 \end{pmatrix} \in \mathbb{C}^{n \times n}.$$

Simple oscillation argument...

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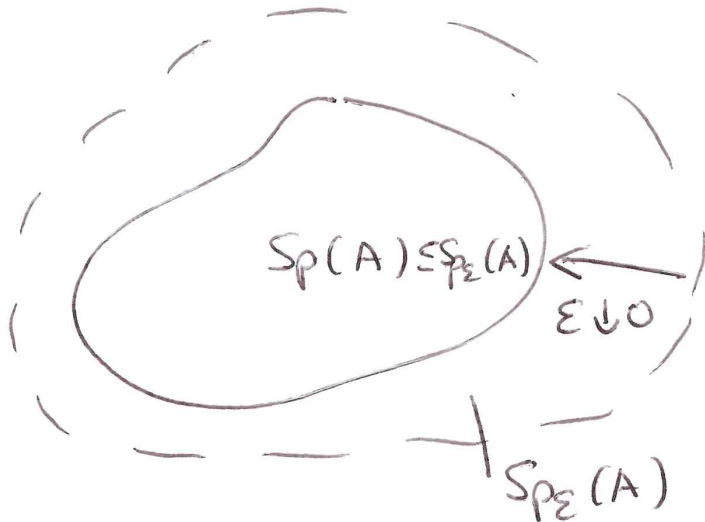
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- Without function g (which links Sp and Sp_ϵ), can compute $\mathrm{Sp}_\epsilon(A)$ in two limits. Let $\epsilon = 1/n_3$ then last limit gives convergence from above so Π_3^A .



Further Results [3]

We have classifications for classes

- Different classes of compact operators
- Normal/self-adjoint/controlled resolvent (g)
- Bounded dispersion
- Diagonal
- General bounded
- Even unbounded
- ...

For problems

- Spectrum
- Pseudospectrum
- Essential Spectrum
- Decision problem: is $z \in \text{Sp}(A)$?
- ...

Schrödinger Operators [3]

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- Unsolved for a long time when considering H acting on $L^2(\mathbb{R}^d)$ allowing non self-adjointness and arbitrary complex potentials.
- Consider the computational problem $\{\Xi, \Omega, \mathcal{M}, \Lambda\}$ with the *Attouch-Wets* metric defined by

$$d_{\text{AW}}(A, B) = \sum_{i=1}^{\infty} 2^{-i} \min \left\{ 1, \sup_{|x| < i} |d(x, A) - d(x, B)| \right\},$$

where A and B are closed subsets of \mathbb{C} - generalises Hausdorff distance to general closed sets.

Example: $V \in \text{BV}_\phi(\mathbb{R}^d)$, $\|V\|_\infty \leq M$

- Assume potential in $\text{BV}_\phi(\mathbb{R}^d) = \{f : \text{TV}(f|_{[-a,a]^d}) \leq \phi(a)\}$. For simplicity, assume V real-valued.

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- Aim: Construct a Σ_1^A tower. Easy to show sharp.
- Method: Choose a suitable basis and compute estimations of matrix of operator. Then can use above method (adapted to unbounded closed operators).
- How: Use $V \in \text{BV}_\phi(\mathbb{R}^d)$, $\|V\|_\infty \leq M$ to bound error in integrals from theory of numerical integration.

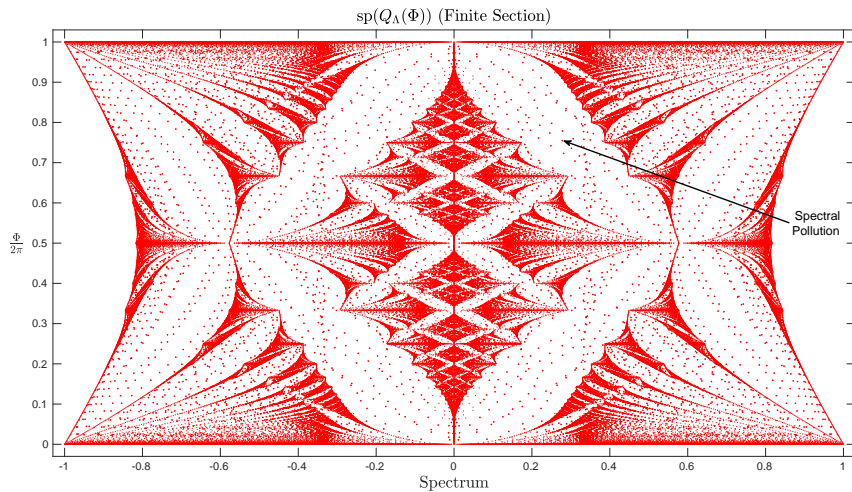
Generalisations

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- Can build an algorithm for sectorial unbounded potentials with blow up at ∞ . Different method - more standard discretisation. Problem lies in Δ_2^A but not $\Sigma_1^G \cup \Pi_1^G$ - same classification as compact operators (realised as infinite matrices).

Graphene



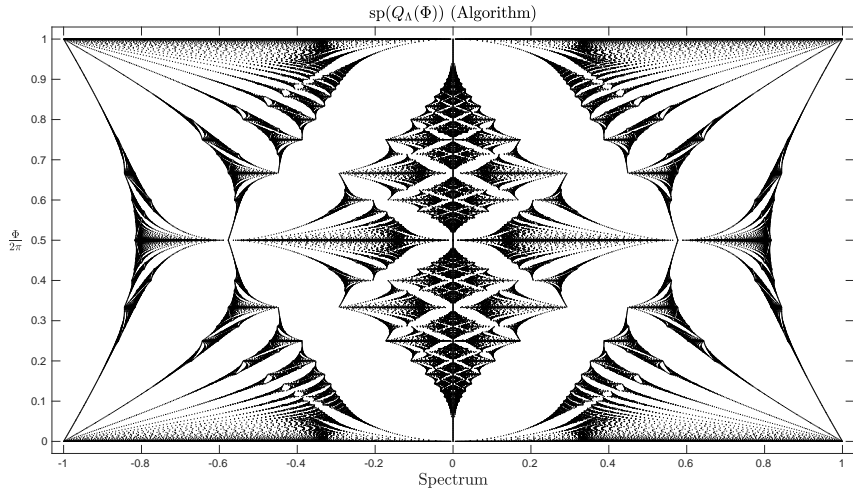
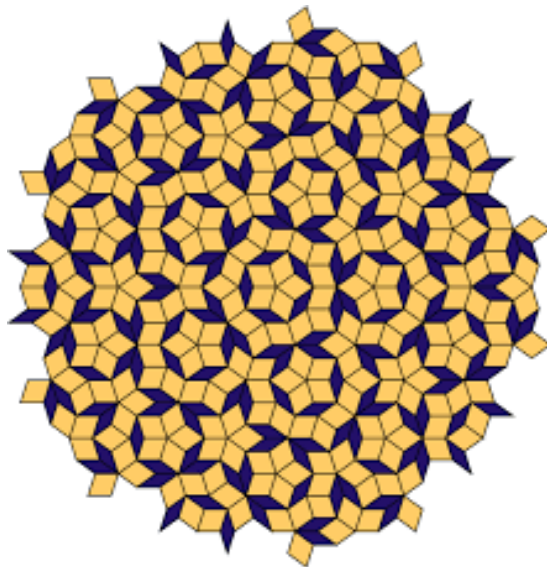
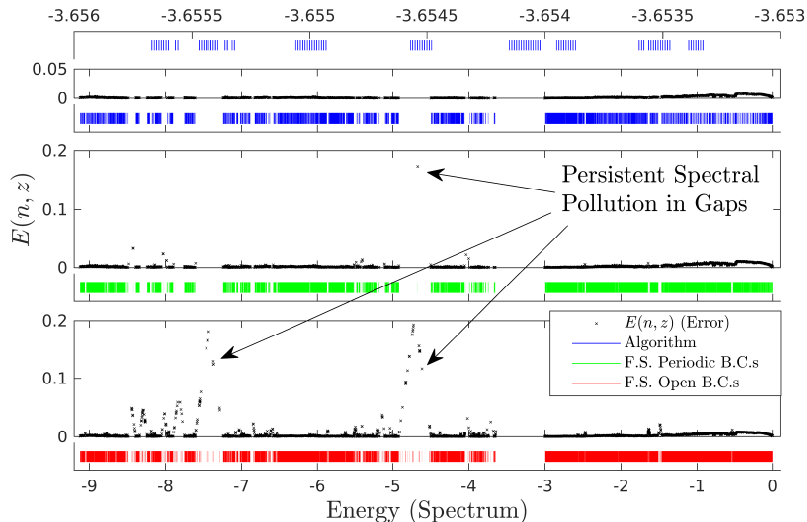


Figure: Guaranteed error bound of 10^{-5} .

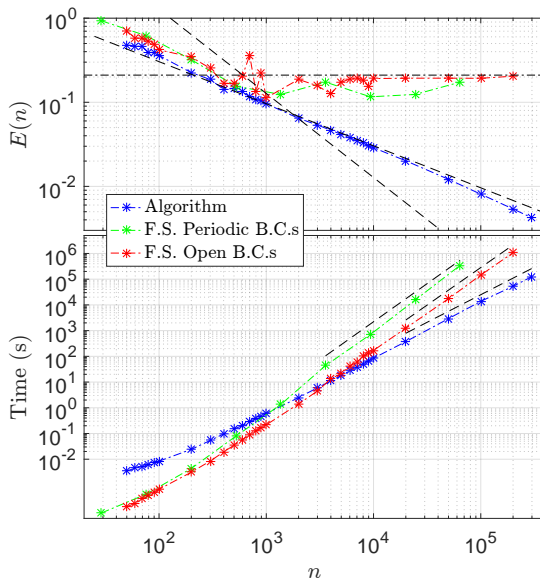
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- However, due to its generality, some of the hierarchies in logic become special cases of the SCI hierarchy.

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- However, due to its generality, some of the hierarchies in logic become special cases of the SCI hierarchy.
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- However, due to its generality, some of the hierarchies in logic become special cases of the SCI hierarchy.
- As a mathematician with no background in logic, I would be very interested in people's opinions on this and making connections across communities...
- In general, is there a connection with Weihrauch computability? Often it is easier to prove upper bounds without encoding \mathcal{M} but tools developed in this community may be useful for lower bounds. (Again comments and discussion at the end most welcome.)

Very easy example: Arithmetical Hierarchy

Given a subset $A \subset \mathbb{Z}_+$ with characteristic function χ_A definable in First-Order Arithmetic, what is SCI of deciding whether a given number $x \in \mathbb{Z}_+$ belongs to A ?

- primary set $\Omega := \mathbb{Z}_+$,
- evaluation set $\Lambda = \{\lambda\}$ consisting of the function $\lambda : \mathbb{Z}_+ \rightarrow \mathbb{C}, x \mapsto x$,
- metric space $\mathcal{M} := (\{1, 0\}, d_{discr})$.

Definition 9 (Kleene-Shoenfield tower)

A tower of algorithms given by a family

$\{\Gamma_{n_k, \dots, n_1} : \Omega \rightarrow \mathcal{M} : n_k, \dots, n_1 \in \mathbb{N}\}$ of functions at the lowest level is said to be a *Kleene-Shoenfield tower*, if the function

$$\mathbb{N}^k \times \Omega \rightarrow \mathcal{M}, \quad (n_k, \dots, n_1, x) \mapsto \Gamma_{n_k, \dots, n_1}(x)$$

is computable.

Theorem 10 (The SCI hierarchy encompasses the arithmetical hierarchy)

For every $m \in \mathbb{N}$ we have

$$\Xi \in \Delta_m \Leftrightarrow \{\Xi, \Omega\} \in \Delta_m^{\text{KS}},$$

$$\Xi \in \Sigma_m \Leftrightarrow \{\Xi, \Omega\} \in \Sigma_m^{\text{KS}},$$

$$\Xi \in \Pi_m \Leftrightarrow \{\Xi, \Omega\} \in \Pi_m^{\text{KS}}.$$

A more interesting result...

Consider $f : \mathbb{R}^* \rightarrow \mathbb{R}^*$. A k -tower for f is $F : \mathbb{N}^k \times \mathbb{R}^* \rightarrow \mathbb{R}^*$ with

$$f(x_1, \dots, x_m) = \lim_{n_k \rightarrow \infty} \dots \lim_{n_1 \rightarrow \infty} F(n_k, \dots, n_1, x_1, \dots, x_m).$$

E. Neumann and A. Pauly recently showed

Theorem 11 ([4])

If $\max\{\text{SCI}_{TTE}(f), \text{SCI}_{BSS}(f)\} \geq 2$ then $\text{SCI}_{TTE}(f) = \text{SCI}_{BSS}(f)$.

Since $\text{SCI}_{TTE}(f) \leq n$ iff $f \leq_w \lim^{(n)}$ we obtain that for $n \geq 2$

$$\text{SCI}_{BSS}(f) \geq n \text{ iff } f \not\leq_w \lim^{(n-1)}.$$

So there is some connection with Weihrauch reducibility (for this type of problem function) and a sense of unification for very non-computable problems...

Computer Assisted Proofs

- Recent computer assisted proof of the long lasting Kepler conjecture (Hilbert's 18th problem) is a great example of the use of numerical calculations in a proof [5].

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Computer Assisted Proofs

- Recent computer assisted proof of the long lasting Kepler conjecture (Hilbert's 18th problem) is a great example of the use of numerical calculations in a proof [5].
- The proof relies on deciding more than 50,000 decision problems in numerical optimisation that are not in Δ_1^G . In particular, the proof hinges on computing undecidable problems.
- Just as most spectral problems of interest are not in Δ_1^G , there are many other crucial problems not in Δ_1^G that may be useful in computer assisted proofs. The key to computer assisted proofs are the classes Σ_1^A and Π_1^A .



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Thank you!

