Residual Dynamic Mode Decomposition

Rigorous data-driven computation of spectral properties of Koopman operators for dynamical systems

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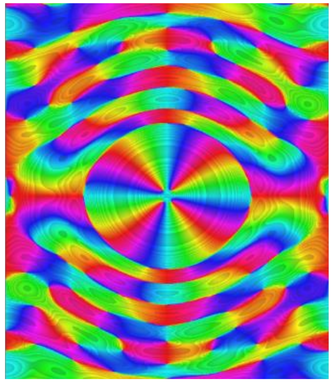
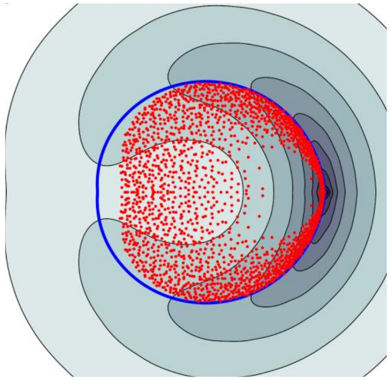




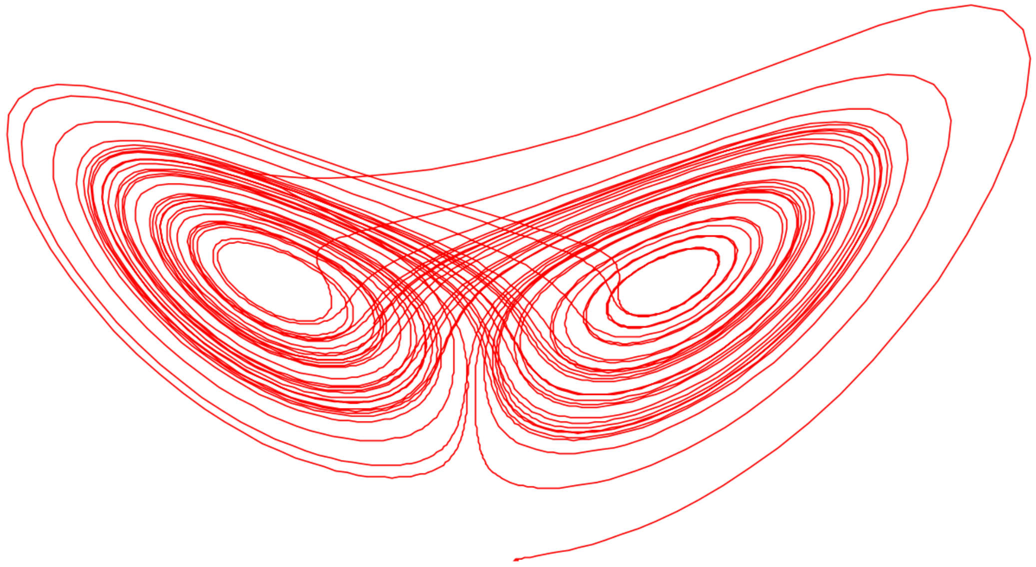
C., T., *"Rigorous data-driven computation of spectral properties of Koopman operators for dynamical systems,"* preprint.

Data-driven dynamical systems

- State $x \in \Omega \subseteq \mathbb{R}^d$, ***unknown*** function $F: \Omega \to \Omega$ governs dynamics

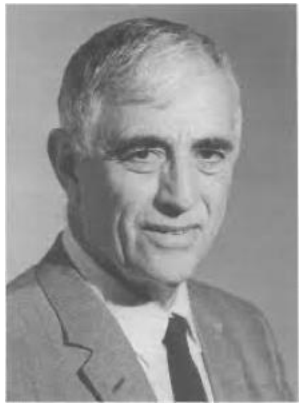
$$x_{n+1} = F(x_n)$$

- **Goal:** Learn about system from data $\left\{x^{(m)}, y^{(m)} = F\left(x^{(m)}\right)\right\}_{m=1}^{M}$
  - **Data:** experimental measurements or numerical simulations
  - E.g., **used for** forecasting, control, design, understanding
- **Applications:** chemistry, climatology, electronics, epidemiology, finance, fluids, molecular dynamics, neuroscience, plasmas, robotics, video processing, etc.



Operator viewpoint

Koopman

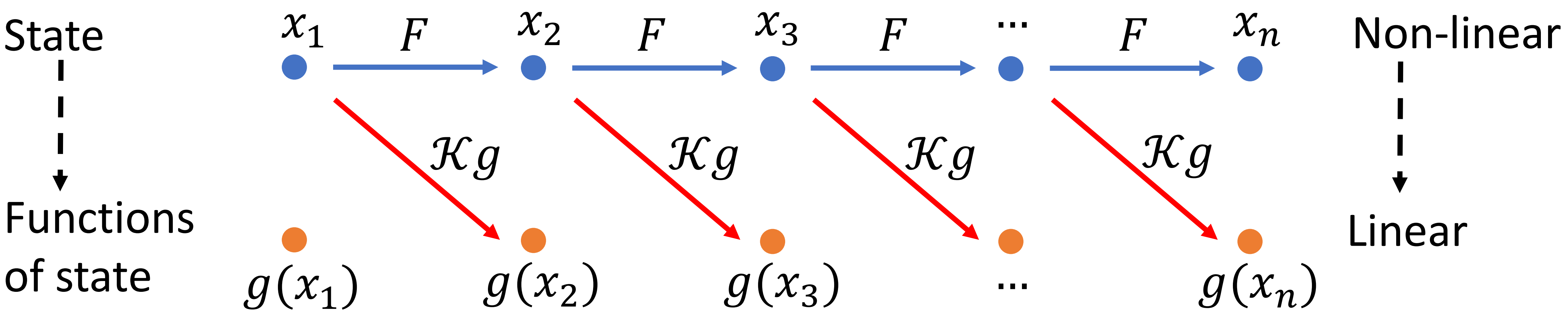


von Neumann

- **Koopman operator** $\mathcal{K}$ acts on <u>functions</u> $g\colon \Omega \to \mathbb{C}$

$$[\mathcal{K}g](x) = g(F(x))$$

- $\mathcal{K}$ is ***linear*** but acts on an ***infinite-dimensional*** space.



- Work in $L^2(\Omega, \omega)$ for positive measure ω, with inner product $\langle \cdot, \cdot \rangle$.

- Koopman, *"Hamiltonian systems and transformation in Hilbert space,"* **Proc. Natl. Acad. Sci. USA**, 1931.
- Koopman, v. Neumann, *"Dynamical systems of continuous spectra,"* **Proc. Natl. Acad. Sci. USA**, 1932.

Koopman mode decomposition

$\boxed{x_{n+1} = F(x_n)}$

$\boxed{[\mathcal{K}g](x) = g(F(x))}$

eigenfunction of $\mathcal{K}$

generalised eigenfunction of $\mathcal{K}$

$$g(x) = \sum_{\text{eigenvalues } \lambda_j} c_{\lambda_j} \varphi_{\lambda_j}(x) + \int_{-\pi}^{\pi} \phi_{\theta,g}(x)\,\mathrm{d}\theta$$

$$g(x_n) = [\mathcal{K}^n g](x_0) = \sum_{\text{eigenvalues } \lambda_j} c_{\lambda_j} {\lambda_j}^n \varphi_{\lambda_j}(x_0) + \int_{-\pi}^{\pi} e^{in\theta} \phi_{\theta,g}(x_0)\,\mathrm{d}\theta$$

Encodes: geometric features, invariant measures, transient behaviour, long-time behaviour, coherent structures, quasiperiodicity, etc.

GOAL: Data-driven approximation of $\mathcal{K}$ and its spectral properties.

- Mezić, "*Spectral properties of dynamical systems, model reduction and decompositions,*" **Nonlinear Dynamics**, 2005.

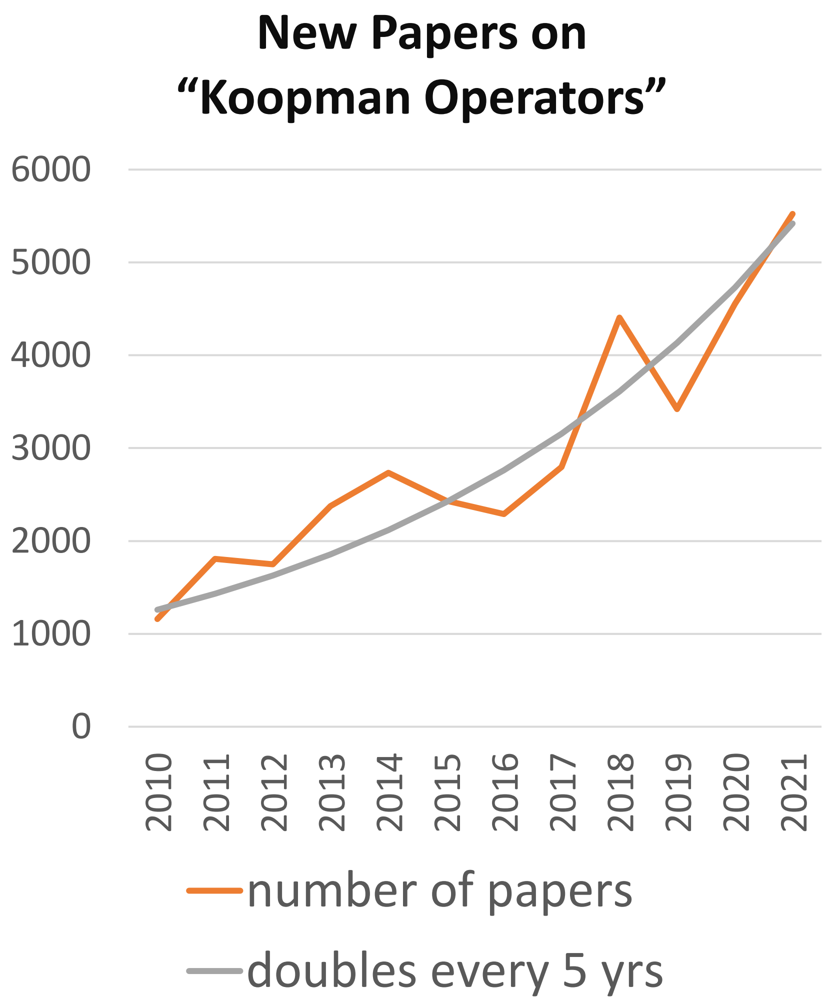
Koopmania*: a revolution in the big data era

≈35,000 papers over last decade!

Very **little on convergence guarantees or verification.**

Why is this lacking?

- Koopman operators have so far been quite distinct from both analysis and computational communities.
- Dealing with infinite dim is notoriously hard …



***Wikipedia*: *“its wild surge in popularity is sometimes jokingly called ‘Koopmania’”*

Challenges of computing $\mathrm{Spec}(\mathcal{K}) = \{\lambda \in \mathbb{C}: \mathcal{K} - \lambda I \text{ is not invertible}\}$

Truncate: $\mathcal{K} \longrightarrow \mathbb{K} \in \mathbb{C}^{N_K \times N_K}$

1) **"Too much":** Approximate spurious modes $\lambda \notin \mathrm{Spec}(\mathcal{K})$
2) **"Too little":** Miss parts of $\mathrm{Spec}(\mathcal{K})$
3) **Continuous spectra**
4) **Verification:** Which part of an approximation can we trust?

Build the matrix: Dynamic Mode Decomposition (DMD)

Given dictionary $\{\psi_1, \ldots, \psi_{N_K}\}$ of functions $\psi_j: \Omega \to \mathbb{C}$,

$$\boxed{\left\{x^{(m)}, y^{(m)} = F(x^{(m)})\right\}_{m=1}^{M}}$$

$$\langle \psi_k, \psi_j \rangle \approx \sum_{m=1}^{M} w_m \overline{\psi_j(x^{(m)})} \psi_k(x^{(m)}) = \Bigg[\underbrace{\begin{pmatrix} \psi_1(x^{(1)}) & \cdots & \psi_{N_K}(x^{(1)}) \\ \vdots & \ddots & \vdots \\ \psi_1(x^{(M)}) & \cdots & \psi_{N_K}(x^{(M)}) \end{pmatrix}^*}_{\Psi_X} \underbrace{\begin{pmatrix} w_1 & & \\ & \ddots & \\ & & w_M \end{pmatrix}}_{W} \underbrace{\begin{pmatrix} \psi_1(x^{(1)}) & \cdots & \psi_{N_K}(x^{(1)}) \\ \vdots & \ddots & \vdots \\ \psi_1(x^{(M)}) & \cdots & \psi_{N_K}(x^{(M)}) \end{pmatrix}}_{\Psi_X} \Bigg]_{jk}$$

$$\langle \mathcal{K}\psi_k, \psi_j \rangle \approx \sum_{m=1}^{M} w_m \overline{\psi_j(x^{(m)})} \underbrace{\psi_k(y^{(m)})}_{[\mathcal{K}\psi_k](x^{(m)})} = \Bigg[\underbrace{\begin{pmatrix} \psi_1(x^{(1)}) & \cdots & \psi_{N_K}(x^{(1)}) \\ \vdots & \ddots & \vdots \\ \psi_1(x^{(M)}) & \cdots & \psi_{N_K}(x^{(M)}) \end{pmatrix}^*}_{\Psi_X} \underbrace{\begin{pmatrix} w_1 & & \\ & \ddots & \\ & & w_M \end{pmatrix}}_{W} \underbrace{\begin{pmatrix} \psi_1(y^{(1)}) & \cdots & \psi_{N_K}(y^{(1)}) \\ \vdots & \ddots & \vdots \\ \psi_1(y^{(M)}) & \cdots & \psi_{N_K}(y^{(M)}) \end{pmatrix}}_{\Psi_Y} \Bigg]_{jk}$$

$$\mathcal{K} \longrightarrow \mathbb{K} = (\Psi_X{}^* W \Psi_X)^{-1} \Psi_X{}^* W \Psi_Y \in \mathbb{C}^{N_K \times N_K}$$

Recall open problems: too much, too little, continuous spectra, verification

- Schmid, “*Dynamic mode decomposition of numerical and experimental data,*” **J. Fluid Mech.**, 2010.
- Kutz, Brunton, Brunton, Proctor, “*Dynamic mode decomposition: data-driven modeling of complex systems,*” **SIAM**, 2016.
- Williams, Kevrekidis, Rowley “*A data-driven approximation of the Koopman operator: Extending dynamic mode decomposition,*” **J. Nonlinear Sci.**, 2015.

Residual DMD (ResDMD): Approx. $\mathcal{K}$ and $\mathcal{K}^*\mathcal{K}$

$$\langle \psi_k, \psi_j \rangle \approx \sum_{m=1}^{M} w_m \overline{\psi_j(x^{(m)})}\, \psi_k(x^{(m)}) = [\underbrace{\Psi_X{}^* W \Psi_X}_{G}]_{jk}$$

$$\langle \mathcal{K}\psi_k, \psi_j \rangle \approx \sum_{m=1}^{M} w_m \overline{\psi_j(x^{(m)})}\, \underbrace{\psi_k(y^{(m)})}_{[\mathcal{K}\psi_k](x^{(m)})} = [\underbrace{\Psi_X{}^* W \Psi_Y}_{K_1}]_{jk}$$

$$\langle \mathcal{K}\psi_k, \mathcal{K}\psi_j \rangle \approx \sum_{m=1}^{M} w_m \overline{\psi_j(y^{(m)})}\, \psi_k(y^{(m)}) = [\underbrace{\Psi_Y{}^* W \Psi_Y}_{K_2}]_{jk}$$

Residuals: $g = \sum_{j=1}^{N_K} \mathbf{g}_j \psi_j,\ \|\mathcal{K}g - \lambda g\|^2 \approx \mathbf{g}^*[K_2 - \lambda K_1{}^* - \bar{\lambda} K_1 + |\lambda|^2 G]\mathbf{g}$

- C., Townsend, *"Rigorous data-driven computation of spectral properties of Koopman operators for dynamical systems,"* preprint.
- C., Ayton, Szőke, *"Residual Dynamic Mode Decomposition,"* **J. Fluid Mech.,** under minor rev.
- Code: https://github.com/MColbrook/Residual-Dynamic-Mode-Decomposition

ResDMD: avoiding "too much"

$$\mathrm{res}(\lambda, \mathbf{g})^2 = \frac{\mathbf{g}^*\left[K_2 - \lambda {K_1}^* - \bar{\lambda} K_1 + |\lambda|^2 G\right]\mathbf{g}}{\mathbf{g}^* G \mathbf{g}}$$

eigenvectors

eigenvalues

Algorithm 1:

1. Compute $G, K_1, K_2 \in \mathbb{C}^{N_K \times N_K}$ and eigendecomposition $K_1 V = G V \Lambda$.
2. For each eigenpair $(\lambda, \mathbf{v})$, compute $\mathrm{res}(\lambda, \mathbf{v})$.
3. **Output:** subset of e-vectors $V_{(\varepsilon)}$ & e-vals $\Lambda_{(\varepsilon)}$ with $\mathrm{res}(\lambda, \mathbf{v}) \le \varepsilon$ $\quad(\varepsilon = \text{input tol})$.

Theorem (no spectral pollution): Suppose quad. rule converges. Then

$$\limsup_{M \to \infty} \max_{\lambda \in \Lambda^{(\varepsilon)}} \|(\mathcal{K} - \lambda)^{-1}\|^{-1} \le \varepsilon$$

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Theorem (no spectral pollution): Suppose quad. rule converges. Then

$$\limsup_{M \to \infty} \max_{\lambda \in \Lambda^{(\varepsilon)}} \|(\mathcal{K} - \lambda)^{-1}\|^{-1} \leq \varepsilon$$

BUT: Typically, does not capture all of spectrum! ("too little")

• C., Townsend, *"Rigorous data-driven computation of spectral properties of Koopman operators for dynamical systems,"* preprint.

ResDMD: avoiding "too little"

$$\mathrm{Spec}_\varepsilon(\mathcal{K}) = \bigcup_{\|\mathcal{B}\|\leq\varepsilon} \mathrm{Spec}(\mathcal{K}+\mathcal{B}), \qquad \lim_{\varepsilon\downarrow 0} \mathrm{Spec}_\varepsilon(\mathcal{K}) = \mathrm{Spec}(\mathcal{K})$$

Algorithm 2:

First convergent method for general $\mathcal{K}$

1. Compute $G, K_1, K_2 \in \mathbb{C}^{N_K \times N_K}$.
2. For z_k in comp. grid, compute $\tau_k = \min_{g=\sum_{j=1}^{N_K} \mathbf{g}_j\psi_j} \mathrm{res}(z_k, g)$, corresponding g_k (gen. SVD).
3. **Output:** $\{z_k : \tau_k < \varepsilon\}$ (approx. of $\mathrm{Spec}_\varepsilon(\mathcal{K})$), $\{g_k : \tau_k < \varepsilon\}$ (ε-pseudo-eigenfunctions).

Theorem (full convergence): Suppose the quadrature rule converges.

- **Error control:** $\{z_k : \tau_k < \varepsilon\} \subseteq \mathrm{Spec}_\varepsilon(\mathcal{K})$ (as $M \to \infty$)
- **Convergence:** Converges locally uniformly to $\mathrm{Spec}_\varepsilon(\mathcal{K})$ (as $N_K \to \infty$)

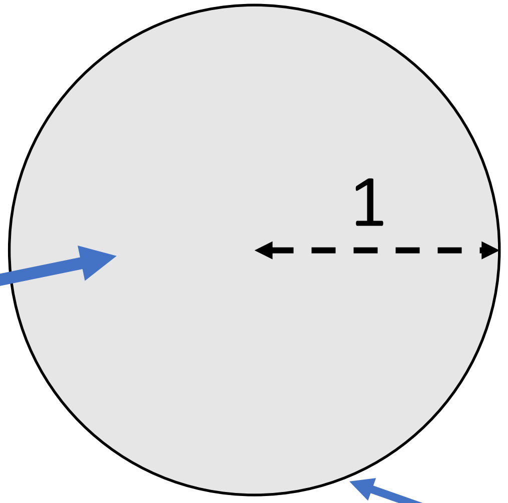
- C., Townsend, *"Rigorous data-driven computation of spectral properties of Koopman operators for dynamical systems,"* preprint.

Setup for continuous spectra

Suppose system is measure preserving (e.g., Hamiltonian, ergodic, post-transient etc.)

$$\Leftrightarrow \mathcal{K}^*\mathcal{K} = I \text{ (isometry)}$$

$$\Rightarrow \mathrm{Spec}(\mathcal{K}) \subseteq \{z: |z| \leq 1\}$$



spectral measure supp. on boundary

(NB: we consider unitary extensions via Wold decomposition.)

Spectral measures → diagonalisation

- **Fin.-dim.:** $B \in \mathbb{C}^{n\times n}$, $B^*B = BB^*$, o.n. basis of e-vectors $\{v_j\}_{j=1}^{n}$

$$v = \left[\sum_{j=1}^{n} v_j {v_j}^*\right] v, \qquad Bv = \left[\sum_{j=1}^{n} \lambda_j v_j {v_j}^*\right] v, \qquad \forall v \in \mathbb{C}^n$$

- **Inf.-dim.:** Operator $\mathcal{L}: \mathcal{D}(\mathcal{L}) \to \mathcal{H}$. Typically, no basis of e-vectors!
  Spectral theorem: (projection-valued) spectral measure E

$$g = \left[\int_{\mathrm{Spec}(\mathcal{L})} 1 \, \mathrm{d}E(\lambda)\right] g, \qquad \mathcal{L}g = \left[\int_{\mathrm{Spec}(\mathcal{L})} \lambda \, \mathrm{d}E(\lambda)\right] g, \qquad \forall g \in \mathcal{H}$$

- **Spectral measures:** $\nu_g(U) = \langle E(U)g, g\rangle$ ($\|g\| = 1$) prob. measure.

Koopman mode decomposition (again!)

ν_g probability measures on $[-\pi,\pi]_{\text{per}}$

Leb. decomp: $$\mathrm{d}\nu_g(y)=\underbrace{\sum_{\text{eigenvalues }\lambda_j=\exp(i\theta_j)}\left\langle P_{\lambda_j}g,g\right\rangle\delta(y-\theta_j)}_{\text{discrete}}+\underbrace{\rho_g(y)\mathrm{d}y+\mathrm{d}\nu_g^{\text{sc}}(y)}_{\text{continuous}}$$

Koopman mode decomposition (again!)

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eigenfunction of $\mathcal{K}$

generalised eigenfunction of $\mathcal{K}$

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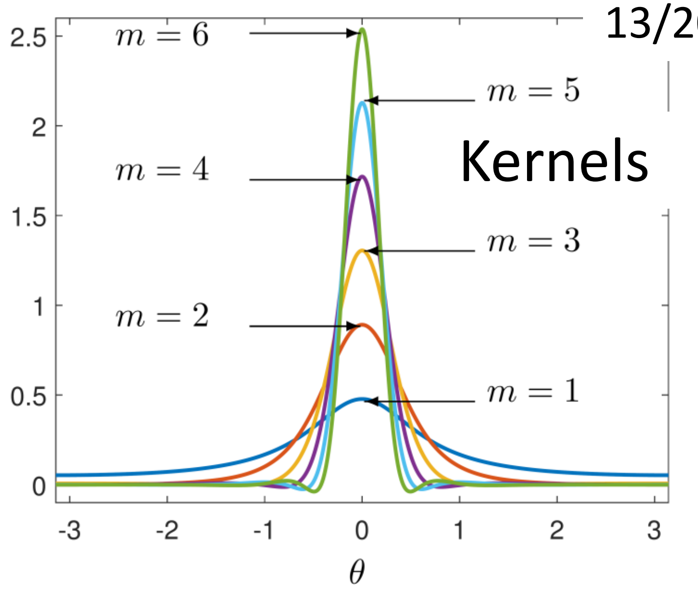
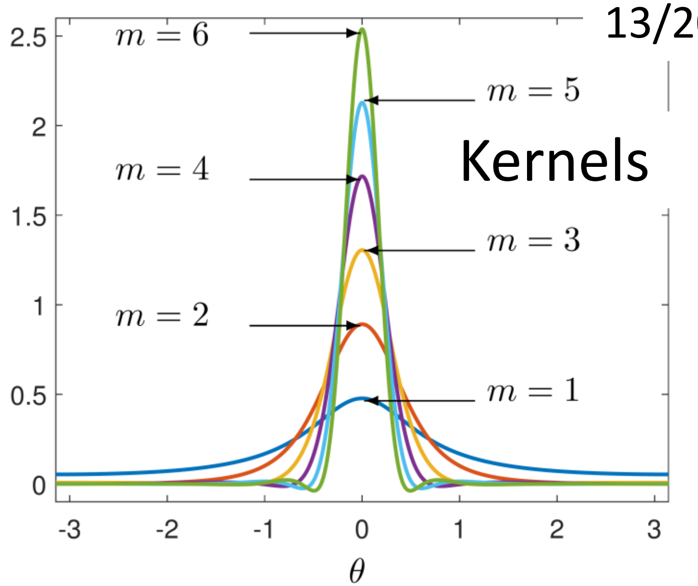
Computing ν_g diagonalises non-linear dynamical system!

Smoothing via convolution

$$K_\varepsilon(\theta) = \frac{e^{-i\theta}}{2\pi} \sum_{j=1}^{m} \left[\frac{c_j}{e^{-i\theta} - (1 + \varepsilon \overline{z_j})^{-1}} - \frac{d_j}{e^{-i\theta} - \left(1 + \varepsilon z_j\right)} \right]$$

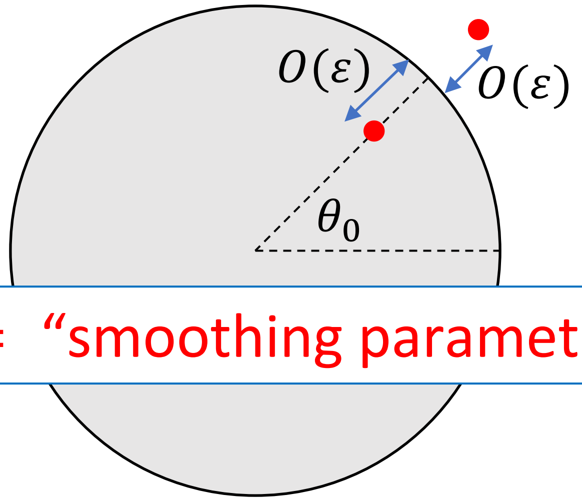


Smoothing via convolution



$$K_\varepsilon(\theta) = \frac{e^{-i\theta}}{2\pi}\sum_{j=1}^{m}\left[\frac{c_j}{e^{-i\theta}-(1+\varepsilon\overline{z_j})^{-1}} - \frac{d_j}{e^{-i\theta}-(1+\varepsilon z_j)}\right]$$

$$[K_\varepsilon * \nu_g](\theta_0) = \sum_{j=1}^{m}\left[c_j\mathcal{C}_g\left(e^{i\theta_0}(1+\varepsilon\overline{z_j})^{-1}\right) - d_j\mathcal{C}_g\left(e^{i\theta_0}(1+\varepsilon z_j)\right)\right]$$



$\varepsilon =$ "smoothing parameter"

$$\mathcal{C}_g(z) = \int_{-\pi}^{\pi}\frac{e^{i\theta}\mathrm{d}\nu_g(\theta)}{e^{i\theta}-z} = \begin{cases} \langle(\mathcal{K}-zI)^{-1}g, \mathcal{K}^*g\rangle, \text{if } |z|>1 \\ -z^{-1}\langle g, (\mathcal{K}-\bar{z}^{-1}I)^{-1}g\rangle, \text{if } 0<|z|<1 \end{cases}$$

ResDMD computes with error control

Convergence

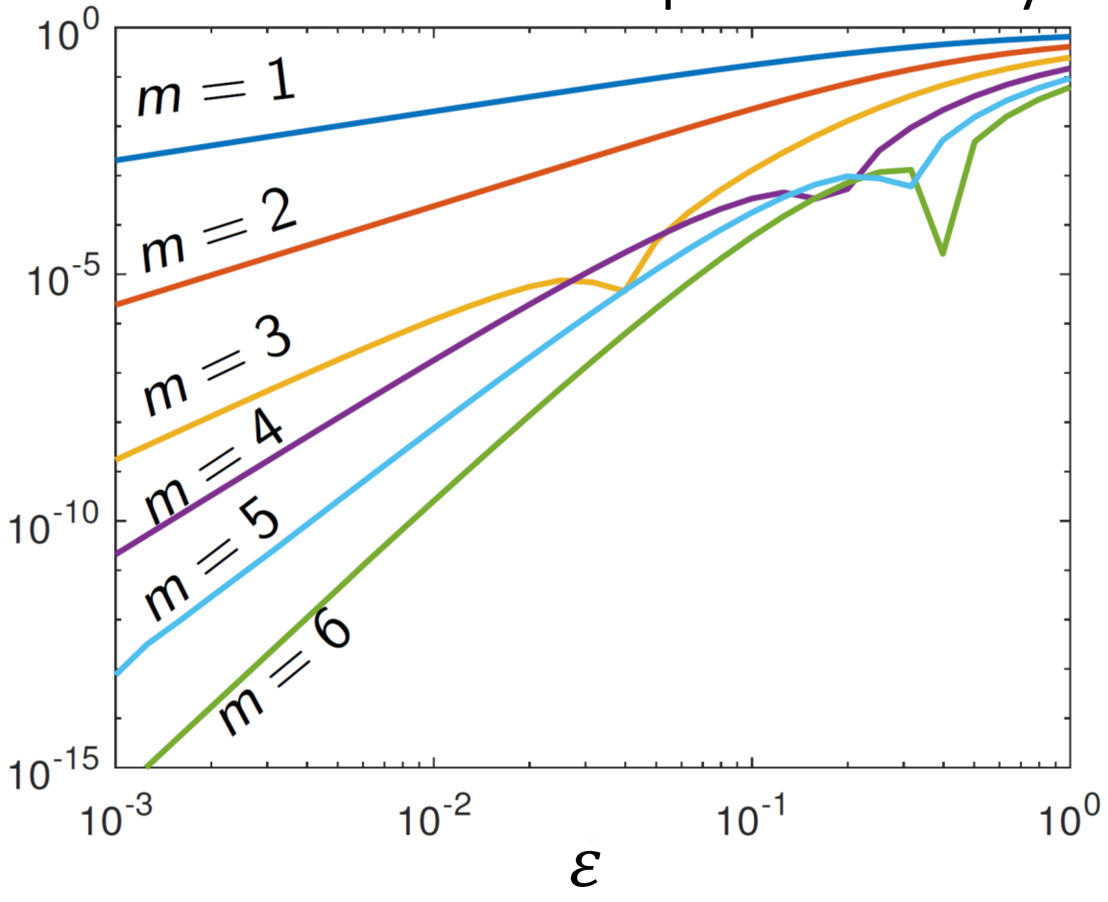
Theorem: *Automatic* selection of $N_K(\varepsilon)$ with $O(\varepsilon^m \log(1/\varepsilon))$ convergence:

- Density of continuous spectrum ρ_g.
  (pointwise and L^p)
- Integration against test functions.
  (weak convergence)

$$\int_{-\pi}^{\pi} h(\theta)\left[K_\varepsilon * \nu_g\right](\theta)\,\mathrm{d}\theta$$
$$= \int_{-\pi}^{\pi} h(\theta)\;\mathrm{d}\nu_g(\theta) + O(\varepsilon^m \log(1/\varepsilon))$$

Also recover discrete spectrum.

Pointwise error for spectral density



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Large d ($\Omega \subseteq \mathbb{R}^d$): *robust* and *scalable*

Popular to learn dictionary $\{\psi_1, \dots, \psi_{N_K}\}$

E.g., DMD with truncated SVD (linear dictionary, most popular), kernel methods (this talk), neural networks, etc.

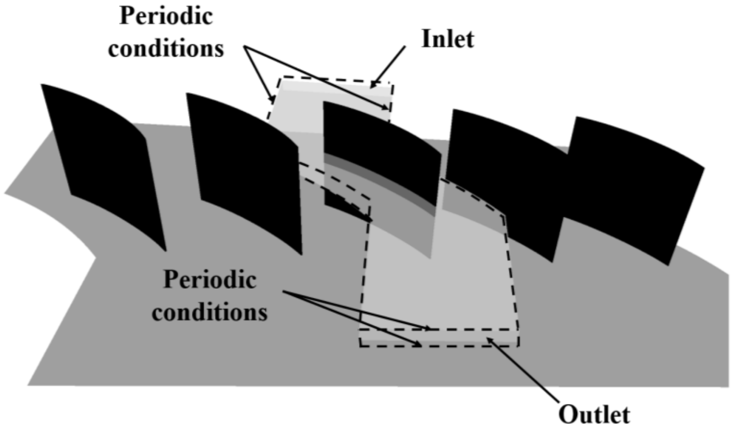
Q: Is discretisation $\mathrm{span}\{\psi_1, \dots, \psi_{N_K}\}$ large/rich enough?

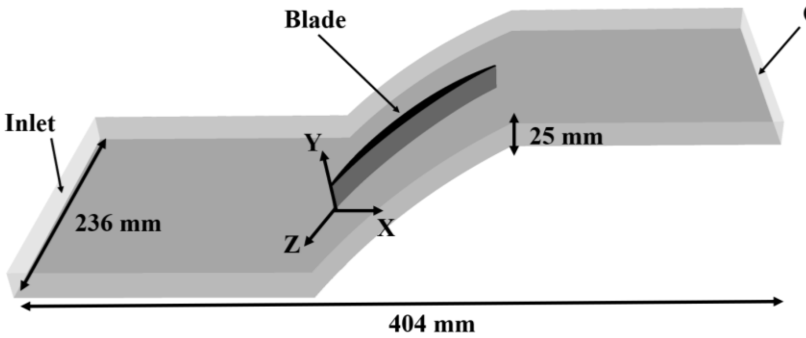
Above algorithms:

- Pseudospectra: $\{z_k : \tau_k < \varepsilon\} \subseteq \mathrm{Spec}_\varepsilon(\mathcal{K})$ **error control**
- Spectral measures: $\mathcal{C}_g(z)$ and smoothed measures **adaptive check**

$\Longrightarrow$ Rigorously ***verify*** learnt dictionary $\{\psi_1, \dots, \psi_{N_K}\}$

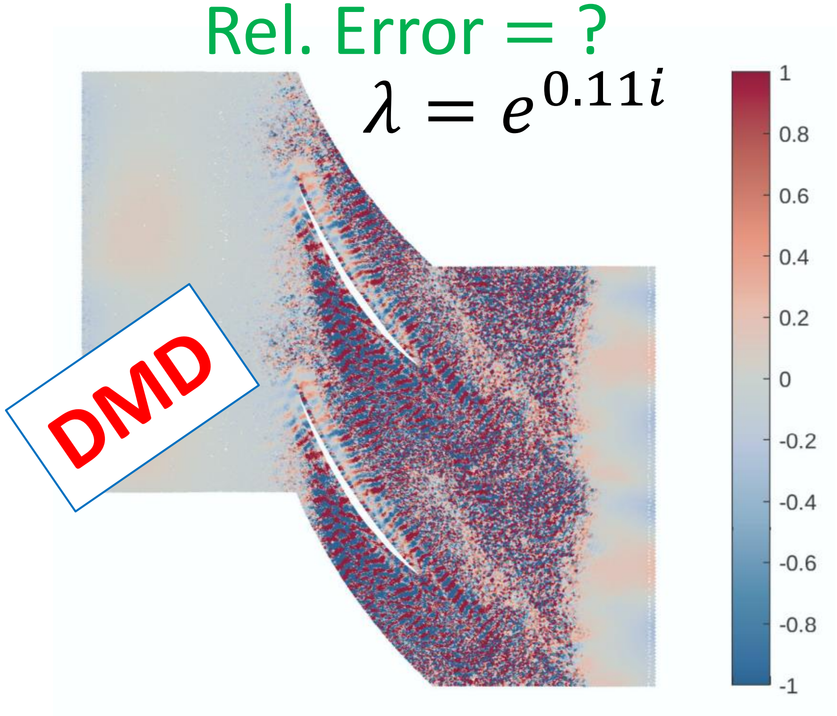
Example: Trustworthy computation for large d

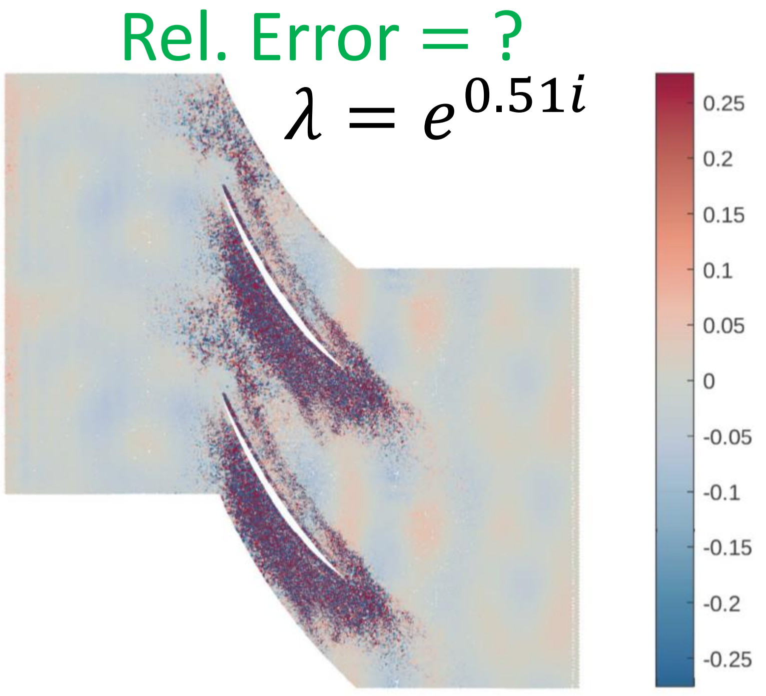


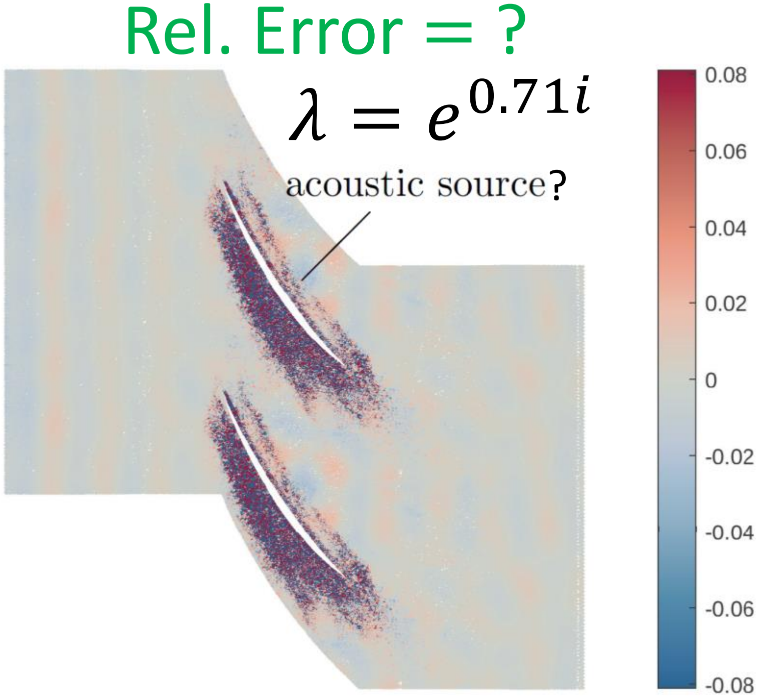


- Reynolds number $\approx 3.9 \times 10^5$
- Ambient dimension (d) $\approx 300{,}000$ (number of measurement points)

*Raw measurements provided by Stephane Moreau (Sherbrooke)







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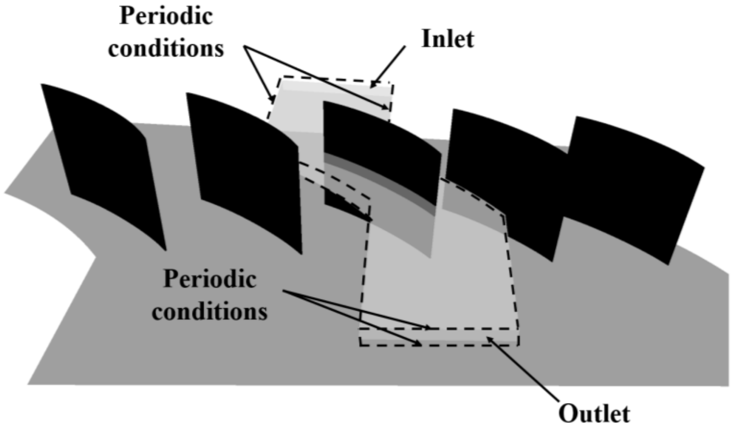

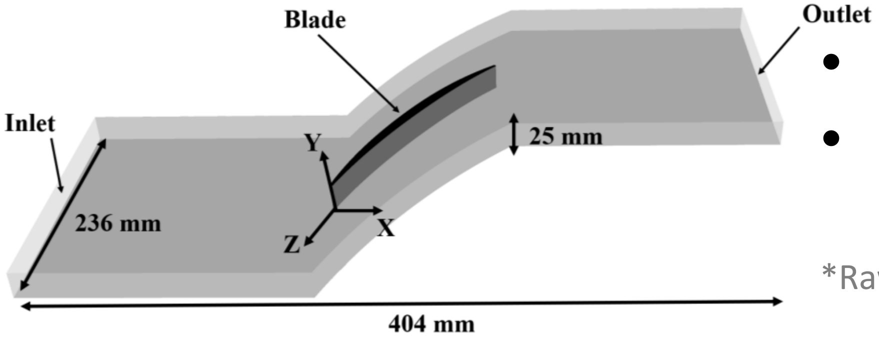

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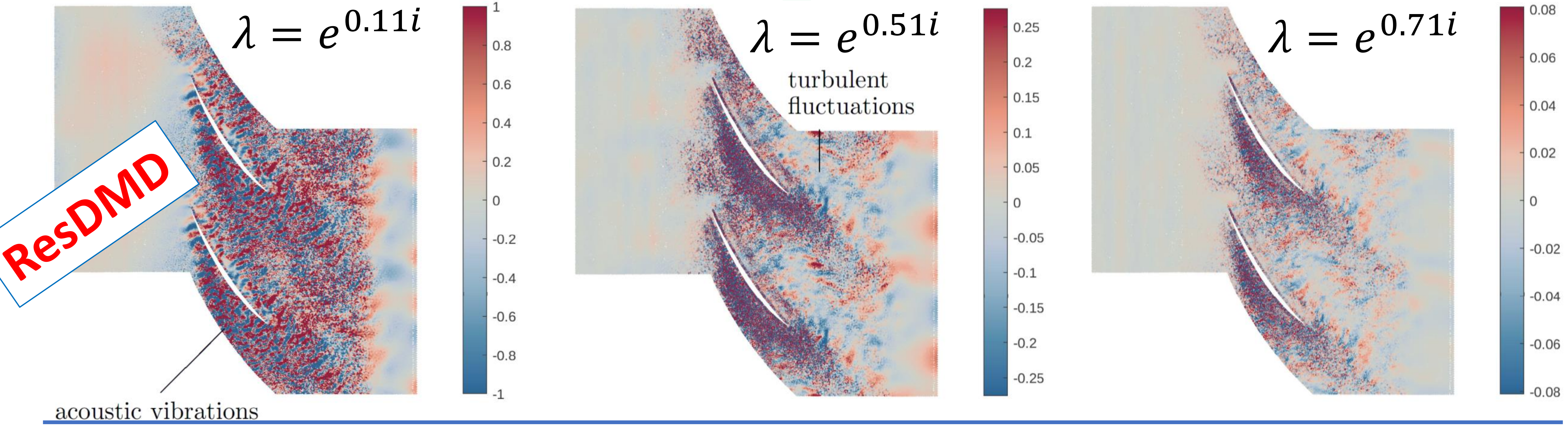
Rel. Error ≤ 0.0054 Rel. Error ≤ 0.0128 Rel. Error ≤ 0.0196



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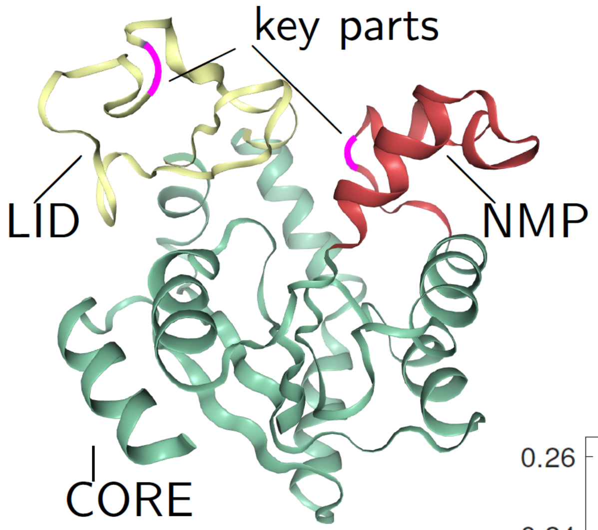
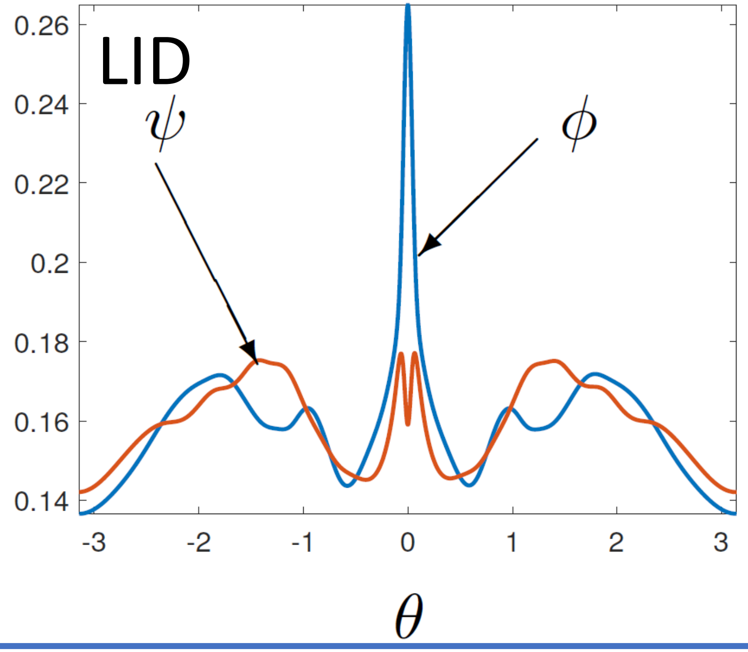
Example: molecular dynamics (Adenylate Kinase)

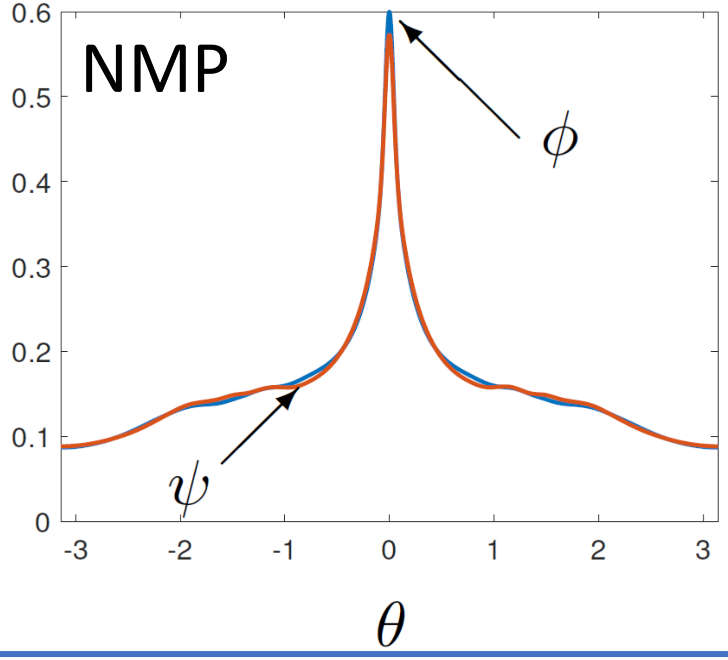
Adenylate Kinase



- Ambient dimension (d) $\approx 20{,}000$ (positions and momenta of atoms)
- 6th order kernel (spec res 10^{-6})

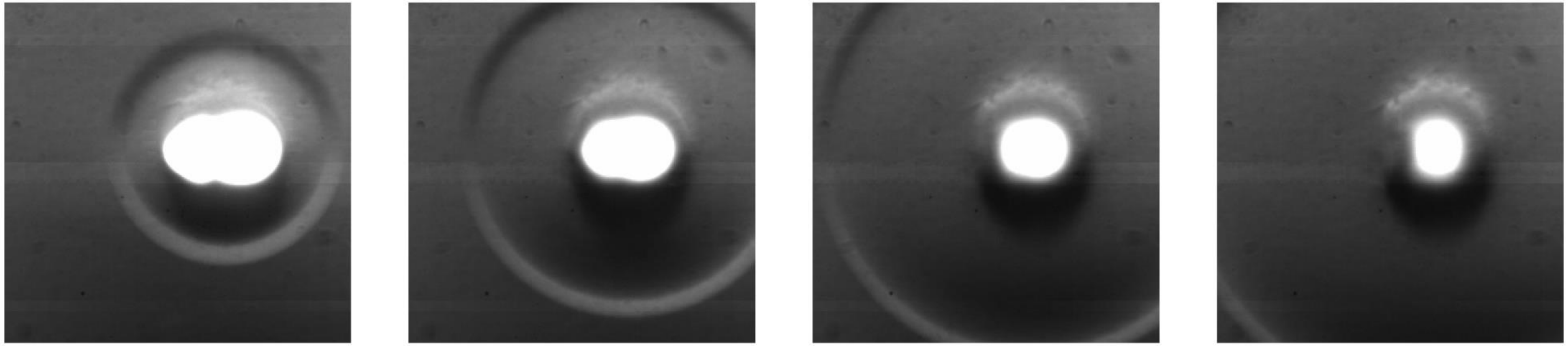
*Dataset: www.mdanalysis.org/MDAnalysisData/adk_equilibrium.html



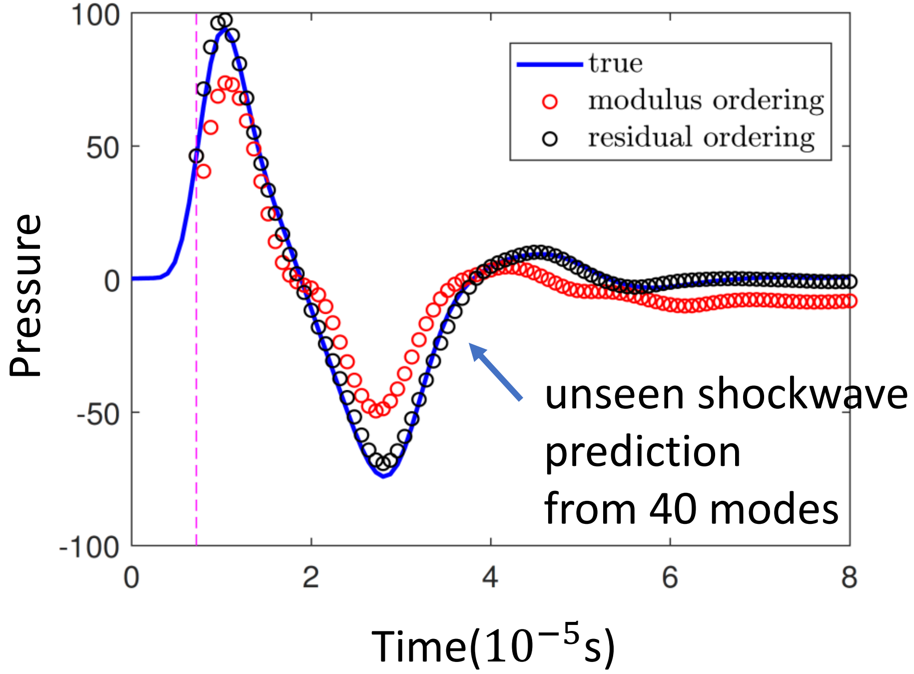


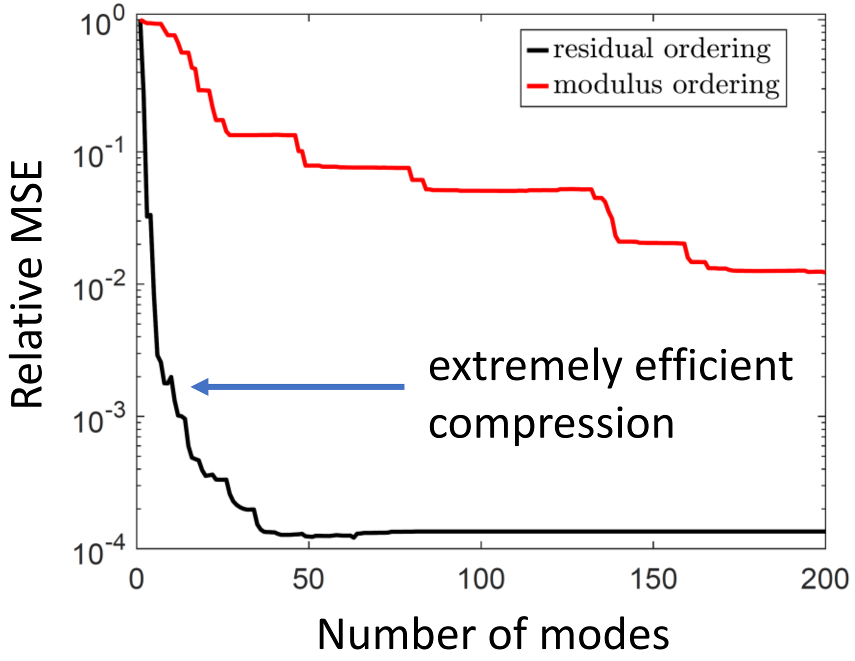
- C., T., *"Rigorous data-driven computation of spectral properties of Koopman operators for dynamical systems,"* preprint.

Example: Trustworthy Koopman mode decomposition



a) $t = 5\ \mu$s　b) $t = 10\ \mu$s　c) $t = 15\ \mu$s　d) $t = 20\ \mu$s





- C., Ayton, Szőke, "*Residual Dynamic Mode Decomposition,*" **J. Fluid Mech.,** under minor rev.

Wider programme

- Inf.-dim. computational analysis $\Longrightarrow$ **Compute spectral properties rigorously.**
- Continuous linear algebra $\Longrightarrow$ **Avoid the woes of discretisation**
- Solvability Complexity Index hierarchy $\Longrightarrow$ **Classify diff. of comp. problems, prove algs are optimal.**
- **Extends to:** Foundations of AI, optimization, computer-assisted proofs, and PDEs etc.

- C., *"On the computation of geometric features of spectra of linear operators on Hilbert spaces,"* **Found. Comput. Math.**, to appear.
- C., *"Computing spectral measures and spectral types,"* **Comm. Math. Phys.,** 2021.
- C., Horning, Townsend *"Computing spectral measures of self-adjoint operators,"* **SIAM Rev.**, 2021.
- C., Roman, Hansen, *"How to compute spectra with error control,"* **Phys. Rev. Lett.**, 2019.
- C., Hansen, *"The foundations of spectral computations via the solvability complexity index hierarchy,"* **J. Eur. Math. Soc.**, 2022.
- C., Antun, Hansen, "*The difficulty of computing stable and accurate neural networks: On the barriers of deep learning and Smale's 18th problem,*" **Proc. Natl. Acad. Sci. USA**, 2022.
- C., *"Computing semigroups with error control,"* **SIAM J. Numer. Anal.**, 2022.
- Ben-Artzi, C., Hansen, Nevanlinna, Seidel, *"On the solvability complexity index hierarchy and towers of algorithms,"* arXiv, 2020.
- Smale, *"The fundamental theorem of algebra and complexity theory,"* **Bull. Amer. Math. Soc.**, 1981, *36 pp.*
- McMullen, *"Families of rational maps and iterative root-finding algorithms,"* **Ann. of Math.**, 1987, *27 pp.*

Summary: rigorous data-driven Koopmanism!

- “Too much” or “Too little”

  Idea: New matrix for residual ⇒ **ResDMD** for computing spectra.

- Continuous spectra and spectral measures:

  Idea: Convolution with rational kernels via resolvent and **ResDMD**.

- Verification

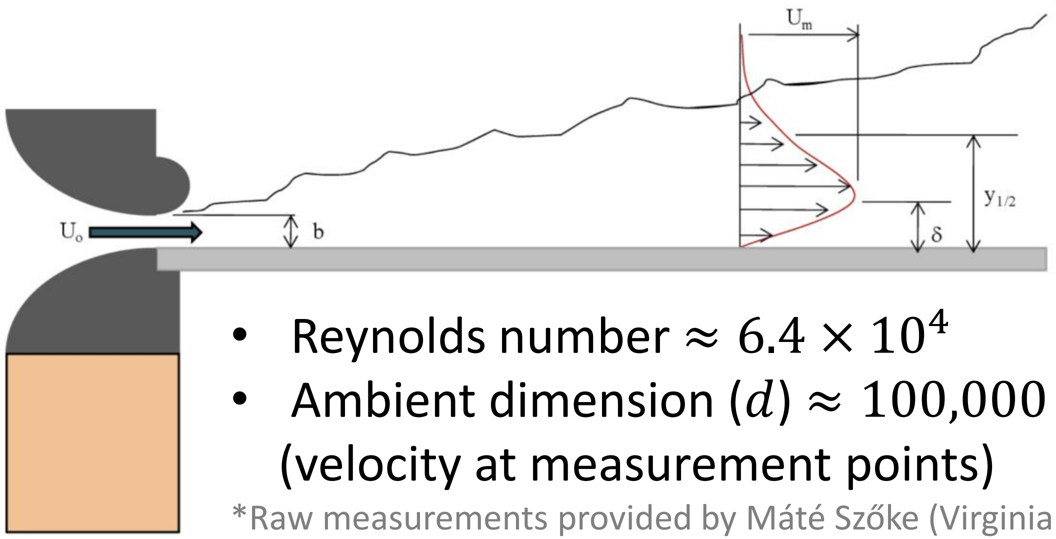
  Idea: Use **ResDMD** to verify computations. E.g., learned dictionaries.

Code:

https://github.com/MColbrook/Residual-Dynamic-Mode-Decomposition

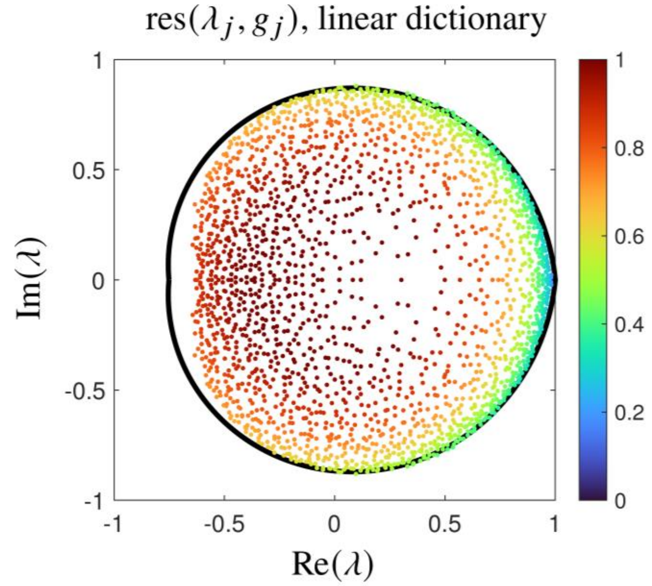
Additional slides…

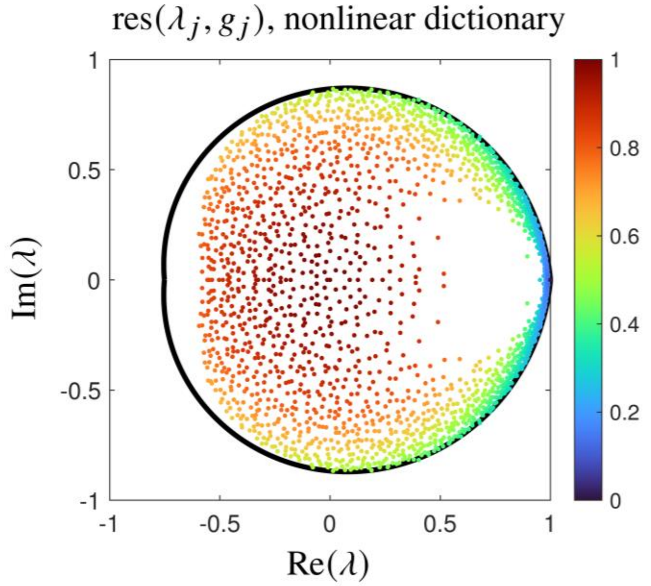
Example: Verify the dictionary



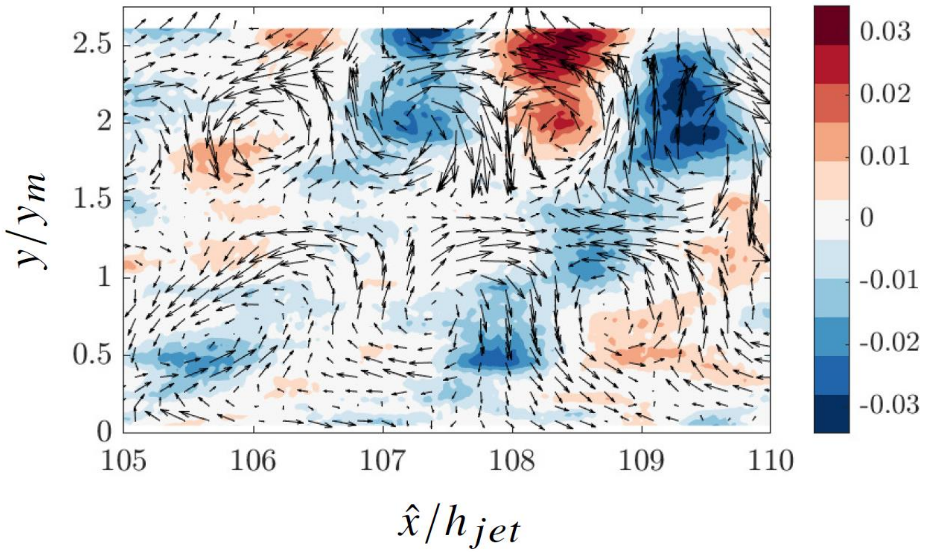
- Reynolds number $\approx 6.4 \times 10^4$
- Ambient dimension (d) $\approx 100{,}000$ (velocity at measurement points)

*Raw measurements provided by Máté Szőke (Virginia Te

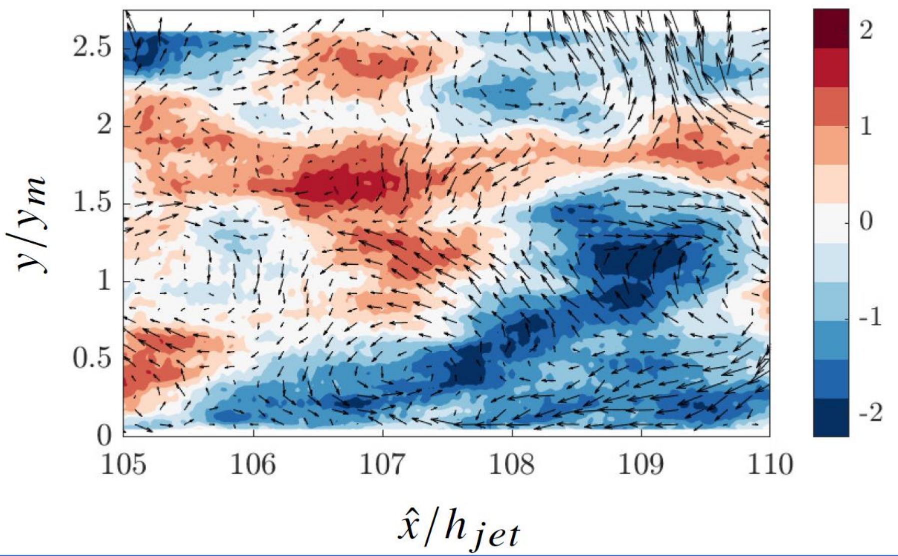




$\lambda = 0.9439 + 0.2458i$, error ≤ 0.0765



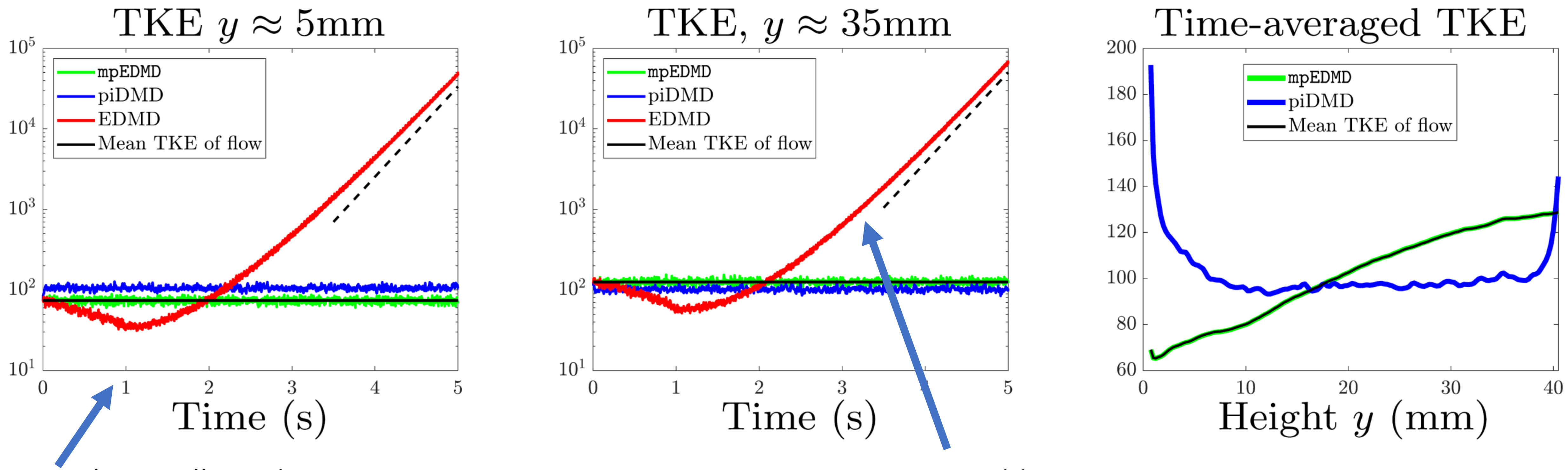
$\lambda = 0.8948 + 0.1065i$, error ≤ 0.1105



- C., Ayton, Szőke, *"Residual Dynamic Mode Decomposition,"* **J. Fluid Mech.**, under minor rev.

measure-preserving EDMD…

- Polar decomposition of $\mathcal{K}$. Easy to combine with any DMD-type method!
- Converges for spectral measures, spectra, Koopman mode decomposition.
- Measure-preserving discretization for arbitrary measure-preserving systems.



Snapshots collected over 1s

EDMD unstable!

- C., *“The mpEDMD Algorithm for Data-Driven Computations of Measure-Preserving Dynamical Systems,”* arXiv 2022.

Convergence of quadrature

E.g., $\langle \mathcal{K}\psi_k, \psi_j \rangle = \lim_{M\to\infty} \sum_{m=1}^{M} w_m \overline{\psi_j(x^{(m)})} \underbrace{\psi_k(y^{(m)})}_{[\mathcal{K}\psi_k](x^{(m)})}$

Three examples:

- **High-order quadrature:** $\{x^{(m)}, w_m\}_{m=1}^{M}$ M-point quadrature rule.
  Rapid convergence. Requires free choice of $\{x^{(m)}\}_{m=1}^{M}$ and small d.
- **Random sampling:** $\{x^{(m)}\}_{m=1}^{M}$ selected at random.
  Large d. Slow Monte Carlo $O(M^{-1/2})$ rate of convergence.
- **Ergodic sampling:** $x^{(m+1)} = F(x^{(m)})$.
  Single trajectory, large d. Requires ergodicity, convergence can be slow.

Most common

Solvability Complexity Index Hierarchy

Class $\Omega \ni A$, want to compute $\Xi: \Omega \to (\mathcal{M}, d)$ metric space

- Δ_0: Problems solved in finite time (v. rare for cts problems).
- Δ_1: Problems solved in "one limit" with full error control:

$$d(\Gamma_n(A), \Xi(A)) \le 2^{-n}$$

- Δ_2: Problems solved in "one limit":

$$\lim_{n\to\infty} \Gamma_n(A) = \Xi(A)$$

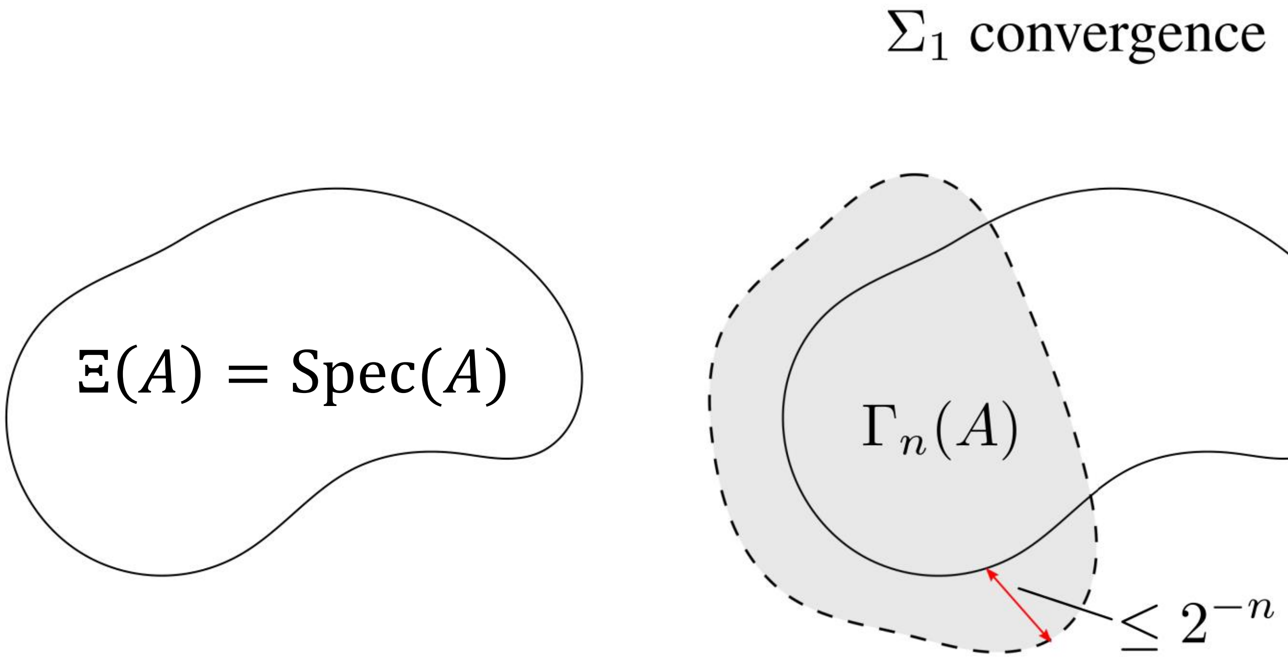
- Δ_3: Problems solved in "two successive limits":

$$\lim_{n\to\infty} \lim_{m\to\infty} \Gamma_{n,m}(A) = \Xi(A)$$

⋮

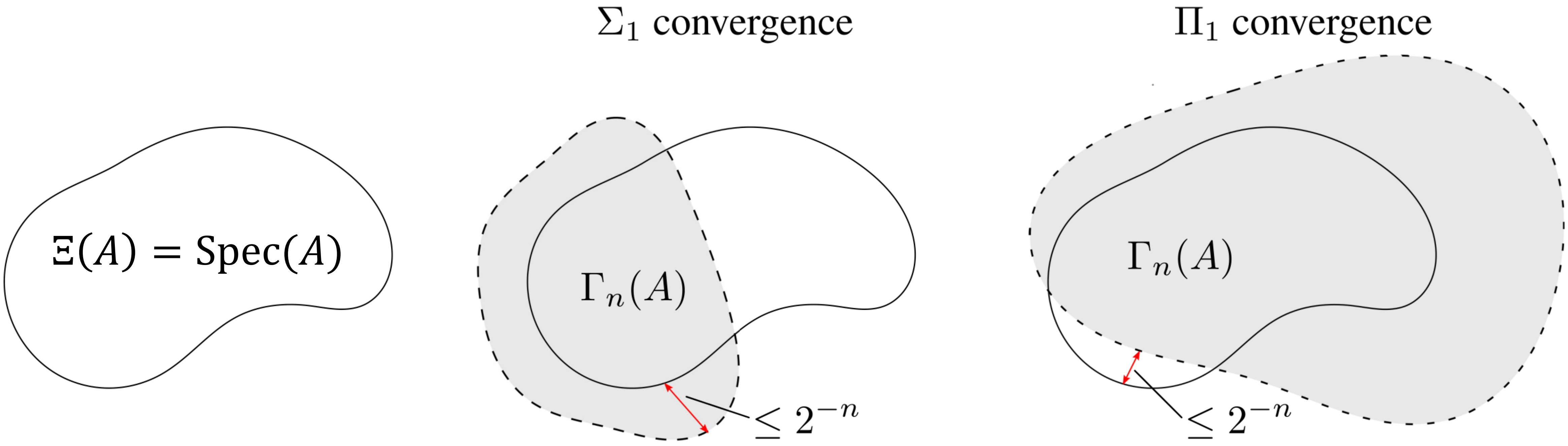
- Ben-Artzi, C., Hansen, Nevanlinna, Seidel, "*On the solvability complexity index hierarchy and towers of algorithms,*" preprint.
- Hansen, "*On the solvability complexity index, the n-pseudospectrum and approximations of spectra of operators,*" **J. Amer. Math. Soc.**, 2011.
- McMullen, "*Families of rational maps and iterative root-finding algorithms,*" **Ann. of Math.**, 1987.
- Doyle, McMullen, "*Solving the quintic by iteration,*" **Acta Math.**, 1989.
- Smale, "*The fundamental theorem of algebra and complexity theory,*" **Bull. Amer. Math. Soc.**, 1981.

Error control for spectral problems



- Σ_1: $\exists$ alg. $\{\Gamma_n\}$ s.t. $\lim_{n\to\infty} \Gamma_n(A) = \Xi(A)$, $\max_{z\in\Gamma_n(A)} \mathrm{dist}\big(z, \Xi(A)\big) \leq 2^{-n}$

Error control for spectral problems



- Σ_1: $\exists$ alg. $\{\Gamma_n\}$ s.t. $\lim_{n\to\infty} \Gamma_n(A) = \Xi(A)$, $\max_{z\in\Gamma_n(A)} \mathrm{dist}\big(z, \Xi(A)\big) \leq 2^{-n}$
- Π_1: $\exists$ alg. $\{\Gamma_n\}$ s.t. $\lim_{n\to\infty} \Gamma_n(A) = \Xi(A)$, $\max_{z\in\Xi(A)} \mathrm{dist}(z, \Gamma_n(A)) \leq 2^{-n}$

Such problems can be used in a proof!

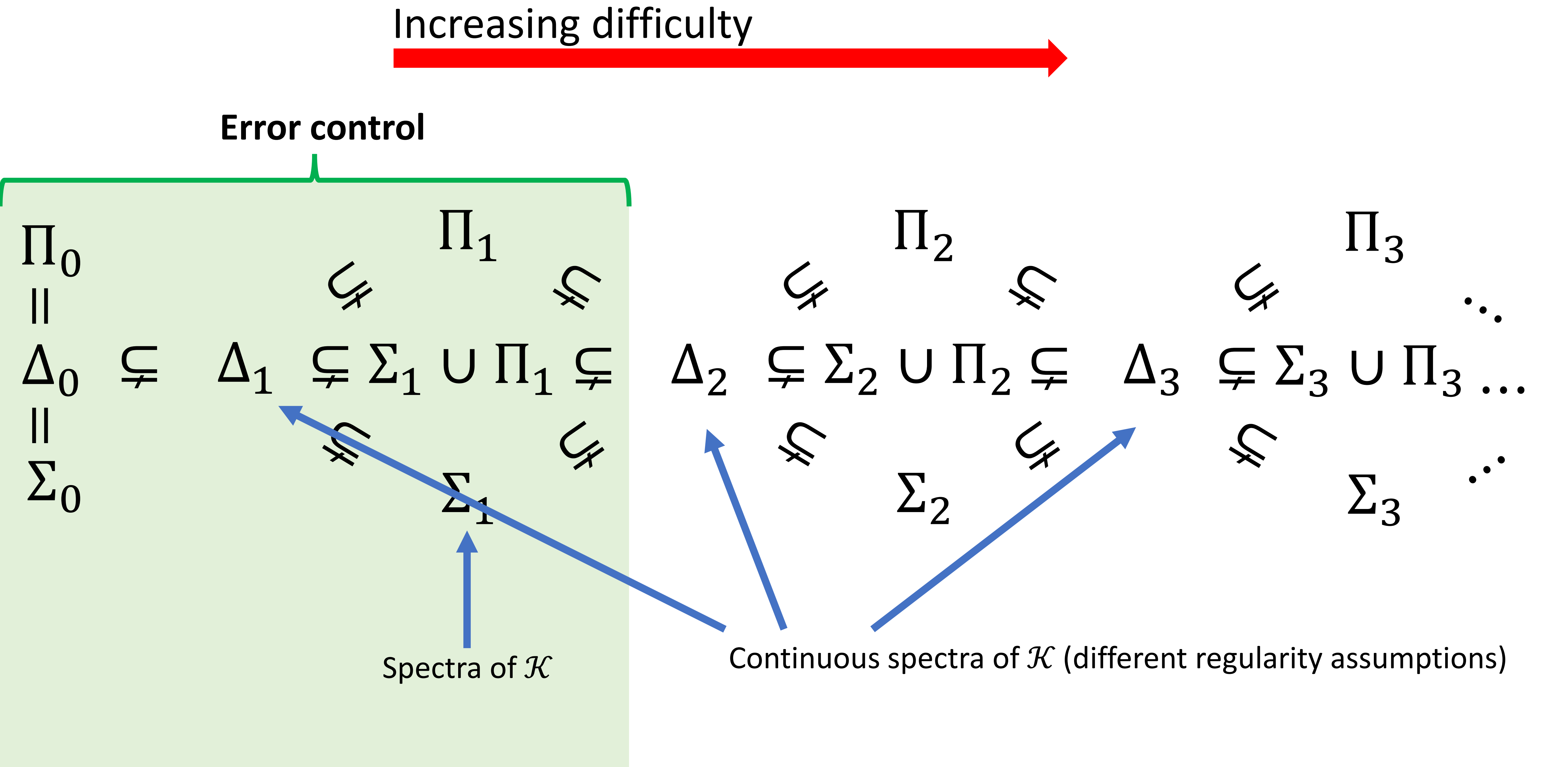
Small sample of classification theorems

Increasing difficulty

Error control

$$\begin{array}{ccccccccccccccc}
\Pi_0 & & & & & & \Pi_1 & & & & \Pi_2 & & & & \Pi_3 \\
\| & & & & & \subsetneq & & \subsetneq & & \subsetneq & & \subsetneq & & \subsetneq & & \ddots \\
\Delta_0 & \subsetneq & \Delta_1 & \subsetneq & \Sigma_1 \cup \Pi_1 & \subsetneq & & \Delta_2 & \subsetneq & \Sigma_2 \cup \Pi_2 & \subsetneq & \Delta_3 & \subsetneq & \Sigma_3 \cup \Pi_3 & \ldots \\
\| & & & & & \subsetneq & & \subsetneq & & \subsetneq & & \subsetneq & & \subsetneq & & \iddots \\
\Sigma_0 & & & & & & \Sigma_1 & & & & \Sigma_2 & & & & \Sigma_3
\end{array}$$

Small sample of classification theorems



Small sample of classification theorems

Increasing difficulty

Error control

Spectra of compact operators

$$\begin{array}{ccccccccccccccc}
\Pi_0 & & & & & \Pi_1 & & & & \Pi_2 & & & & \Pi_3 & \\
\| & & & \rotatebox{45}{$\subsetneq$} & & & \rotatebox{-45}{$\subsetneq$} & & \rotatebox{45}{$\subsetneq$} & & \rotatebox{-45}{$\subsetneq$} & & \rotatebox{45}{$\subsetneq$} & & \ddots \\
\Delta_0 & \subsetneq & \Delta_1 & \subsetneq & \Sigma_1 \cup \Pi_1 & & \subsetneq & \Delta_2 & \subsetneq & \Sigma_2 \cup \Pi_2 & \subsetneq & \Delta_3 & \subsetneq & \Sigma_3 \cup \Pi_3 & \ldots \\
\| & & & \rotatebox{-45}{$\subsetneq$} & & & \rotatebox{45}{$\subsetneq$} & & \rotatebox{-45}{$\subsetneq$} & & \rotatebox{45}{$\subsetneq$} & & \rotatebox{-45}{$\subsetneq$} & & \iddots \\
\Sigma_0 & & & & & \Sigma_1 & & & & \Sigma_2 & & & & \Sigma_3 &
\end{array}$$

Spectra of $\mathcal{K}$

Continuous spectra of $\mathcal{K}$ (different regularity assumptions)

Small sample of classification theorems

Increasing difficulty

Error control

Spectra of compact operators

Spectra of Schrödinger* (different potential classes)

$$\begin{array}{cccccccccccccc}
\Pi_0 & & & & \Pi_1 & & & & \Pi_2 & & & & \Pi_3 & \\
\| & & & \rotatebox{45}{$\subsetneq$} & & \rotatebox{-45}{$\subsetneq$} & & \rotatebox{45}{$\subsetneq$} & & \rotatebox{-45}{$\subsetneq$} & & \rotatebox{45}{$\subsetneq$} & & \iddots \\
\Delta_0 & \subsetneq & \Delta_1 & \subsetneq & \Sigma_1 \cup \Pi_1 & \subsetneq & \Delta_2 & \subsetneq & \Sigma_2 \cup \Pi_2 & \subsetneq & \Delta_3 & \subsetneq & \Sigma_3 \cup \Pi_3 & \dots \\
\| & & & \rotatebox{-45}{$\subsetneq$} & & \rotatebox{45}{$\subsetneq$} & & \rotatebox{-45}{$\subsetneq$} & & \rotatebox{45}{$\subsetneq$} & & \rotatebox{-45}{$\subsetneq$} & & \ddots \\
\Sigma_0 & & & & \Sigma_1 & & & & \Sigma_2 & & & & \Sigma_3 &
\end{array}$$

Spectra of $\mathcal{K}$

Continuous spectra of $\mathcal{K}$ (different regularity assumptions)

*_Open problem of Schwinger_: "The special canonical group," "Unitary operator bases," PNAS, 1960.

Small sample of classification theorems

Increasing difficulty

Error control

Spectra of compact operators

Spectra of Schrödinger* (different potential classes)

$$\begin{array}{cccccccccccccc}
\Pi_0 & & & \rotatebox{45}{$\subsetneq$} & \Pi_1 & \rotatebox{-45}{$\subsetneq$} & & \rotatebox{45}{$\subsetneq$} & \Pi_2 & \rotatebox{-45}{$\subsetneq$} & & \rotatebox{45}{$\subsetneq$} & \Pi_3 & \iddots \\
\| & & & & & & & & & & & & & \\
\Delta_0 & \subsetneq & \Delta_1 & \subsetneq & \Sigma_1 \cup \Pi_1 & \subsetneq & \Delta_2 & \subsetneq & \Sigma_2 \cup \Pi_2 & \subsetneq & \Delta_3 & \subsetneq & \Sigma_3 \cup \Pi_3 & \ldots \\
\| & & & & & & & & & & & & & \\
\Sigma_0 & & & \rotatebox{-45}{$\subsetneq$} & \Sigma_1 & \rotatebox{45}{$\subsetneq$} & & \rotatebox{-45}{$\subsetneq$} & \Sigma_2 & \rotatebox{45}{$\subsetneq$} & & \rotatebox{-45}{$\subsetneq$} & \Sigma_3 & \ddots
\end{array}$$

Spectra of $\mathcal{K}$

Spectral gap problem

Continuous spectra of $\mathcal{K}$ (different regularity assumptions)

**Open problem of Schwinger*: "The special canonical group," "Unitary operator bases," PNAS, 1960.

Small sample of classification theorems

Increasing difficulty

Error control

Spectra of compact operators

Spectra of Schrödinger* (different potential classes)

Spectral stability

$$
\begin{array}{ccccccccccccccc}
\Pi_0 & & & & \Pi_1 & & & & \Pi_2 & & & & \Pi_3 & & \\
\| & & & \rotatebox{-45}{$\subsetneq$} & & \rotatebox{45}{$\supsetneq$} & & \rotatebox{-45}{$\subsetneq$} & & \rotatebox{45}{$\supsetneq$} & & \rotatebox{-45}{$\subsetneq$} & & & \ddots \\
\Delta_0 & \subsetneq & \Delta_1 & \subsetneq & \Sigma_1 \cup \Pi_1 & \subsetneq & \Delta_2 & \subsetneq & \Sigma_2 \cup \Pi_2 & \subsetneq & \Delta_3 & \subsetneq & \Sigma_3 \cup \Pi_3 & \ldots & \\
\| & & & \rotatebox{45}{$\subsetneq$} & & \rotatebox{-45}{$\supsetneq$} & & \rotatebox{45}{$\subsetneq$} & & \rotatebox{-45}{$\supsetneq$} & & \rotatebox{45}{$\subsetneq$} & & & \cdot^{\cdot^{\cdot}} \\
\Sigma_0 & & & & \Sigma_1 & & & & \Sigma_2 & & & & \Sigma_3 & &
\end{array}
$$

Spectral gap problem

Spectra of $\mathcal{K}$

Continuous spectra of $\mathcal{K}$ (different regularity assumptions)

**Open problem of Schwinger*: "The special canonical group," "Unitary operator bases," PNAS, 1960.