

Exercise Sheet 1 Solutions

Intro to OT

Cont 2018-2019

1.1 Let $B \subseteq \mathbb{R}$. Then

$$\int_{\mathbb{R}} \mathbb{1}_B d\mu = \mu(T_1^{-1}(B))$$

$$= \int_{T_1^{-1}(B)} \chi_{\text{Cont}}(x) dx$$

$$= \int_{T_1^{-1}(B) \cap \text{Cont}} 1 dx$$

$$= \int_{B \cap (1,2]} 1 dy \quad [\text{change of variables, } y = T_1(x) = x+1]$$

$$= \int_B \chi_{\text{Cont}}(y) dy$$

$$= \nu(B).$$

To show $\int_{\mathbb{R}} \mu \neq \nu$ choose $B = [0, 1/2]$. Then

$$\int_{\mathbb{R}} \mu(B) = \mu(S^{-1}(B)) = \mu([0, 1/2]) = 1/2$$

$$\text{and } \nu(B) = \nu([0, 1/2]) = 0.$$

1.2 Assume $\pi = (\mathbb{P}_A \times \mathbb{P})_{\#} \mu$. Let $P(x,y) = x$ then for $B \subseteq$

$$\int_{\mathbb{R}} \pi(B) = \pi(P^{-1}(B)) = \pi(\{(x,y) \in X \times Y : P(x,y) \in B\})$$

$$= \pi(\{(x,y) \in X \times Y : x \in B\}) = \pi(B \times Y)$$

$$= \mu((\mathbb{P}_A \times \mathbb{P})^{-1}(\underbrace{B \times Y}_{\text{Cont}}))$$

$$= \mu \left(\{x : (F \circ F)(x) \in B \times Y\} \right)$$

$$= \mu \left(\{x : x \in B \text{ and } F(x) \in Y\} \right)$$

$$= \mu(B)$$

By disintegration of measures (Thm 1.4) \exists a family $\pi(\cdot|x)$,

$x \in X$ s.t.

$$\int_{X \times Y} F(x,y) d\pi(x,y) = \int_X \int_{X \times Y} F(x,y) d\pi(y|x) d\mu(x)$$

\forall measurable $F: X \times Y \rightarrow [0, \infty]$. Choose $F(x,y) = G(x) \chi_B(y)$. Then we have

$$\int_{X \times Y} G(x) \chi_B(y) d\pi(x,y) = \int_X G(x) \pi(B|x) d\mu(x) \quad (1)$$

By the change of variable formula (Prop 2.3) the left hand side can be written

$$\int_{X \times Y} G(x) \chi_B(y) d\pi(x,y) = \int_{X \times Y} G(x) \chi_B(y) d(F \circ F)_\# \mu(x,y)$$

$$= \int_X G(x) \chi_B(F(x)) d\mu(x) \quad (2)$$

Comparing (1) and (2) we have $\pi(B|x) = \chi_B(F(x))$ for μ -a.e. $x \in X$.

Hence $\pi(\cdot|x) = \delta_{F(x)}$ as required.

[Alternative proof: check $\pi(\cdot|x) = \delta_{F(x)}$ satisfies the disintegration of measures theorem.]

1.43

Assum $\nu = \tau_{\#} \mu$. Let $\varphi: X \rightarrow \mathbb{R}^2$ be measurable + bounded

$$\begin{aligned} \int_Y \varphi(y) d\nu(y) &= \int_Y \varphi(y) d(\tau_{\#} \mu)(y) \\ &= \int_X \varphi(\tau(x)) d\mu(x) \quad \text{by prop 1.5} \\ &\quad \wedge \text{ as stand.} \end{aligned}$$

On the other hand, if $\int_Y \varphi(y) d\nu(y) = \int_X \varphi(\tau(x)) d\mu(x)$
for all bounded and measurable φ then we choose
 $\varphi = \chi_B$. So

$$\begin{aligned} \nu(B) &= \int_Y \varphi(y) d\nu(y) = \int_X \varphi(\tau(x)) d\mu(x) \\ &= \int_X \chi_B(\tau(x)) d\mu(x) \\ &= \mu(\{x : \tau(x) \in B\}) \\ &= \tau_{\#} \mu(B). \end{aligned}$$

then $\nu = \tau_{\#} \mu$ as required.

1.84

Assume $\nu = T_{\#} \mu$. Then

$$\int_Y F(y) d\nu(y) = \int_Y F(y) dT_{\#} \mu(y) \quad \forall F: Y \rightarrow [0, \infty] \text{ measurable.}$$

By change of variables (Prop 2.3)

$$\begin{aligned} \int_Y F(y) dT_{\#} \mu(y) &= \int_X F(T(x)) d\mu(x) \\ &= \int_X F(T(x)) f(x) dx \end{aligned}$$

On the other hand

$$\begin{aligned} \int_Y F(y) d\nu(y) &= \int_Y F(y) g(y) dy \\ &= \int_{T^{-1}(Y)} F(T(x)) g(T(x)) |\det(DT(x))| dx \quad \begin{array}{l} \text{by using a} \\ \text{change of variables} \\ y = T(x) \end{array} \\ &= \int_X F(T(x)) g(T(x)) |\det(DT(x))| dx \quad \text{since } X = T^{-1}(Y) \end{aligned}$$

Since this holds for all F measurable, we have

$$f(x) = g(T(x)) |\det(DT(x))| \quad \text{for } \mu \text{ a.e. } x \in X.$$

Since the argument holds in reverse we have that

$$f(x) = g(T(x)) |\det(DT(x))| \quad \text{implies} \quad \nu = T_{\#} \mu.$$

1.5 Hence, (when $x=a=1$)

$$\begin{aligned}\int_x \varphi\left(\frac{1}{2}(x)\right) d\mu(b) &= \int_0^1 \varphi\left(\frac{1}{2}(2-x)\right) dx \\ &= \int_1^2 \varphi(y) dy \quad (\text{since } y = \frac{1}{2}(2-x) = 2-x) \\ &= \int_Y \varphi(y) d\omega(y)\end{aligned}$$

$$\begin{aligned}\int_x \varphi\left(\frac{1}{3}(x)\right) d\mu(b) &= \int_0^{1/2} \varphi\left(x + \frac{2}{3}\right) dx + \int_{1/2}^1 \varphi(2-x) dx \\ &= \int_{3/2}^2 \varphi(y) dy + \int_1^{3/2} \varphi(y) dy \\ &= \int_1^2 \varphi(y) dy \\ &= \int_Y \varphi(y) d\omega(y)\end{aligned}$$

$$\text{So } (\tau_2)_{\mathcal{A}} = (\tau_3)_{\mathcal{A}} = 0.$$

1.6

$$\begin{aligned}\int_A \mu(A) &= \mu(\{x : f(x) \in A\}) \\ &= \mu(\{x : -x \in A\}) \\ &= \mu(-A) \\ &= \mu(A)\end{aligned}$$

1.7 Assume $\pi = (\mathbb{I} \times \mathbb{T})_{\#} \mu$ and $\nu = \mathbb{I}_{\#} \mu$.

Then let $P^X(x,y) = x$ and $P^Y(x,y) = y$.

$$\begin{aligned}P^X_{\#} \pi(A) &= \pi(\{(x,y) : P^X(x,y) \in A\}) \\ &= (\mathbb{I} \times \mathbb{T})_{\#} \mu(\{(x,y) : x \in A\}) \\ &= (\mathbb{I} \times \mathbb{T})_{\#} \mu(A \times Y) \\ &= \mu(\{x : (\mathbb{I} \times \mathbb{T})(x) \in A \times Y\}) \\ &= \mu(\{x : x \in A \text{ and } \mathbb{T}(x) \in Y\}) \\ &= \mu(A)\end{aligned}$$

Similarly,

$$\begin{aligned}P^Y_{\#} \pi(B) &= (\mathbb{I} \times \mathbb{T})_{\#} \mu(X \times B) \\ &= \mu(\{x : (\mathbb{I} \times \mathbb{T})(x) \in X \times B\}) \\ &= \mu(\{x : x \in X \text{ and } \mathbb{T}(x) \in B\})\end{aligned}$$

$$= \mu(\{x: f(x) \in B\})$$

$$= \mathcal{T}_\# \mu(B)$$

$$= \nu(B)$$

Hence $\nu \in \mathcal{T}(\mu, \nu)$.

On the other hand, if $\nu \in \mathcal{T}(\mu, \nu)$ then we have

$$\nu(B) = \mathcal{P}_\#^Y \nu(B) = \mathcal{T}_\# \mu(B)$$

Hence $\nu = \mathcal{T}_\# \mu$.

1.8 (a) $c(x, y) = |x - y|^2$

$$\mathcal{M}(\mathcal{T}_1) = \int_0^1 |x - \eta(x)|^2 dx$$

$$= \int_0^1 |x - x - 1|^2 dx$$

$$= 1$$

$$\mathcal{M}(\mathcal{T}_2) = \int_0^1 |x - \eta(x)|^2 dx$$

$$= \int_0^1 |x - x + x|^2 dx$$

$$= \int_0^1 (x - 1)^2 dx$$

$$= \int_{-1}^0 y^2 dy$$

letting $y = x - 1$

$$= \frac{24}{3} [y^3]_{-1}^0$$

$$= 8/3.$$

$$M_2(p_3) = \int_0^1 |x - f_3(x)|^2 dx$$

$$= \int_0^{1/2} |x - x - 3/2|^2 dx + \int_{1/2}^1 |x - 2+x|^2 dx$$

$$= \int_0^{1/2} (3/2)^2 dx + 4 \int_{1/2}^1 (1-x)^2 dx$$

$$= \frac{9}{8} + 4 \int_{-1/2}^0 y^2 dy$$

$$= \frac{9}{8} + \frac{4}{3} [y^3]_{-1/2}^0$$

$$= \frac{9}{8} + \frac{4}{3} \times \frac{1}{2^3}$$

$$= \frac{9}{8} \frac{27}{24} + \frac{4}{24}$$

$$= 31/24.$$

$$(b) M_1(p_1) = \int_0^1 |x - x - 1| dx = 1$$

$$M_1(p_2) = 2 \int_0^1 |x-1| dx = 2 \int_0^1 (1-x) dx = 2 \int_0^1 y dy = [y^2]_0^1 = 1$$

$$M_1(p_3) = \int_0^{1/2} |x - 3/2| dx + 2 \int_{1/2}^1 |1-x| dx$$

$$= \frac{3}{4} + 2/8 = 1.$$

$$(c) \quad M(\varphi_1) = \int_0^1 \sqrt{1-x} \, dx = 1$$

$$\begin{aligned} M(\varphi_2) &= \sqrt{2} \int_0^1 \sqrt{1-x} \, dx = \sqrt{2} \int_0^1 \sqrt{y} \, dy \\ &= \frac{2\sqrt{2}}{3} [y^{3/2}]_0^1 = \frac{2\sqrt{2}}{3} \end{aligned}$$

$$\begin{aligned} M(\varphi_3) &= \int_0^{1/2} \sqrt{3/2} \, dx + \sqrt{2} \int_{1/2}^1 \sqrt{1-x} \, dx \\ &= \frac{1}{2} \sqrt{3/2} + \sqrt{2} \int_0^{1/2} \sqrt{y} \, dy \\ &= \frac{1}{2} \sqrt{3/2} + \frac{2\sqrt{2}}{3} [y^{3/2}]_0^{1/2} \\ &= \frac{1}{2} \sqrt{3/2} + \frac{2\sqrt{2}}{3} \frac{1}{2\sqrt{2}} \\ &= \frac{\sqrt{3}}{2\sqrt{2}} + \frac{1}{3} \end{aligned}$$

1.9 Let $T: X \rightarrow Y$ then with $\mu_X = \nu$

$$M(\varphi) = \int_0^1 h(|x - T(x)|) \, dx$$

$$\geq h\left(\left|\int_0^1 (x - T(x)) \, dx\right|\right) \quad \text{by Jensen's inequality}$$

$$\begin{aligned} \text{Now } \int_0^1 x - T(x) \, dx &= \int_0^1 x \, dx - \int_0^1 T(x) \, dx \\ &= \frac{1}{2} - \int_0^1 T(x) \, d\mu(x) = \frac{1}{2} - \int_1^2 y \, d\nu(y) \\ &= \frac{1}{2} - \frac{1}{2} [y^2]_1^2 = \frac{1}{2} - \frac{1}{2}(4-1) = \frac{1}{2} - \frac{3}{2} = -1. \end{aligned}$$

$$\text{Hence } M(\varphi) \geq h(1)$$

Now,

$$\begin{aligned} \mathbb{M}(T_i) &= \int_0^1 h(|x - x - 1|) dx \\ &= \int_0^1 h(1) dx \\ &= h(1). \end{aligned}$$

Then $\mathbb{M}(T_i) \leq \mathbb{M}(T)$ $\forall T: X \rightarrow Y$ with $T_{\#} \mu = \nu$.

Since $(T_i)_{T_{\#} \mu = \nu}$ we have that T_i is a minimizer of the problem.

1.10 Claim h is convex, it is then by (1.9), T_i is optimal.

$$h'(s) = 1 + \log(s+1)$$

$$h''(s) = \frac{1}{s+1} > 0 \text{ for } s > 0. \quad \Rightarrow h \text{ is convex.}$$

1.11

Let $T_{\#} \mu = \nu$. Then

$$\mathbb{M}(T) = \int_X h(\varphi(x) - x) d\mu(x) = h\left(\int_X (\varphi(x) - x) d\mu(x)\right)$$

$$= h\left(\int_X \varphi(x) d\mu(x)\right) - h\left(\int_X x d\mu(x)\right) \quad \left(\text{Since } X, Y \text{ are bounded then we avoid the case where we have } \infty - \infty\right).$$

$$\text{Now } \int_X \varphi(x) d\mu(x) = \int_Y y d(T_{\#} \mu)(y) = \int_Y y d\nu(y)$$

$$\text{So } \mathbb{M}(T) = h\left(\int_Y y d\nu(y)\right) - h\left(\int_X x d\mu(x)\right) \text{ which is independent of } T. \quad (10)$$

1.12 Let let $h(x) = x$, then by Ex 1.1 T_1 is optimal.

~~By Ex 1.6 (b) $M(T_1) = 1$~~

~~Now $M(T_1) = \int_0^1 |x - x - 2| dx$~~

Now,

$$\begin{aligned} M(T_1) &= \frac{1}{2} \int_0^2 |x - T_1(x)| dx \\ &= \frac{1}{2} \int_0^2 |x - x - 1| dx \\ &= 1 \end{aligned}$$

And

$$\begin{aligned} M(T_2) &= \frac{1}{2} \int_0^2 |x - T_2(x)| dx \\ &= \frac{1}{2} \int_0^1 |x - x - 2| dx + \frac{1}{2} \int_1^2 0 dx \\ &= \frac{1}{2} \int_0^1 2 dx = 1 \end{aligned}$$

To check $(T_1)_{\alpha} \neq 0$ we have

$$\begin{aligned} \int_0^1 \varphi(x) dx &= \frac{1}{2} \int_0^2 \varphi(T_1(x)) dx = \frac{1}{2} \int_0^2 \varphi(x+1) dx \\ &= \frac{1}{2} \int_1^3 \varphi(y) dy = \frac{1}{4} \varphi(2) \int_1^3 dy \end{aligned} \quad \text{and apply Ex 1.3.}$$

To check $(T_a)_\# \mu = \omega$ we have

$$\begin{aligned} \int_X \varphi(T_a(x)) d\mu(x) &= \frac{1}{2} \int_0^1 \varphi(x+z) dx + \frac{1}{2} \int_1^2 \varphi(x) dx \\ &= \frac{1}{2} \int_2^3 \varphi(y) dy + \frac{1}{2} \int_1^2 \varphi(y) dy \\ &= \frac{1}{2} \int_1^3 \varphi(y) dy \\ &= \int_Y \varphi(y) d\omega(y) \quad \text{and similarly for (1.3).} \end{aligned}$$

1.13

(a) ~~$\int_X \varphi(x) d\mu(x)$~~ By Prop 1.5 $S_\# (\tau_a)_\# \mu = (S \circ \tau_a)_\# \mu$

$$\int_X \varphi((S \circ \tau_a)(x)) d\mu(x) = \int_X \varphi(\tau(x) - b) d\mu(x)$$

$$= \int_X \varphi(y - b) d((T_a)_\# \mu)(y) \quad \text{by Prop 1.5}$$

$$= \int_X \varphi(\tau_b(y)) d\omega(y)$$

$$= \int_X \varphi(\tau_b(y)) d\omega(y)$$

If $S_\# (\tau_b)_\# \mu = \omega$ then we have

$$\int_Y \varphi(y) d\omega(y) = \int_X \varphi((S \circ \tau_b)(x)) d\mu(x) = \int_X \varphi(\tau_b(x)) d\omega(x)$$

so $(\tau_b)_\# \omega = \omega$ and vice versa.

(b) Let $T^{a,b}$ be an optimal map between μ and ν , i.e.

$$\tau(\mu, \nu) = \mathbb{M}(T^{a,b}) \quad \text{Define } S = \tau_a(T^{a,b}). \quad \text{By part (c)}$$

~~(c)~~ $\int_{\mathbb{R}} \tau_a(\cdot) d\mu$ Let $\mu_a = (\tau_a)_\# \mu$ and $\nu_b = (\tau_b)_\# \nu$.

By part (c) $\int_{\mathbb{R}} \mu_a = \nu_b$ so

$$\tau(\mu_a, \nu_b) \leq \mathbb{M}(S)$$

$$= \int_{-\infty}^{\infty} |S(x) - x|^2 d\mu_a(x)$$

$$= \int_{-\infty}^{\infty} |\tau_a(x) - b - x|^2 d[(\tau_a)_\# \mu(x)]$$

$$= \int_{-\infty}^{\infty} |\tau^{a,b}(\tau_a(x) + x) - b - \tau_a(x)|^2 d\mu(x) \quad \text{by Prop 1.5}$$

$$= \int_{-\infty}^{\infty} |\tau(x) - b - x + x + a|^2 d\mu(x)$$

$$= \int_{-\infty}^{\infty} |\tau(x) - x|^2 d\mu(x) + (a-b)^2 \int_{-\infty}^{\infty} d\mu(x)$$

$$+ 2 \int_{-\infty}^{\infty} (\tau(x) - x)(a-b) d\mu(x)$$

$$= \tau(\mu, \nu) + (a-b)^2 + 2(a-b) \left(\int_{-\infty}^{\infty} \tau^{a,b}(x) d\mu(x) - \int_{-\infty}^{\infty} x d\mu(x) \right)$$

$$= \tau(\mu, \nu) + (a-b)^2 + 2(a-b) \left(\int_{-\infty}^{\infty} y d \underbrace{\left(\frac{\tau^{a,b}}{\mu} \right)}_{= \nu} - \int_{-\infty}^{\infty} x d\mu(x) \right)$$

$$= \tau(\mu, \nu) + (a-b)^2 + 2(a-b)(M_\nu - M_\mu).$$

(*)

(13)

(conversely, let $T^{a,b}$ be an optimal map between μ_a and ν_b .

Define $S = \tau_b \circ (T^{a,b} \circ \tau_a)$. By part (a) (exchange $a \rightarrow -a, b \rightarrow -b$)
 $\mu_a \rightarrow \mu_a, \nu_b \rightarrow \nu_b$

we have $S_{\#}([\tau_a]_{\#} \mu_a) = [\tau_b]_{\#} \nu_b$.

Since $[\tau_a]_{\#} \mu_a \stackrel{(a)}{=} \mu_a \circ [\tau_a]_{\#} \mu_a$
 $= (\tau_a \circ \tau_a)_{\#} \mu_a$
 $= \mu_a$

and similarly $[\tau_b]_{\#} \nu_b = \nu_b$ we have

that $S_{\#} \mu_a = \nu_b$, so S is a candidate map between

μ_a and ν_b . In particular

$$\begin{aligned} \tau(\mu_a, \nu_b) &\leq \int_{\mathbb{R}} |S(x) - x|^2 d\mu_a(x) \\ &= \int_{\mathbb{R}} |T^{a,b}(x-a) + b - x|^2 d\mu_a(x) \\ &= \int_{\mathbb{R}} |T^{a,b}(\tau_a(x) - a) + b - \tau_a(x)|^2 d\mu_a(x) \\ &= \int_{\mathbb{R}} |T^{a,b}(x) + b - x - a|^2 d\mu_a(x) \\ &= \int_{\mathbb{R}} |T^{a,b}(x) - x|^2 d\mu_a(x) + (b-a)^2 + 2(b-a) \int_{\mathbb{R}} (T^{a,b}(x) - x) d\mu_a(x) \\ &= \tau(\mu_a, \nu_b) + (b-a)^2 + 2(b-a) \tau(\mu_a, \nu_b) \end{aligned}$$

Now,

$$\begin{aligned}\int_{\mathbb{R}} x \, d\mu_n(x) &= \int_{\mathbb{R}} x \, d[\tau_a]_{\#} \mu(x) = \int_{\mathbb{R}} \tau(x) \, d\mu(x) \\ &= \int_a^b M_{\mathbb{R}} - a\end{aligned}$$

And

$$\begin{aligned}\int_{\mathbb{R}} T^{M_0, U_0}(x) \, d\mu_n(x) &= \int_{\mathbb{R}} \cancel{T^{M_0, U_0}(x)} \, d[\tau_a]_{\#} \mu(x) = \int_{\mathbb{R}} \\ &= \int_{\mathbb{R}} y \, d T_{\theta}^{M_0, U_0} \mu(y) \\ &= \int_{\mathbb{R}} y \, d U_0(y) = \int_{\mathbb{R}} y \, d[\tau_b]_{\#} \nu(y) \\ &= \int_a^b \tau(y) \, d\nu(y) \\ &= M_0 - b\end{aligned}$$

$$\begin{aligned}\text{So, } \tau(\mu_n) &\leq \tau(\mu_n, U_0) + (b-a)^2 + 2(b-a)(M_0 - b - M_{\mathbb{R}} + a) \\ &= \tau(\mu_n, U_0) + (b-a)^2 + 2(b-a)^2 + 2(b-a)(M_0 - M_{\mathbb{R}}) \\ &= \tau(\mu_n, U_0) - (b-a)^2 - 2(a-b)(M_0 - M_{\mathbb{R}}) \quad (\text{X})\end{aligned}$$

Combining (X) and (X') yields

$$\tau(\mu_n) = \tau(\mu_n, U_0) - (b-a)^2 - 2(a-b)(M_0 - M_{\mathbb{R}}).$$

(A further proof: use explicit construction of transport map in \mathbb{R} in terms of the cdf's.)