

Exercise Sheet 3 Solutions

Intro to OT

Leht 2018-2019

3.1

Let $\varphi(x) = -2x \cdot x_0$ with $x_0 = \mathbb{P}_B \mu$

$$\begin{aligned} \text{then } \psi(y) &= \inf_x (|x-y|^2 - \varphi(x)) \\ &= \inf_x (|x-y|^2 + \underbrace{2x \cdot x_0}_{F(x)}) \end{aligned}$$

$$\approx \inf_x |x|^2$$

$$\nabla F(x) = 2(x-y) + 2x_0$$

$$\nabla F(x) = 0 \Rightarrow x = y - x_0 \quad \text{then}$$

$$\psi(y) = |x_0|^2 + 2(y-x_0) \cdot x_0$$

one can check $\varphi(x) + \psi(y) \leq |x-y|^2$

$$\text{Now } \min_{\varphi, \psi} \mathcal{M}(\Gamma) \geq \mathcal{J}(\varphi, \psi) = -2 \int_{\mathbb{R}^d} x \cdot x_0 d\mu(x) + \int_{\mathbb{R}^d} (|x_0|^2 + 2(y-x_0) \cdot x_0) d\mu(y)$$

↑
by duality

$$= -2 \int_{\mathbb{R}^d} x \cdot x_0 d\mu(x) + \int_{\mathbb{R}^d} |x_0|^2 d\mu(x) + 2 \int_{\mathbb{R}^d} (y-x_0) \cdot x_0 d\mu(y)$$

$$= -2 \int_{\mathbb{R}^d} x \cdot x_0 d\mu(x) + \int_{\mathbb{R}^d} |x_0|^2 d\mu(x) + 2 \int_{\mathbb{R}^d} (T(x) - x_0) \cdot x_0 d\mu(x)$$

$$= -2 \int_{\mathbb{R}^d} x \cdot x_0 d\mu(x) + \int_{\mathbb{R}^d} |x_0|^2 d\mu(x) + 2 \int_{\mathbb{R}^d} x \cdot x_0 d\mu(x)$$

$$= \int_{\mathbb{R}^d} |x_0|^2 d\mu(x) = \int_{\mathbb{R}^d} |T(x) - x|^2 d\mu(x) = \mathcal{M}(\Gamma)$$

(Hence T is optimal.)

3.2

$$(a) \quad \varphi_1^*(y) = \sup_{x \in \mathbb{R}^d} (x \cdot y - \varphi_1(x))$$

$$= \sup_{x \in \mathbb{R}^d} \underbrace{(x \cdot y - x \cdot x)}_{F_1(x)}$$

$$\nabla F_1(x) = y - 2x \quad \text{so} \quad \nabla F_1(x) = 0 \Rightarrow x = \frac{1}{2}y$$

$$\text{E} \quad \varphi_1^*(y) = \frac{1}{2}y \cdot y - \frac{1}{4}y \cdot y = \frac{1}{4}y \cdot y$$

$$(b) \quad \varphi_2^*(y) = \sup_{x \in \mathbb{R}^d} (x \cdot y - x \cdot x_0)$$

$$= \sup_{x \in \mathbb{R}^d} x \cdot (y - x_0)$$

$$= \begin{cases} 0 & \text{if } y = x_0 \\ +\infty & \text{else} \end{cases}$$

$$(c) \quad \varphi_3^*(y) = \sup_{x \in \mathbb{R}^d} (x \cdot y - \varphi_3(x))$$

$$= x_0 \cdot y$$

$$(d) \quad \varphi_4^*(y) = \sup_{x \in \mathbb{R}^d} \underbrace{(x \cdot y - \frac{1}{p} |x|^p)}_{F_4(x)}$$

$$\nabla F_4(x) = y - x |x|^{p-2} \quad \text{so} \quad \nabla F_4(x) = 0 \Rightarrow y = x |x|^{p-2}$$

so $x \cdot y = |x|^p$, then $F_4(x) = |x|^p - \frac{1}{p} |x|^p = (1 - \frac{1}{p}) |x|^p$
 Moreover $|y| = |x|^{p-1}$ so $|x|^p = |y|^{\frac{p}{p-1}}$, then $F_4(y) = (1 - \frac{1}{p}) |y|^{\frac{p}{p-1}}$

(E)

$$S_0 \quad \varphi_p^*(|y|) = \left(1 - \frac{1}{p}\right) |y|^{\frac{p}{p-1}}$$

Note that if we let $z = \frac{1}{1 - \frac{1}{p}} = \frac{p}{p-1}$ then

$$\varphi_p^*(|y|) = \frac{1}{z} |y|^z \quad \text{and} \quad \frac{1}{p} + \frac{1}{z} = \frac{1}{p} + 1 - \frac{1}{p} = 1.$$

3.3

Let $x \in \mathbb{R}^d$, then

$$y \in \partial\varphi(x) \Leftrightarrow x \cdot y = \varphi(x) + \varphi^*(y) \Leftrightarrow x \cdot y = \underbrace{\varphi^{**}(x)}_{\text{prop 6.5}} + \varphi^*(y) \quad \text{prop 6.7}$$

$$\Leftrightarrow x \in \partial\varphi^*(y)$$

↑
prop 6.5.

3.4

(1) Feasibility of the problem.

Assume $x, y \in \mathbb{R}^d$ we seek the $\partial\varphi(x) = \partial\varphi(y)$ and $x \neq y$.

$$\text{By strict convexity} \quad \partial\varphi(x) \cdot (y-x) < \varphi(y) - \varphi(x) \quad \textcircled{*}$$

$$\partial\varphi(y) \cdot (x-y) < \varphi(x) - \varphi(y) \quad \textcircled{+}$$

Using $\partial\varphi(x) = \partial\varphi(y)$ we have $\textcircled{*} \Rightarrow \partial\varphi(y) \cdot (y-x) < \varphi(y) - \varphi(x)$

$\Rightarrow \partial\varphi(y) \cdot (x-y) > \varphi(x) - \varphi(y)$: a contradiction with $\textcircled{+}$

$$\left[\begin{array}{l} \partial\varphi(x) \cdot (y-x) < \varphi(y) - \varphi(x) \text{ follows from } \varphi(x) < \varphi(y) \\ \varphi(y) > \varphi(x) + \partial\varphi(x) \cdot (y-x) \end{array} \right].$$

(2) Strictly convex of the gradient. For y_0

let $g(x) = \varphi(x) - x \cdot y_0$ ~~for finding y .~~

Since g is convex then if $g(x) \rightarrow \infty$ as $|x| \rightarrow \infty$ then \exists a minimum of g .

Now $g(x) = \varphi(x) - x \cdot y_0 \geq \varphi(x) - |x| |y_0| = |x| \left(\frac{\varphi(x)}{|x|} - |y_0| \right)$

As $|x| \rightarrow \infty$ since $\frac{\varphi(x)}{|x|} > |y_0|$. Then $g(x) \rightarrow \infty$ as $|x| \rightarrow \infty$.

Hence $\varphi^*(y) = \sup_{x \in \mathbb{R}^d} (\varphi(x) - x \cdot y) = \inf_{x \in \mathbb{R}^d} g(x) = \min_{x \in \mathbb{R}^d} g(x)$.

As the minimum of C^1 function φ^* is achieved at $x = \varphi^*(y)$ where by \mathbb{R}^d implies $y \in \text{dom } \varphi^* = \text{dom } \varphi$

Since g is convex, it has diff and coercive \exists a minimum of g at x_0 at y_0 and $\nabla g(x_0) = 0$. But $\nabla g(x_0) = \nabla \varphi(x_0) - y_0$
 So $\exists x_0$ s.t. $\nabla \varphi(x_0) = y_0$. For points $\nabla \varphi$ is surjective

3.5

Let $n \in \mathbb{N}$ and $(x_i, y_i) \in \Gamma$, $i=1, \dots, n$.

Then $y_i \in \partial \varphi(x_i) \Rightarrow \varphi(z) \geq \varphi(x_i) + y_i \cdot (z - x_i) \quad \forall z \in \mathbb{R}^d$

choose $z = x_{i+1}$ then $\varphi(x_{i+1}) \geq \varphi(x_i) + y_i \cdot (x_{i+1} - x_i) \quad \forall i$

summing over i
 $\sum_{i=1}^n \varphi(x_{i+1}) \geq \sum_{i=1}^n \varphi(x_i) + \sum_{i=1}^n y_i \cdot (x_{i+1} - x_i)$
 $\Rightarrow 0 \leq \sum_{i=1}^n y_i \cdot x_{i+1} - \sum_{i=1}^n y_i \cdot x_i$ as required. (4)

3.6 we have $(\tilde{\varphi}, \tilde{\psi}) \in \tilde{\mathcal{F}}$ (ignoring integrability conditions)

$$\Leftrightarrow \tilde{\varphi}(x) + \tilde{\psi}(y) \geq x \cdot y \quad \forall x, y$$

$$\Leftrightarrow |x|^2 - 2\tilde{\varphi}(x) + |y|^2 - 2\tilde{\psi}(y) \leq |x|^2 + |y|^2 - 2xy = |x-y|^2$$

$$\Leftrightarrow \varphi(x) + \psi(y) \leq |x-y|^2$$

$$\Leftrightarrow (\varphi, \psi) \in \mathcal{F}_c$$

And
$$\begin{aligned} \mathcal{J}(\tilde{\varphi}, \tilde{\psi}) &= \int \tilde{\varphi} d\mu(x) + \int \tilde{\psi} d\nu(y) \\ &= \int (|x|^2 - 2\tilde{\varphi}(x)) d\mu(x) + \int (|y|^2 - 2\tilde{\psi}(y)) d\nu(y) \\ &= \int |x|^2 d\mu(x) + \int |y|^2 d\nu(y) - 2\mathcal{J}(\tilde{\varphi}, \tilde{\psi}). \end{aligned}$$

$$\int_0 \max_{(\varphi, \psi) \in \mathcal{F}_c} \mathcal{J}(\varphi, \psi) = \int |x|^2 d\mu(x) + \int |y|^2 d\nu(y) - 2 \inf_{(\tilde{\varphi}, \tilde{\psi}) \in \tilde{\mathcal{F}}} \mathcal{J}(\tilde{\varphi}, \tilde{\psi})$$

And moreover if $(\varphi, \psi) \in \mathcal{F}_c$ maximizes \mathcal{J} in \mathcal{F}_c
 $\Leftrightarrow (\tilde{\varphi}, \tilde{\psi}) \in \tilde{\mathcal{F}}$ minimizes \mathcal{J} in $\tilde{\mathcal{F}}$.

By Corollary 6.3 we have $T = \nabla \tilde{\varphi}$ is an optimal plan when $(\tilde{\varphi}, \tilde{\psi}^-)$ minimizes \mathcal{J} in $\tilde{\mathcal{F}}$. Here $T = \nabla \left(\frac{1}{2}|x|^2 - \frac{1}{2}\varphi \right) = \text{Id} - \frac{1}{2}\nabla\varphi$ when (φ, φ^c) maximizes \mathcal{J} in \mathcal{F}_c (and when $\varphi^c = |x|^2 - 2\tilde{\varphi}^-$).

3.7

We use that $\phi(x) = -2x \cdot x_0$ is the maximum of \mathcal{T} in \mathbb{R}^2 .

By Ex 3.6 the OT map is given by

$$T(x) = x - \frac{1}{2} \nabla \phi(x) = x + x_0.$$

3.8

We use the ansatz $T(x) = \frac{x}{|x|^2}$. Then only for

$\mathbb{R}^n, n=2$ we need, by Ex 1.4,

$$(*) \quad f(x) = \text{sgn}(T(x)) |\det(\nabla T(x))|.$$

Now since $\frac{\partial}{\partial x_i} T_j(x) = \frac{1}{|x|^2} (\delta_{ij} - \frac{2x_i x_j}{|x|^2})$ we have

$$\det \nabla T(x) = \frac{1}{|x|^{2n}} \det \begin{pmatrix} 1 - \frac{2x_1^2}{|x|^2} & -\frac{2x_1 x_2}{|x|^2} \\ -\frac{2x_1 x_2}{|x|^2} & 1 - \frac{2x_2^2}{|x|^2} \end{pmatrix}$$

$$= \frac{1}{|x|^{2n}} \left(\left(1 - \frac{2x_1^2}{|x|^2}\right) \left(1 - \frac{2x_2^2}{|x|^2}\right) - \frac{4x_1^2 x_2^2}{|x|^4} \right)$$

$$= \frac{1}{|x|^{2n}} \left(1 - \frac{2x_1^2}{|x|^2} - \frac{2x_2^2}{|x|^2} + \frac{4x_1^2 x_2^2}{|x|^4} - \frac{4x_1^2 x_2^2}{|x|^4} \right)$$

$$= \frac{1-2}{|x|^{2n}}$$

$$\text{from } (*) \Leftrightarrow \frac{1}{|x|} = \frac{3|x|}{2|x|^2 |x|^{2n}} = \frac{3|x| (1-2)}{2|x|^2 |x|^{2n}}$$

This is satisfied for $n = \frac{1}{3}$.

Now we recall that if $(\tilde{\varphi}, \tilde{\varphi}^*)$ maximizes \mathcal{J} over $\tilde{\mathcal{F}}$
 then we have $\nabla \tilde{\varphi} = \tau$. Assume $\tilde{\varphi}(a) = \alpha(|a|)$. Then
 $\nabla \tilde{\varphi}(a) = \frac{\alpha'(|a|)a}{|a|}$. Hence $\nabla \tilde{\varphi} = \tau$ implies

$$\frac{\alpha'(|a|)}{|a|} = \frac{1}{|a|^{5/3}}$$

Hence, $\alpha'(r) = r^{2/3} \Rightarrow \alpha(r) = \frac{3r^{5/3}}{5}$

$\therefore \tilde{\varphi}(x) = \frac{3|x|^{5/3}}{5}$ [One can check that $\nabla \tilde{\varphi} = \tau$]

Now to compute $\tilde{\varphi}^*$ we use by theorem 3.4 that

$\tilde{\varphi}^*(y) = x \cdot y - \tilde{\varphi}(x)$ where $\nabla \tilde{\varphi}(x) = y \Leftrightarrow \frac{x}{|x|^{2/3}} = y$

$$= x \cdot y - \frac{3|x|^{5/3}}{5}$$

$$= |y|^2 |x|^{5/3} - \frac{3}{5} |x|^{5/3}$$

$$= |y|^2 |y|^{5/2} - \frac{3}{5} |y|^{5/2}$$

$$= \frac{2}{5} |y|^{5/2}$$

Since $\frac{x \cdot y}{|x|^{2/3}} = |y|^2$

and $|x|^{2/3} = |y|$
 $|x| = |y|^{3/2}$

By ex 3.6 we have

$$\varphi(x) = |x|^2 - 2\tilde{\varphi}(x) = |x|^2 - \frac{36}{5}|x|^{5/3}$$

$$\psi(y) = |y|^2 - 2\tilde{\varphi}(y) = |y|^2 - \frac{44}{5}|y|^{5/2}$$

is candidate maximum to the dual problem.

First we check $(\varphi, \psi) \in \mathbb{D}_c$:

$$\varphi(x) + \psi(y) = |x|^2 + |y|^2 - \frac{63}{5}|x|^{5/3} - \frac{44}{5}|y|^{5/2}$$

By Young's inequality $|x \cdot y| \leq \frac{|x|^p}{p} + \frac{|y|^q}{q}$ where $\frac{1}{p} + \frac{1}{q} = 1, p, q > 1$.

choosing $p = 5/3$ and $q = 5/2$ we have $\frac{1}{p} + \frac{1}{q} = \frac{3}{5} + \frac{2}{5} = 1$ and

$$-2|x \cdot y| \geq -\frac{6|x|^{5/3}}{5} - \frac{4|y|^{5/2}}{5}$$

$$\text{Hence } \varphi(x) + \psi(y) \leq |x|^2 + |y|^2 - 2|x \cdot y| = |x - y|^2$$

$$\text{Now } J(\varphi, \psi) = \int_{\mathbb{R}^2} \varphi(x) dx + \int_{\mathbb{R}^2} \psi(y) dy$$

$$= \frac{2\pi}{\pi} \int_0^1 (r^2 - \frac{6}{5}r^{5/3}) r dr + \frac{3 \times 2\pi}{2\pi} \int_0^1 (r^2 - \frac{4}{5}r^{5/2}) r^2 dr$$

$$= \frac{-2 \times 17}{220} + \frac{3 \times 3}{55} = \frac{1}{110}$$

And

$$\begin{aligned}
 M(\pi) &= \int_{\mathbb{R}^2} |x - \pi(x)|^2 d\mu(x) \\
 &= \frac{2\pi}{\pi} \int_0^1 \int_{\mathbb{R}^2} \left|x - \frac{x}{|x|^{1/2}}\right|^2 d\mu(x) \\
 &= \int_{\mathbb{R}^2} |x|^2 \left(1 - \frac{1}{|x|^{1/2}}\right)^2 d\mu(x) \\
 &= \frac{2\pi}{\pi} \int_0^1 r^3 \left(1 - \frac{1}{r^{1/2}}\right)^2 dr \\
 &= \frac{1}{110}.
 \end{aligned}$$

Since $M(\pi) = \mathcal{J}(\varphi, \psi)$ it follows that (from duality) that π is optimal.

3.9

Let $\mu = \frac{1}{n} \sum_{i=1}^n \delta_{x_i}$ and $\nu = \frac{1}{n} \sum_{j=1}^n \delta_{y_j}$. By Thm 3.7

\exists a solution to the MOT problem between μ and ν with cost $c(x, y) = |x - y|$. I.e. $\exists \pi \in \Pi(\mu, \nu)$ s.t.

$$\inf_{\pi \in \Pi(\mu, \nu)} M(\pi) = M(\pi^*), \quad \sum_{i,j} \pi_{ij} = 0$$

where $M(\pi) = \frac{1}{n} \sum_{i=1}^n |x_i - \pi(x_i)|$.

(consider the line ℓ_i from x_i to $\pi(x_i)$). For a contradiction we assume $\exists k \neq j$ s.t. ℓ_k intersects ℓ_j . Define a transport map $\tilde{\pi}$ by

$$\tilde{T}(x_i) = \begin{cases} T(x_i) & \text{if } i \neq k, j \\ T^+(x_k) & \text{if } i = j \\ T^+(x_j) & \text{if } i = k \end{cases}$$

We will show $\|A(T^+) > \|A(\tilde{T})$.

Indeed, let $\{x\} = \{x_k \wedge x_j\}$ then

$$|x_j - T^+(x_j)| + |x_k - T^+(x_k)| = |x_j - x| + |x - T^+(x_j)| + |x_k - x| + |x - T^+(x_k)|$$

$$\geq |x_j - T^+(x_k)| + |x_k - T^+(x_j)| \quad \text{by } \Delta \text{ inequality}$$

To show the inequality is in fact strict let us assume

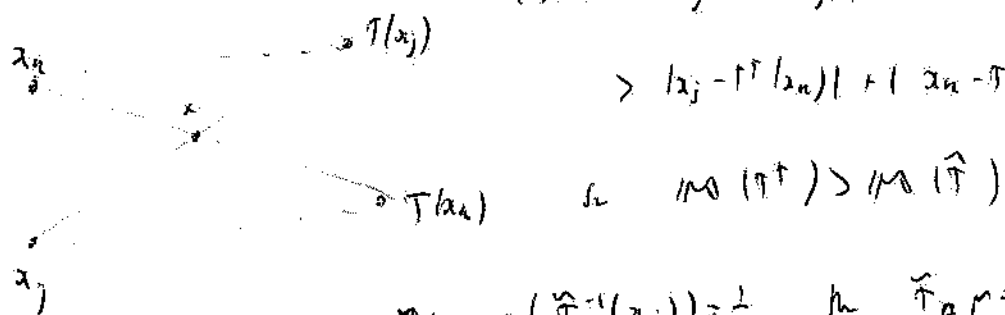
$$\text{the } |x_j - T^+(x_j)| + |x_k - T^+(x_k)| = |x_j - T^+(x_k)| + |x_k - T^+(x_j)|$$

$$\text{Then, } |x_j - T^+(x_k)| = |x_j - x| + |x - T^+(x_k)|$$

$$\text{and } |x_k - T^+(x_j)| = |x_k - x| + |x - T^+(x_j)|$$

So x is also in the line between x_j and $T^+(x_k)$ and x_k and $T^+(x_j)$. This is only possible if points are collinear.

$$\text{Thus } |x_j - T^+(x_j)| + |x_k - T^+(x_k)| > |x_j - T^+(x_k)| + |x_k - T^+(x_j)|$$



$$\text{So } \|A(T^+) > \|A(\tilde{T})$$

Since \tilde{T} is still a bijection and $\tilde{T}^{-1}(\tilde{T}(x_i)) = x_i$ the \tilde{T} is a contraction. So \tilde{T} is contractible, and is a minor of the original problem. This is a contradiction. So T^+ satisfies the desired property. Since T^+ is bijective we can define $\sigma(i) = j$ exactly when $T(x_i) = y_j$ (10)