

Summary of Vector Calculus

The following results apply to any (suitably differentiable) scalar field $\phi(\mathbf{x})$ and vector fields $\mathbf{E}(\mathbf{x})$ and $\mathbf{B}(\mathbf{x})$. They all have important applications in electromagnetism.

Derivatives of a vector field:

$$\begin{aligned} \operatorname{div} \mathbf{E} &\equiv \nabla \cdot \mathbf{E} = \frac{\partial E_i}{\partial x_i} && \text{has one component and is a scalar} \\ \operatorname{curl} \mathbf{E} &\equiv (\nabla \times \mathbf{E})_i = \epsilon_{ijk} \frac{\partial E_k}{\partial x_j} && \text{has three components and is a vector} \\ \operatorname{grad} \mathbf{E} &\equiv (\nabla \mathbf{E})_{ij} = \frac{\partial E_i}{\partial x_j} && \text{has nine components and is a 2nd-rank tensor} \end{aligned}$$

Two identities:

$$\operatorname{curl} \operatorname{grad} \phi = \nabla \times \nabla \phi \equiv 0 . \quad \operatorname{div} \operatorname{curl} \mathbf{E} = \nabla \cdot \nabla \times \mathbf{E} \equiv 0 .$$

Three vector triple products:

$$\begin{aligned} \nabla \times (\nabla \times \mathbf{E}) &= \nabla(\nabla \cdot \mathbf{E}) - \nabla^2 \mathbf{E} \\ \mathbf{E} \times (\nabla \times \mathbf{E}) &= \frac{1}{2} \nabla E^2 - (\mathbf{E} \cdot \nabla) \mathbf{E} \\ \nabla \times (\mathbf{E} \times \mathbf{B}) &= (\mathbf{B} \cdot \nabla) \mathbf{E} - (\mathbf{E} \cdot \nabla) \mathbf{B} + \mathbf{E}(\nabla \cdot \mathbf{B}) - \mathbf{B}(\nabla \cdot \mathbf{E}) \end{aligned}$$

Position vector: let \mathbf{r} or r_i denote the position vector, and $r = |\mathbf{r}|$. Then $\hat{\mathbf{r}} = \mathbf{r}/r$ defines a unit vector in the direction of \mathbf{r} .

$$\begin{aligned} \partial_i r_j &= \delta_{ij}, \quad \partial_i r = \frac{r_i}{r}, \quad \text{or} \quad \nabla r = \hat{\mathbf{r}} \\ \frac{\partial}{\partial r_i} \left(\frac{1}{r} \right) &= -\frac{r_i}{r^3}, \quad \frac{\partial^2}{\partial r_i \partial r_j} \left(\frac{1}{r} \right) = \frac{3r_i r_j - r^2 \delta_{ij}}{r^5}, \quad \nabla^2 \left(\frac{1}{r} \right) = 0. \end{aligned}$$

Divergence Theorem (Gauss): If V is a simply connected domain with surface S and outward normal \mathbf{n} then

$$\int_V (\nabla \cdot \mathbf{E}) dV = \int_S \mathbf{E} \cdot \mathbf{n} dS.$$

Stokes' Theorem: If C is a closed curve spanned by the surface S then

$$\oint_C \mathbf{E} \cdot d\mathbf{l} = \int_S (\nabla \times \mathbf{E}) \cdot d\mathbf{S}$$

Gradient Theorem:

$$\int_{\mathbf{a}}^{\mathbf{b}} (\nabla \phi) \cdot d\mathbf{l} = \phi(\mathbf{b}) - \phi(\mathbf{a}).$$

Curl in curvilinear coordinates (ξ_1, ξ_2, ξ_3) :

$$\nabla \times \mathbf{E} = \frac{1}{h_1 h_2 h_3} \begin{vmatrix} h_1 \mathbf{e}_1 & h_2 \mathbf{e}_2 & h_3 \mathbf{e}_3 \\ \frac{\partial}{\partial \xi_1} & \frac{\partial}{\partial \xi_2} & \frac{\partial}{\partial \xi_3} \\ h_1 E_1 & h_2 E_2 & h_3 E_3 \end{vmatrix},$$

where: $h_1 = 1, h_2 = r, h_3 = 1$ in cylindrical polars (r, θ, z) ; and
 $h_1 = 1, h_2 = r, h_3 = r \sin \theta$ in spherical polars (r, θ, φ) .

Cylindrical coordinates (r, θ, z) **Grad, div and Laplacian:**

$$\begin{aligned} \nabla \phi &= \left(\frac{\partial \phi}{\partial r}, \frac{1}{r} \frac{\partial \phi}{\partial \theta}, \frac{\partial \phi}{\partial z} \right) \\ \nabla \cdot \mathbf{E} &= \frac{1}{r} \frac{\partial(r E_r)}{\partial r} + \frac{1}{r} \frac{\partial E_\theta}{\partial \theta} + \frac{\partial E_z}{\partial z} \\ \nabla^2 \phi &= \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \phi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2} + \frac{\partial^2 \phi}{\partial z^2} \end{aligned}$$

Volume and line elements, and normal to cylinder:

$$\begin{aligned} dV &= r dr d\theta dz & \mathbf{dl} &= (dr, r d\theta, dz) \\ \mathbf{n} &= (\cos \theta, \sin \theta, 0) \end{aligned}$$

Spherical coordinates (r, θ, φ)

Note that r and θ denote different quantities in cylindrical and spherical polars.

Grad, div and Laplacian:

$$\begin{aligned} \nabla \phi &= \left(\frac{\partial \phi}{\partial r}, \frac{1}{r} \frac{\partial \phi}{\partial \theta}, \frac{1}{r \sin \theta} \frac{\partial \phi}{\partial \varphi} \right) \\ \nabla \cdot \mathbf{E} &= \frac{1}{r^2} \frac{\partial(r^2 E_r)}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial(\sin \theta E_\theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial E_\varphi}{\partial \varphi} \\ \nabla^2 \phi &= \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial \phi}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial \phi}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 \phi}{\partial \varphi^2} \end{aligned}$$

Volume and line elements, and normal to sphere:

$$\begin{aligned} dV &= r^2 \sin \theta dr d\theta d\varphi & \mathbf{dl} &= (dr, r d\theta, r \sin \theta d\varphi) \\ \mathbf{n} &= (\cos \theta, \sin \theta \cos \varphi, \sin \theta \sin \varphi) \end{aligned}$$