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The Computational Spectral Problem and a New Classification Theory Novel Algorithms, Impossibility Results and Computer Assisted Proofs

Matthew Colbrook University of Cambridge



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Motivat	ion				

 Motivating example: spectra of infinite-dimensional operators, vast number of applications. W. Arveson (leading operator theorist U.C. Berkeley) in 90s: "Unfortunately, there is a dearth of literature on this basic problem, and ... there are no proven techniques." Situation even worse for the Schrödinger case:

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- Given a Schrödinger operator

$$H = -\Delta + V, \qquad V : \mathbb{R}^d \to \mathbb{C},$$

Can we compute the spectrum from point samples of the potential V(x) (or similar appropriate data)? Very important open problem both in continuous and discrete cases.

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• Naive discretisations can fail spectacularly even when V real valued.

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Can we compute the spectrum from point samples of the potential V(x) (or similar appropriate data)? Very important open problem both in continuous and discrete cases.

- Naive discretisations can fail spectacularly even when V real valued.
- Talk will present solution to this problem and how to compute spectra for much more general cases.

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Computational Schrödinger Problem

Problem of algorithmically computing Sp(H) goes at least as far back as Schrödinger himself [1].

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Computational Schrödinger Problem

Problem of algorithmically computing Sp(H) goes at least as far back as Schrödinger himself [1].

Studied by great scientists and mathematicians throughout 20th and 21st centuries. **Very** incomplete list - P.W. Anderson [2], J. Schwinger [3], A. Weyl [4], T. Digernes, V.S. Varadarajan and S.R.S. Varadhan [5], A. Böttcher [6, 7], P.A. Deift, L.C. Li and C. Tomei [8], C. Fefferman and L. Seco

[9, 10, 11, 12, 13, 14, 15, 16, 17], P. Hertel, E. Lieb and W.

Thirring [18], L. Demanet and W. Schlag [19], M. Zworski [20, 21].

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A curio	us case of lim	its			

Problem: Given an infinite matrix (acting as a bounded operator on $l^2(\mathbb{N})$)

$$A = \begin{pmatrix} a_{11} & a_{12} & a_{13} & \dots \\ a_{21} & a_{22} & a_{23} & \dots \\ a_{31} & a_{32} & a_{33} & \dots \\ \vdots & \vdots & \vdots & \ddots \end{pmatrix}$$

can we compute the spectrum Sp(A) from the matrix elements in Hausdorff metric?

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can we compute the spectrum Sp(A) from the matrix elements in Hausdorff metric?

Answer [22]: No! Best one can do is compute using three successive limits:

$$\lim_{n_3\to\infty}\lim_{n_2\to\infty}\lim_{n_1\to\infty}\Gamma_{n_3,n_2,n_1}(A)=\operatorname{Sp}(A)$$

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400 year old problem



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Flyspeck program (T. Hales) - fully computer assisted verification via 50000 linear programs with irrational inputs.

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Flyspeck program (T. Hales) - fully computer assisted verification via 50000 linear programs with irrational inputs. Computational problem: decide whether there is an $x \in \mathbb{R}^N$ such that

(1)
$$\langle x, c \rangle_K \leq M$$
 subject to $Ax = y, x \geq 0,$

where

$$\langle x, c \rangle_{\kappa} = \lfloor 10^{\kappa} \langle x, c \rangle \rfloor 10^{-\kappa}, \quad \kappa \in \mathbb{N}, \quad M \in \mathbb{Q}.$$

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Irrational input numbers means that A and y are only known approximately, however, to any precision one wants.

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Irrational input numbers means that A and y are only known approximately, however, to any precision one wants. Not computable. But if replace $\langle x, c \rangle_K \leq M$ by $\langle x, c \rangle_K < M$ then problem is verifiable. If there had been cases with equality, the Flyspeck program may never have resolved Kepler's conjecture!

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The SCI bierarchy					

SCI=number of limits needed to solve problem.

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The SCI hierarchy					

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The SCI hierarchy					

SCI=number of limits needed to solve problem. Work in model of computation α BUT remarkably all results presented today are independent of power of model - NOT a talk about recursivity.

(i) Δ_0^α is the set of problems that can be computed in finite time, the SCI = 0.

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- (i) Δ_0^α is the set of problems that can be computed in finite time, the SCI = 0.
- (ii) Δ_1^{α} is the set of problems that can be computed using one limit, the SCI = 1, however one has error control and one knows an error bound that tends to zero as the algorithm progresses.

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- (iii) Δ_2^{α} is the set of problems that can be computed using one limit, the SCI = 1, but error control may not be possible.
- (iv) Δ_{m+1}^{α} , for $m \in \mathbb{N}$, is the set of problems that can be computed by using *m* limits, the SCI $\leq m$.

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More Structure (Monotone)

How do we capture 'verifiable' problems that can be used in computer assisted proofs and rigorous numerics?

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The SCI hierarchy

More Structure (Monotone)

How do we capture 'verifiable' problems that can be used in computer assisted proofs and rigorous numerics? Easy if computational problem (thing we want to compute) maps to a totally ordered metric space (e.g. \mathbb{R}).

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More Structure (Monotone)

How do we capture 'verifiable' problems that can be used in computer assisted proofs and rigorous numerics? Easy if computational problem (thing we want to compute) maps to a totally ordered metric space (e.g. \mathbb{R}). Σ_m - problems requiring *m* limits but final limit from below.

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 Σ_m - problems requiring *m* limits but final limit from below.

 Π_m - problems requiring *m* limits but final limit from above. One side version of error control.

What about other spaces such as Hausdorff metric?

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Figure: Meaning of Σ_1 and Π_1 convergence for problem function Ξ . The red area represents $\Xi(A)$ whereas the green areas represent the output of the algorithm $\Gamma_n(A)$. Σ_1 convergence means convergence as $n \to \infty$ but each output point in $\Gamma_n(A)$ is at most distance 2^{-n} from $\Xi(A)$. Similarly for Π_1 , we have convergence as $n \to \infty$ but any point in $\Xi(A)$ is at most distance 2^{-n} from $\Gamma_n(A)$.

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• Lower bounds mean we no longer waste time looking for an algorithm that doesn't exist. Turns out that many everyday problems in numerical analysis are not computable.

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- Lower bounds mean we no longer waste time looking for an algorithm that doesn't exist. Turns out that many everyday problems in numerical analysis are not computable.
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- Construction of towers of algorithms usually can give us information needed to lower SCI. I.e. information needed about the class of objects to help compute the problem.

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- It is **crucial** in rigorous numerical analysis to understand the difference between Δ_1 (convergence with global error control), Σ_1 (convergence with error control of output) and Δ_2 (convergence with no error control).

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- Construction of towers of algorithms usually can give us information needed to lower SCI. I.e. information needed about the class of objects to help compute the problem.
- It is **crucial** in rigorous numerical analysis to understand the difference between Δ_1 (convergence with global error control), Σ_1 (convergence with error control of output) and Δ_2 (convergence with no error control).
- Problems in Σ₁ and Π₁ can be used in computer assisted proofs in pure maths and mathematical physics.

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Schrödinger Operators

• $\operatorname{Sp}(H) := \{z \in \mathbb{C} : H - zI \text{ not invertible}\}.$

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Schrödinger					
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- $\operatorname{Sp}(H) := \{z \in \mathbb{C} : H zI \text{ not invertible}\}.$
- Want to compute spectrum of a Schrödinger operator

$$H = -\Delta + V, \qquad V : \mathbb{R}^d \to \mathbb{C},$$

Classical problem in computational quantum mechanics. Consider computations using point samples of the potential V(x) (no matrix values are assumed).

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• Unsolved for a long time when considering H acting on $L^2(\mathbb{R}^d)$. Also allow non self-adjointness (complex potentials).

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- Unsolved for a long time when considering H acting on $L^2(\mathbb{R}^d)$. Also allow non self-adjointness (complex potentials).
- (\mathcal{M}, d) the Attouch-Wets metric defined by

$$d_{AW}(A,B) = \sum_{i=1}^{\infty} 2^{-i} \min \left\{ 1, \sup_{|x| < i} |d(x,A) - d(x,B)| \right\},$$

for non-empty close A and B - generalises Hausdorff metric.
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Schrödinger					

Schrödinger operators: Bounded potential

$$\begin{split} \phi &: [0,\infty) \to [0,\infty) \text{ some increasing function and } M > 0\\ \Omega_{\phi} &:= \{H : \mathcal{D}(H) = \mathrm{W}^{2,2}(\mathbb{R}^d), V \in \mathrm{BV}_{\phi}(\mathbb{R}^d), \|V\|_{\infty} \leq M\},\\ \Omega_{\phi,g} &:= \{H \in \Omega_{\phi} : \|(-\Delta + V - zI)^{-1}\|^{-1} \geq g(\mathrm{dist}(z, \mathrm{Sp}(H)))\}, \end{split}$$

- Controlled oscillation: $\mathrm{BV}_{\phi}(\mathbb{R}^d) = \{f : \mathrm{TV}(f_{[-a,a]^d}) \le \phi(a)\}$
- Controlled resolvent growth near spectrum: $g : \mathbb{R}_+ \to \mathbb{R}_+$ continuous increasing function with $g(x) \le x$, $\lim_{x\to\infty} g(x) = \infty$.

$$g(\operatorname{dist}(z, \operatorname{Sp}(H))) \le ||(H - zI)^{-1}||^{-1}$$

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Schrodinger

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$$g(\operatorname{dist}(z,\operatorname{Sp}(H))) \leq \|(H-zI)^{-1}\|^{-1}.$$

Theorem 1 (Bounded potential [22])

 $\Delta_1^G \not\ni \{\operatorname{Sp}(\cdot),\Omega_\phi\} \in \mathsf{\Pi}_2^\mathcal{A} \ , \quad \Delta_1^G \not\ni \{\operatorname{Sp}(\cdot),\Omega_{\phi,g}\} \in \Sigma_1^\mathcal{A}.$

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Extensio	ons				

Can extend the above to

- Unbounded potentials.
- PDEs $Tu(x) = \sum_{|k| \le N} a_k(x) \partial^k u(x)$ with polynomially bounded coefficients.
- Different domains (such as half line, polygons etc.) and different boundary conditions.

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Recall t	he problem				

Given an infinite matrix (acting as a bounded operator on $I^2(\mathbb{N})$)

$$A = \begin{pmatrix} a_{11} & a_{12} & a_{13} & \dots \\ a_{21} & a_{22} & a_{23} & \dots \\ a_{31} & a_{32} & a_{33} & \dots \\ \vdots & \vdots & \vdots & \ddots \end{pmatrix}$$

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Want to compute the spectrum Sp(A).

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Want to compute the spectrum Sp(A).

What about other properties like discrete spectra, fractal dimensions, spectral gaps,...?

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What structure do we need to lower the SCI?

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Want to compute the spectrum Sp(A).

What about other properties like discrete spectra, fractal dimensions, spectral gaps,...?

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Simply taking square truncations $Sp(P_nAP_n)$ (finite section) can fail spectacularly even in self-adjoint case (spectral pollution - false eigenvalues in gaps of essential spectrum).

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First ever algorithm that computes spectrum without spectral pollution

Definition 2 (Dispersion - off-diagonal decay)

We say that the dispersion of $A \in \mathcal{B}(l^2(\mathbb{N}))$ is bounded by the function $f : \mathbb{N} \to \mathbb{N}$ if

 $D_{f,m}(A) := \max\{\|(I-P_{f(m)})AP_m\|, \|P_mA(I-P_{f(m)})\|\} \rightarrow 0 \quad \text{as } m \rightarrow \infty.$

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Definition 2 (Dispersion - off-diagonal decay)

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$$D_{f,m}(A):=\max\{\|(I-P_{f(m)})AP_m\|,\|P_mA(I-P_{f(m)})\|\}
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Definition 3 (Controlled growth of the resolvent - well-conditioned)

 $g:[0,\infty) \to [0,\infty)$ continuous, strictly increasing, vanishing only at x = 0 and tending to infinity as $x \to \infty$ with $g(x) \le x$. Controlled growth of the resolvent by g if

 $\|(A-zI)^{-1}\|^{-1} \ge g(\operatorname{dist}(z,\operatorname{Sp}(A))) \quad \forall z \in \mathbb{C}.$

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What do	oes this mean	1?			

• Dispersion - think banded matrices.

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What do	oes this mean	?			

- Dispersion think banded matrices.
- Controlled resolvent g is a measure of the conditioning of the problem of computing Sp(A) through the formula

$$\{z \in \mathbb{C} : \|(A - zI)^{-1}\|^{-1} \le \epsilon\} = \bigcup_{\|B\| \le \epsilon} \operatorname{Sp}(A + B).$$

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$$\{z \in \mathbb{C} : \|(A - zI)^{-1}\|^{-1} \le \epsilon\} = \bigcup_{\|B\| \le \epsilon} \operatorname{Sp}(A + B).$$

• Self-adjoint and normal operators (A commutes with A*) have well conditioned spectral problems since

$$\|(A - zI)^{-1}\|^{-1} = \operatorname{dist}(z, \operatorname{Sp}(A)), \quad g(x) = x.$$

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• Self-adjoint and normal operators (A commutes with A*) have well conditioned spectral problems since

$$\|(A - zI)^{-1}\|^{-1} = \operatorname{dist}(z, \operatorname{Sp}(A)), \quad g(x) = x.$$

Turns out if we know f and g we can compute the spectrum with Σ_1 error control! A completely different method to other previous approaches - local, fast and rigorous [23].

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Have classifications of:

• Lebesgue measure and fractal dimensions of spectra (different types).

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- Lebesgue measure and fractal dimensions of spectra (different types).
- Discrete spectra, essential spectra, eigenvectors (if they exist)
 + multiplicity, spectral type, point spectra etc.

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- Lebesgue measure and fractal dimensions of spectra (different types).
- Discrete spectra, essential spectra, eigenvectors (if they exist)
 + multiplicity, spectral type, point spectra etc.
- Spectral radii, essential numerical ranges, geometric features of spectrum etc.

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Have classifications of:

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For a whole bunch of classes:

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For a whole bunch of classes:

• Self-adjoint, normal, diagonal.

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ALL constructed algorithms can cope with inexact input using only arithmetic over \mathbb{Q} , are stable and recursive.

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• Quantum mechanics, quasicrystals



Figure: Left: Dan Shechtman, Nobel Prize in Chemistry 2011. Right: Electron diffraction pattern of quasicrystal.

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• Quantum mechanics, quasicrystals



Figure: Left: Dan Shechtman, Nobel Prize in Chemistry 2011. Right: Electron diffraction pattern of quasicrystal.

• Intensely investigated since the 1950s, still very active today.



Figure: Left: Artur Avila, Fields Medal 2014. Right: Hofstadter butterfly.

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Laplacian on Penrose Tile



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Naïve A	pproximations	5			

 Finite section with open boundary conditions: compute eigenvalues of truncated matrix P_nH₀P_n for large n. Similar "Galerkin" methods - suffer from spectral pollution.

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Naïve A	pproximation	S			

- Finite section with open boundary conditions: compute eigenvalues of truncated matrix P_nH₀P_n for large n. Similar "Galerkin" methods - suffer from spectral pollution.
- ② Can construct Penrose tile via "Pentagrid" ~> "Periodic Approximants"



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Naïve A	pproximation	S			

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- Can construct Penrose tile via "Pentagrid" ~> "Periodic Approximants"



These represent state of art in (vast physics/maths) literature. Can we beat this?

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Laplacian on Penrose Tile



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Open P	roblems				

 Sharp classification for continuous non-Hermitian Schrödinger operators (recall only know ∈ Π^A₂) and more general PDEs applications in rigorous numerics for resonances in arbitrary dimension etc.

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Open P	roblems				

- Sharp classification for continuous non-Hermitian Schrödinger operators (recall only know ∈ Π^A₂) and more general PDEs applications in rigorous numerics for resonances in arbitrary dimension etc.
- Non-linear eigenvalue problems, extensions to Banach spaces...

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Open Pi	roblems				

- Sharp classification for continuous non-Hermitian Schrödinger operators (recall only know ∈ Π^A₂) and more general PDEs applications in rigorous numerics for resonances in arbitrary dimension etc.
- Non-linear eigenvalue problems, extensions to Banach spaces...
- Current work is looking at **rigorous** computability results for **stable** neural networks (looking increasingly likely that this **can** be done).

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Thank you for listening

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Solvability Complexity Index (SCI) [24, Hansen, JAMS]

 Ω is some set, called the primary set,

A is a set of complex valued functions on Ω , called the *evaluation* set, \mathcal{M} is a metric space, where the thing we compute lives Ξ is a mapping $\Omega \to \mathcal{M}$, called the *problem* function.

E.g. $\Omega = \mathcal{B}(\mathcal{H})$, problem function Ξ maps $A \mapsto \operatorname{Sp}(A)$, (\mathcal{M}, d) set of all compact subsets of \mathbb{C} with Hausdorff metric and evaluation functions in Λ consist of $f_{i,j} : A \mapsto \langle Ae_j, e_i \rangle$, $i, j \in \mathbb{N}$, which provide the entries of the matrix representation of A w.r.t. an orthonormal basis $\{e_i\}_{i\in\mathbb{N}}$.

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Definition 4 (General Algorithm)

Given a computational problem $\{\Xi, \Omega, \mathcal{M}, \Lambda\}$, a general algorithm is a mapping $\Gamma : \Omega \to \mathcal{M}$ such that for each $A \in \Omega$:

- (i) there exists a finite subset of evaluations $\Lambda_{\Gamma}(A) \subset \Lambda$,
- (ii) the action of Γ on A only depends on $\{A_f\}_{f \in \Lambda_{\Gamma}(A)}$ where $A_f := f(A)$,
- (iii) for every $B \in \Omega$ such that $B_f = A_f$ for every $f \in \Lambda_{\Gamma}(A)$, it holds that $\Lambda_{\Gamma}(B) = \Lambda_{\Gamma}(A)$.

No restrictions on the operations allowed (can consult any fixed oracle etc.). But can consider different types of towers. E.g. type-2 Turing machines, allow radicals, BSS model, ...

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Definition 5 (Tower of algorithms)

Given $\{\Xi, \Omega, \mathcal{M}, \Lambda\}$, a tower of algorithms of height k for $\{\Xi, \Omega, \mathcal{M}, \Lambda\}$ is a collection of sequences of functions

$$\Gamma_{n_k}:\Omega\to\mathcal{M},\quad \Gamma_{n_k,n_{k-1}}:\Omega\to\mathcal{M},\,\ldots\,,\Gamma_{n_k,\ldots,n_1}:\Omega\to\mathcal{M},$$

where $n_k, \ldots, n_1 \in \mathbb{N}$ and the functions $\Gamma_{n_k, \ldots, n_1}$ are general algorithms. Moreover, for every $A \in \Omega$,

$$\lim_{n_k\to\infty}\ldots\lim_{n_1\to\infty}\Gamma_{n_k,\ldots,n_1}(A)=\Xi(A)$$

with convergence in metric space \mathcal{M} .

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Definition 6 (Solvability Complexity Index)

 $\{\Xi, \Omega, \mathcal{M}, \Lambda\}$ is said to have $SCI(\Xi, \Omega, \mathcal{M}, \Lambda)_{\alpha} = k$ with respect to a tower of algorithms of type α if k is the smallest integer for which there exists a tower of algorithms of type α of height k.

If no such tower exists then $SCI(\Xi, \Omega, \mathcal{M}, \Lambda)_{\alpha} = \infty$.

If there exists a tower $\{\Gamma_n\}_{n\in\mathbb{N}}$ of type α and height one such that $\Xi = \Gamma_{n_1}$ for some finite n_1 , then we define $\operatorname{SCI}(\Xi, \Omega, \mathcal{M}, \Lambda)_{\alpha} = 0$.

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Definition 7 (The Solvability Complexity Index Hierarchy)

Consider a collection C of computational problems and let T be the collection of all towers of algorithms of type α for the computational problems in C. Define

$$\Delta_0^{lpha} := \{\{\Xi, \Omega\} \in \mathcal{C} \mid \mathrm{SCI}(\Xi, \Omega)_{lpha} = 0\}$$

 $\Delta_{m+1}^{lpha} := \{\{\Xi, \Omega\} \in \mathcal{C} \mid \mathrm{SCI}(\Xi, \Omega)_{lpha} \le m\}, \qquad m \in \mathbb{N},$

as well as

$$\Delta_1^{\alpha} := \{\{\Xi, \Omega\} \in \mathcal{C} \mid \exists \{\Gamma_n\}_{n \in \mathbb{N}} \in \mathcal{T} \text{ s.t. } \forall A \ d(\Gamma_n(A), \Xi(A)) \le 2^{-n}\}$$