# The Computational Spectral Problem and a New Classification Theory <br> Novel Algorithms, Impossibility Results and Computer Assisted Proofs 

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## Motivation

- Motivating example: spectra of infinite-dimensional operators, vast number of applications. W. Arveson (leading operator theorist U.C. Berkeley) in 90s: "Unfortunately, there is a dearth of literature on this basic problem, and ... there are no proven techniques." Situation even worse for the Schrödinger case:


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- Given a Schrödinger operator

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- Naive discretisations can fail spectacularly even when $V$ real valued.
- Talk will present solution to this problem and how to compute spectra for much more general cases.


## Computational Schrödinger Problem

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Studied by great scientists and mathematicians throughout 20th and 21st centuries. Very incomplete list - P.W. Anderson [2], J. Schwinger [3], A. Weyl [4], T. Digernes, V.S. Varadarajan and S.R.S. Varadhan [5], A. Böttcher [6, 7], P.A. Deift, L.C. Li and C.

Tomei [8], C. Fefferman and L. Seco
[9, 10, 11, 12, 13, 14, 15, 16, 17], P. Hertel, E. Lieb and W.
Thirring [18], L. Demanet and W. Schlag [19], M. Zworski [20, 21].

## A curious case of limits

Problem: Given an infinite matrix (acting as a bounded operator on $I^{2}(\mathbb{N})$ )

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can we compute the spectrum $\operatorname{Sp}(A)$ from the matrix elements in Hausdorff metric?
Answer [22]: No! Best one can do is compute using three successive limits:

$$
\lim _{n_{3} \rightarrow \infty} \lim _{n_{2} \rightarrow \infty} \lim _{n_{1} \rightarrow \infty} \Gamma_{n_{3}, n_{2}, n_{1}}(A)=\operatorname{Sp}(A)
$$

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Computational problem: decide whether there is an $x \in \mathbb{R}^{N}$ such that

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\text { (1) }\langle x, c\rangle_{K} \leq M \text { subject to } A x=y, \quad x \geq 0
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where

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Irrational input numbers means that $A$ and $y$ are only known approximately, however, to any precision one wants. Not computable. But if replace $\langle x, c\rangle_{K} \leq M$ by $\langle x, c\rangle_{K}<M$ then problem is verifiable. If there had been cases with equality, the Flyspeck program may never have resolved Kepler's conjecture!

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(iv) $\Delta_{m+1}^{\alpha}$, for $m \in \mathbb{N}$, is the set of problems that can be computed by using $m$ limits, the $\mathrm{SCI} \leq m$.

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One side version of error control.
What about other spaces such as Hausdorff metric?


Figure: Meaning of $\Sigma_{1}$ and $\Pi_{1}$ convergence for problem function $\overline{\text {. }}$. The red area represents $\Xi(A)$ whereas the green areas represent the output of the algorithm $\Gamma_{n}(A)$. $\Sigma_{1}$ convergence means convergence as $n \rightarrow \infty$ but each output point in $\Gamma_{n}(A)$ is at most distance $2^{-n}$ from $\bar{\equiv}(A)$. Similarly for $\Pi_{1}$, we have convergence as $n \rightarrow \infty$ but any point in $\Xi(A)$ is at most distance $2^{-n}$ from $\Gamma_{n}(A)$.

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- It is crucial in rigorous numerical analysis to understand the difference between $\Delta_{1}$ (convergence with global error control), $\Sigma_{1}$ (convergence with error control of output) and $\Delta_{2}$ (convergence with no error control).
- Problems in $\Sigma_{1}$ and $\Pi_{1}$ can be used in computer assisted proofs in pure maths and mathematical physics.


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- Unsolved for a long time when considering $H$ acting on $\mathrm{L}^{2}\left(\mathbb{R}^{d}\right)$. Also allow non self-adjointness (complex potentials).
- $(\mathcal{M}, d)$ the Attouch-Wets metric defined by

$$
d_{\mathrm{AW}}(A, B)=\sum_{i=1}^{\infty} 2^{-i} \min \left\{1, \sup _{|x|<i}|d(x, A)-d(x, B)|\right\}
$$

for non-empty close $A$ and $B$ - generalises Hausdorff metric.

## Schrödinger operators: Bounded potential

$$
\begin{aligned}
\phi & :[0, \infty) \rightarrow[0, \infty) \text { some increasing function and } M>0 \\
\Omega_{\phi} & :=\left\{H: \mathcal{D}(H)=\mathrm{W}^{2,2}\left(\mathbb{R}^{d}\right), V \in \mathrm{BV}_{\phi}\left(\mathbb{R}^{d}\right),\|V\|_{\infty} \leq M\right\}, \\
\Omega_{\phi, g} & :=\left\{H \in \Omega_{\phi}:\left\|(-\Delta+V-z)^{-1}\right\|^{-1} \geq g(\operatorname{dist}(z, \operatorname{Sp}(H)))\right\},
\end{aligned}
$$

- Controlled oscillation: $\mathrm{BV}_{\phi}\left(\mathbb{R}^{d}\right)=\left\{f: \operatorname{TV}\left(f_{[-a, a]^{d}}\right) \leq \phi(a)\right\}$
- Controlled resolvent growth near spectrum: $g: \mathbb{R}_{+} \rightarrow \mathbb{R}_{+}$ continuous increasing function with $g(x) \leq x$, $\lim _{x \rightarrow \infty} g(x)=\infty$.

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## Theorem 1 (Bounded potential [22])

$$
\Delta_{1}^{G} \nexists\left\{\operatorname{Sp}(\cdot), \Omega_{\phi}\right\} \in \Pi_{2}^{A}, \quad \Delta_{1}^{G} \nexists\left\{\operatorname{Sp}(\cdot), \Omega_{\phi, g}\right\} \in \Sigma_{1}^{A} .
$$

## Extensions

Can extend the above to

- Unbounded potentials.
- PDEs $T u(x)=\sum_{|k| \leq N} a_{k}(x) \partial^{k} u(x)$ with polynomially bounded coefficients.
- Different domains (such as half line, polygons etc.) and different boundary conditions.


## Recall the problem

Given an infinite matrix (acting as a bounded operator on $I^{2}(\mathbb{N})$ )

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What about other properties like discrete spectra, fractal dimensions, spectral gaps,...?
What structure do we need to lower the SCI ?
Simply taking square truncations $\operatorname{Sp}\left(P_{n} A P_{n}\right)$ (finite section) can fail spectacularly even in self-adjoint case (spectral pollution - false eigenvalues in gaps of essential spectrum).

## First ever algorithm that computes spectrum without

 spectral pollution
## Definition 2 (Dispersion - off-diagonal decay)

We say that the dispersion of $A \in \mathcal{B}\left(I^{2}(\mathbb{N})\right)$ is bounded by the function $f: \mathbb{N} \rightarrow \mathbb{N}$ if
$D_{f, m}(A):=\max \left\{\left\|\left(I-P_{f(m)}\right) A P_{m}\right\|,\left\|P_{m} A\left(I-P_{f(m)}\right)\right\|\right\} \rightarrow 0 \quad$ as $m \rightarrow \infty$.

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Definition 3 (Controlled growth of the resolvent - well-conditioned)
$g:[0, \infty) \rightarrow[0, \infty)$ continuous, strictly increasing, vanishing only at $x=0$ and tending to infinity as $x \rightarrow \infty$ with $g(x) \leq x$.
Controlled growth of the resolvent by $g$ if

$$
\left\|(A-z l)^{-1}\right\|^{-1} \geq g(\operatorname{dist}(z, \operatorname{Sp}(A))) \quad \forall z \in \mathbb{C} .
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- Self-adjoint and normal operators ( $A$ commutes with $A^{*}$ ) have well conditioned spectral problems since

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Turns out if we know $f$ and $g$ we can compute the spectrum with $\Sigma_{1}$ error control! A completely different method to other previous approaches - local, fast and rigorous [23].

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ALL constructed algorithms can cope with inexact input using only arithmetic over $\mathbb{Q}$, are stable and recursive.

- Quantum mechanics, quasicrystals


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Right: Electron diffraction pattern of quasicrystal.

- Intensely investigated since the 1950s, still very active today.


Figure: Left: Artur Avila, Fields Medal 2014. Right: Hofstadter butterfly.

## Laplacian on Penrose Tile



## Naïve Approximations

(1) Finite section with open boundary conditions: compute eigenvalues of truncated matrix $P_{n} H_{0} P_{n}$ for large $n$. Similar "Galerkin" methods - suffer from spectral pollution.

## Naïve Approximations

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These represent state of art in (vast physics/maths) literature. Can we beat this?

## Laplacian on Penrose Tile



## Laplacian on Penrose Tile



## Open Problems

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## Open Problems

- Sharp classification for continuous non-Hermitian Schrödinger operators (recall only know $\in \Pi_{2}^{A}$ ) and more general PDEs applications in rigorous numerics for resonances in arbitrary dimension etc.
- Non-linear eigenvalue problems, extensions to Banach spaces...
- Current work is looking at rigorous computability results for stable neural networks (looking increasingly likely that this can be done).

Thank you for listening

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## Solvability Complexity Index (SCI) [24, Hansen, JAMS]

$\Omega$ is some set, called the primary set,
$\Lambda$ is a set of complex valued functions on $\Omega$, called the evaluation set, $\mathcal{M}$ is a metric space, where the thing we compute lives
三 is a mapping $\Omega \rightarrow \mathcal{M}$, called the problem function.
E.g. $\Omega=\mathcal{B}(\mathcal{H})$, problem function $\equiv$ maps $A \mapsto \operatorname{Sp}(A)$, $(\mathcal{M}, d)$ set of all compact subsets of $\mathbb{C}$ with Hausdorff metric and evaluation functions in $\Lambda$ consist of $f_{i, j}: A \mapsto\left\langle A e_{j}, e_{i}\right\rangle, i, j \in \mathbb{N}$, which provide the entries of the matrix representation of $A$ w.r.t. an orthonormal basis $\left\{e_{i}\right\}_{i \in \mathbb{N}}$.

## Definition 4 (General Algorithm)

Given a computational problem $\{\equiv, \Omega, \mathcal{M}, \Lambda\}$, a general algorithm is a mapping $\Gamma: \Omega \rightarrow \mathcal{M}$ such that for each $A \in \Omega$ :
(i) there exists a finite subset of evaluations $\Lambda_{\Gamma}(A) \subset \Lambda$,
(ii) the action of $\Gamma$ on $A$ only depends on $\left\{A_{f}\right\}_{f \in \Lambda_{\Gamma}(A)}$ where $A_{f}:=f(A)$,
(iii) for every $B \in \Omega$ such that $B_{f}=A_{f}$ for every $f \in \Lambda_{\Gamma}(A)$, it holds that $\Lambda_{\Gamma}(B)=\Lambda_{\Gamma}(A)$.

No restrictions on the operations allowed (can consult any fixed oracle etc.). But can consider different types of towers. E.g. type-2 Turing machines, allow radicals, BSS model, ...

## Definition 5 (Tower of algorithms)

Given $\{三, \Omega, \mathcal{M}, \Lambda\}$, a tower of algorithms of height $k$ for $\{\equiv, \Omega, \mathcal{M}, \Lambda\}$ is a collection of sequences of functions

$$
\Gamma_{n_{k}}: \Omega \rightarrow \mathcal{M}, \quad \Gamma_{n_{k}, n_{k-1}}: \Omega \rightarrow \mathcal{M}, \ldots, \Gamma_{n_{k}, \ldots, n_{1}}: \Omega \rightarrow \mathcal{M}
$$

where $n_{k}, \ldots, n_{1} \in \mathbb{N}$ and the functions $\Gamma_{n_{k}, \ldots, n_{1}}$ are general algorithms. Moreover, for every $A \in \Omega$,

$$
\lim _{n_{k} \rightarrow \infty} \ldots \lim _{n_{1} \rightarrow \infty} \Gamma_{n_{k}, \ldots, n_{1}}(A)=\equiv(A)
$$

with convergence in metric space $\mathcal{M}$.

## Definition 6 (Solvability Complexity Index)

$\{\equiv, \Omega, \mathcal{M}, \Lambda\}$ is said to have $\operatorname{SCI}(\equiv, \Omega, \mathcal{M}, \Lambda)_{\alpha}=k$ with respect to a tower of algorithms of type $\alpha$ if $k$ is the smallest integer for which there exists a tower of algorithms of type $\alpha$ of height $k$.

If no such tower exists then $\operatorname{SCI}(\equiv, \Omega, \mathcal{M}, \Lambda)_{\alpha}=\infty$.
If there exists a tower $\left\{\Gamma_{n}\right\}_{n \in \mathbb{N}}$ of type $\alpha$ and height one such that $\equiv=\Gamma_{n_{1}}$ for some finite $n_{1}$, then we define $\operatorname{SCI}(\equiv, \Omega, \mathcal{M}, \Lambda)_{\alpha}=0$.

## Definition 7 (The Solvability Complexity Index Hierarchy)

Consider a collection $\mathcal{C}$ of computational problems and let $\mathcal{T}$ be the collection of all towers of algorithms of type $\alpha$ for the computational problems in $\mathcal{C}$. Define

$$
\begin{aligned}
\Delta_{0}^{\alpha} & :=\left\{\{\equiv, \Omega\} \in \mathcal{C} \mid \operatorname{SCI}(\equiv, \Omega)_{\alpha}=0\right\} \\
\Delta_{m+1}^{\alpha} & :=\left\{\{\equiv, \Omega\} \in \mathcal{C} \mid \operatorname{SCI}(\equiv, \Omega)_{\alpha} \leq m\right\}, \quad m \in \mathbb{N},
\end{aligned}
$$

as well as
$\Delta_{1}^{\alpha}:=\left\{\{三, \Omega\} \in \mathcal{C} \mid \exists\left\{\Gamma_{n}\right\}_{n \in \mathbb{N}} \in \mathcal{T}\right.$ s.t. $\left.\forall A d\left(\Gamma_{n}(A), \equiv(A)\right) \leq 2^{-n}\right\}$

