

# On the Mathematical Foundations of Infinite-Dimensional Spectral Computations

Matthew Colbrook  
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UNIVERSITY OF  
CAMBRIDGE



TRINITY  
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*“The infinite! No other question has ever moved so profoundly the spirit of humankind; no other idea has so fruitfully stimulated the intellect; yet no other concept stands in greater need of clarification.” – David Hilbert*

*“To classify is to bring order into chaos.” – George Pólya*

For papers and talks, visit: <http://www.damtp.cam.ac.uk/user/mjc249/home.html>

# Motivation: Szegő limit theorems

## Beiträge zur Theorie der Toeplitzschen Formen.

(Erste Mitteilung.)

Von

G. Szegő in Budapest.

§ 8.

### Ein Satz über die Eigenwerte der Toeplitzschen Formen.

21. Satz XVIII. *Es sei  $f(\theta)$  ( $L$ ) integrabel und  $m \leq f(\theta) \leq M$ .  
Es seien ferner*

$$\lambda_0^{(n)}, \lambda_1^{(n)}, \dots, \lambda_n^{(n)} \quad (n = 0, 1, 2, \dots)$$

*die zu  $f(\theta)$  gehörigen Eigenwerte. Dann ist*

$$m \leq \lambda_n^{(n)} \leq M \quad (n = 0, 1, \dots, n; n = 0, 1, 2, \dots)$$

*und wenn  $F(\lambda)$  eine für  $m \leq \lambda \leq M$  definierte stetige Funktion bezeichnet,*

$$\lim_{n \rightarrow \infty} \frac{F(\lambda_0^{(n)}) + F(\lambda_1^{(n)}) + \dots + F(\lambda_n^{(n)})}{n+1} = \frac{1}{2\pi} \int_0^{2\pi} F[f(\theta)] d\theta. \quad (37)$$

Continuous test function.

Asymptotic behavior of spectral measures!

Integrable real-valued function

$$c_n = \frac{1}{2\pi} \int_0^{2\pi} f(\theta) e^{in\theta} d\theta$$



Gábor Szegő  
(Stanford)

Eigenvalues

$$\begin{pmatrix} c_0 & c_{-1} & c_{-2} & \dots & c_{-n} \\ c_1 & c_0 & c_{-1} & \dots & c_{-n+1} \\ c_2 & c_1 & c_0 & \dots & c_{-n+2} \\ \dots & \dots & \dots & \dots & \dots \\ c_n & c_{n-1} & c_{n-2} & \dots & c_0 \end{pmatrix},$$

Self-adjoint  
Toeplitz matrix.

# Motivation: Schwinger's approx. of quantum systems

*Schwinger*: approx.  $-\Delta + V$  on  $\mathbb{R}$  using periodic finite grids

$$X_N = \{j\sqrt{2\pi/N} : j = 0, \pm 1, \dots, \pm N\}, \quad q_N \text{ multiplication,}$$

$$p_N \text{ F.T. of } q_N, \quad H_N = \frac{1}{2} (p_N^2 + V(q_N))$$



Julian Schwinger  
(Harvard,

Nobel Prize in Physics 1965)

*Digernes, Varadarajan, and Varadhan*: Schwinger's method converges to spectra of  $-\Delta + V$  on  $L^2(\mathbb{R}^d)$  for certain families with compact resolvent.

Given a self-adjoint Schrödinger operator  $-\Delta + V$  on  $\mathbb{R}^d$ ,  
can we approximate its spectrum from sampling  $V$ ?

- Schwinger, "Unitary operator bases," **Proc. Natl. Acad. Sci. USA**, 1960.
- Weyl, "The theory of groups and quantum mechanics," **Dover**, 1931.
- Digernes, Varadarajan, Varadhan, "Finite approximations to quantum systems," **Rev. Math. Phys.**, 1994.

# Computational spectral theory

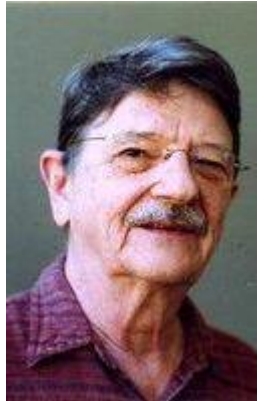
- **Applications:** Quantum mechanics, structural mechanics, optics, acoustics, statistical physics, number theory, matter physics, PDEs, data analysis, neural networks and AI, nuclear scattering, optics, computational chemistry, ...
- **Rich history:** D. Arnold (Minnesota), W. Arveson (Berkeley), A. Böttcher (Chemnitz), W. Dahmen (South Carolina), E. B. Davies (KCL), P. Deift (NYU), L. Demanet (MIT), M. Embree (Virginia Tech), C. Fefferman (Princeton), G. Golub (Stanford), A. Iserles (Cambridge), I. Ipsen (NCS), S. Jitomirskaya (UCI), A. Laptev (Imperial), L. Lin (Berkeley) M. Luskin (Minnesota), S. Mayboroda (Minnesota), W. Schlag (Yale), E. Schrödinger (DIAS), J. Schwinger (Harvard), N. Trefethen (Oxford), V. Varadarajan (UCLA), S. Varadhan (NYU), J. von Neumann (IAS), M. Zworski (Berkeley), ...
- **Verified computations:** Many **computer-assisted proofs** involve spectra. E.g.,  

$$E(Z) = \inf_{N \geq 1} \inf \{z \in \text{Sp}(H_{N,Z})\}, \quad H_{N,Z} = \sum_{k=1}^N (-\Delta_{x_k} - Z|x_k|^{-1}) + \sum_{j \leq k} |x_j - x_k|^{-1}.$$
**Dirac-Schwinger conjecture:** asymptotics of  $E(Z)$  as  $Z \rightarrow \infty$  (Fefferman, Seco 1996)
- **Foundations:** What is computationally possible? Beyond spectra etc.

# Arveson's work on $C^*$ -algebras and finite sections of bounded operators

$$A = \begin{pmatrix} a_{11} & a_{12} & \cdots \\ a_{21} & a_{22} & \cdots \\ \vdots & \vdots & \ddots \end{pmatrix}, \quad A \left( \sum_{k=1}^{\infty} x_k e_k \right) = \sum_{j=1}^{\infty} \left( \sum_{k=1}^{\infty} a_{jk} x_k \right) e_j$$

Canonical basis vectors of  $l^2(\mathbb{N})$



William Arveson  
(Berkeley)

$$\text{Sp}(A) = \{z \in \mathbb{C} : A - zI \text{ is not invertible}\}$$

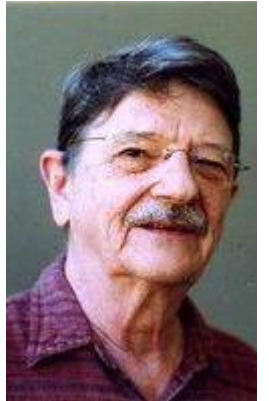
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$A_n$

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When does  $\text{Sp}(A_n)$  converge? In what sense?  
Can we compute  $\text{Sp}(A)$  from matrix entries?

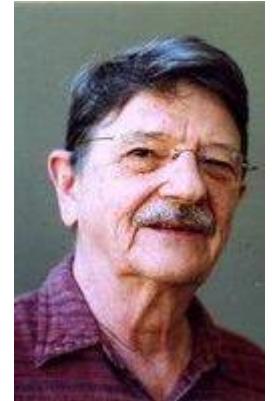
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*"Most operators that arise in practice are not presented in a representation in which they are diagonalized, and it is often very hard to locate even a single point in the spectrum. Thus, one often has to settle for numerical approximations. Unfortunately, there is a dearth of literature on this basic problem and, so far as we have been able to tell, **there are no proven [general] techniques.**"*

W. Arveson, Berkeley (1994)



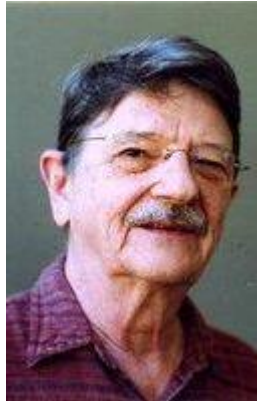
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Canonical basis vectors of  $l^2(\mathbb{N})$



William Arveson  
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When does  $\text{Sp}(A_n)$  converge? In what sense?  
Can we compute  $\text{Sp}(A)$  from matrix entries?

**Goal of talk: Explore mathematical foundations of computing  $\text{Sp}(A)$ .**



What can go wrong...

# Spectral pollution

**Definition:** Let  $\{S_n\} \subset \mathbb{C}$  be a sequence of closed sets (approximations of  $\text{Sp}(A)$ ). We say the sequence suffers from *spectral pollution* if there exists  $\lambda \in \mathbb{C} \setminus \text{Sp}(A)$  with

$$\liminf_{n \rightarrow \infty} \text{dist}(\lambda, S_n) = 0.$$


Examples of  $\{S_n\}$ :

- **Matrix case ( $l^2(\mathbb{N})$ ):** truncate to  $\mathcal{P}_n A \mathcal{P}_n \in \mathbb{C}^{n \times n}$ ,  $S_n = \text{Sp}(\mathcal{P}_n A \mathcal{P}_n)$
- **PDE on unbounded domain:** truncate domain then discretise.

Pervasive: Dirac and Schrödinger operators, magnetohydrodynamics, matter physics, photonic waveguides, ...

# Spectral pollution

eigenvalues of  
infinite multiplicity:  
 $H$  is unitarily  
equivalent to a  
countable sum of  
harmonic oscillators



Magnetic Schrödinger on  $L^2(\mathbb{R}^2)$ :

$$H = (i\partial_x + y/2)^2 + (i\partial_y - x/2)^2, \quad \text{Sp}(H) = \{1, 3, 5, \dots\}$$

Use orthonormal basis  $\psi_j(x) \otimes \psi_k(y)$ ,

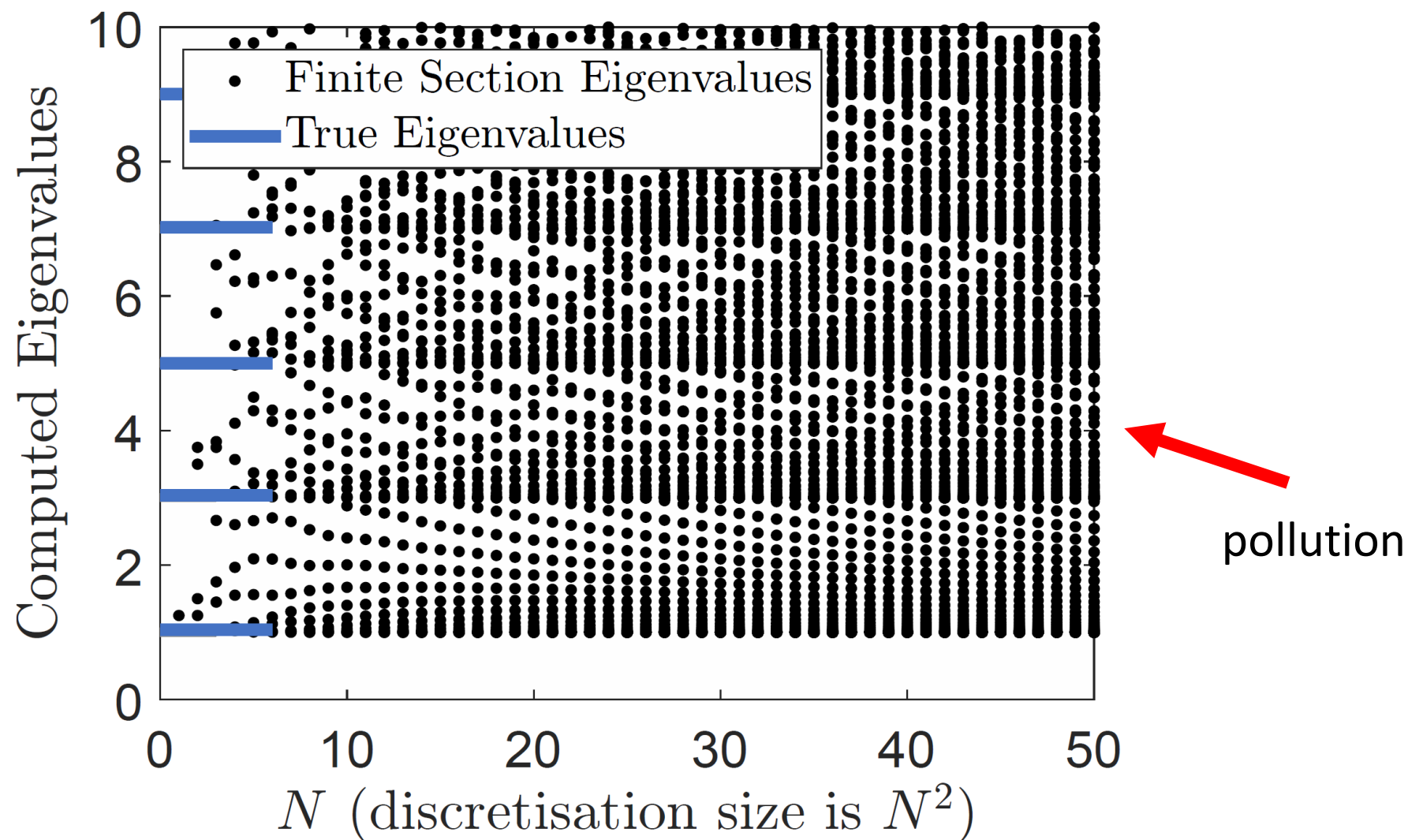
$$\psi_k(x) = \frac{(-1)^k}{\sqrt{2^k k!} \sqrt{\pi}} e^{x^2/2} \frac{d^k}{dx^k} e^{-x^2}$$

Hermite functions



→ Sparse and self-adjoint “matrix”. BUT...

# Spectral pollution



# Where does spectral pollution occur?

**Numerical range:**  $W(A) = \{\langle Ax, x \rangle : x \in \mathcal{D}(A), \|x\| = 1\}$

**Essential numerical range:**  $W_e(A) = \bigcap_{B \text{ compact}} \text{Cl}(W(A + B))$

**Theorem (Pokrzywa):** Let  $A$  be a bounded operator on a separable Hilbert space  $\mathcal{H}$ ,  $\{\mathcal{P}_n\}$  finite-rank orthogonal projections that converge strongly to  $I$ .

- If  $z \notin W_e(A)$ ,  $z \in \text{Sp}(A)$  if and only if  $\lim_{n \rightarrow \infty} \text{dist}(z, \text{Sp}(\mathcal{P}_n A \mathcal{P}_n)) = 0$ .
- If  $S \subset W_e(A)$  compact,  $\exists$  finite-rank orth. project.  $\{Q_n\}$  with  $\mathcal{P}_n \leq Q_n$  and 
$$\lim_{n \rightarrow \infty} \sup_{x \in \text{Sp}(\mathcal{P}_n A \mathcal{P}_n) \cup S} \text{dist}(x, \text{Sp}(Q_n A Q_n)) + \sup_{x \in \text{Sp}(Q_n A Q_n)} \text{dist}(x, \text{Sp}(\mathcal{P}_n A \mathcal{P}_n) \cup S) = 0$$

Spectral pollution occurs precisely on  $W_e(A) \setminus \text{Sp}(A)$ .

Extensions to unbounded  $A$ , domain truncation ([Bögli, Marletta, Tretter, 2020](#))

- Pokrzywa, "Method of orthogonal projections and approximation of the spectrum of a bounded operator," *Studia Mathematica*, 1979.
- Bögli, Marletta, Tretter, "The essential numerical range for unbounded linear operators," *Journal of Functional Analysis*, 2020

# Spectral invisibility

**Definition:** Let  $\{S_n\} \subset \mathbb{C}$  be a sequence of closed sets (approximations of  $\text{Sp}(A)$ ). We say the sequence suffers from ***spectral invisibility*** if there exists  $\lambda \in \text{Sp}(A)$  with

$$\limsup_{n \rightarrow \infty} \text{dist}(\lambda, S_n) > 0.$$

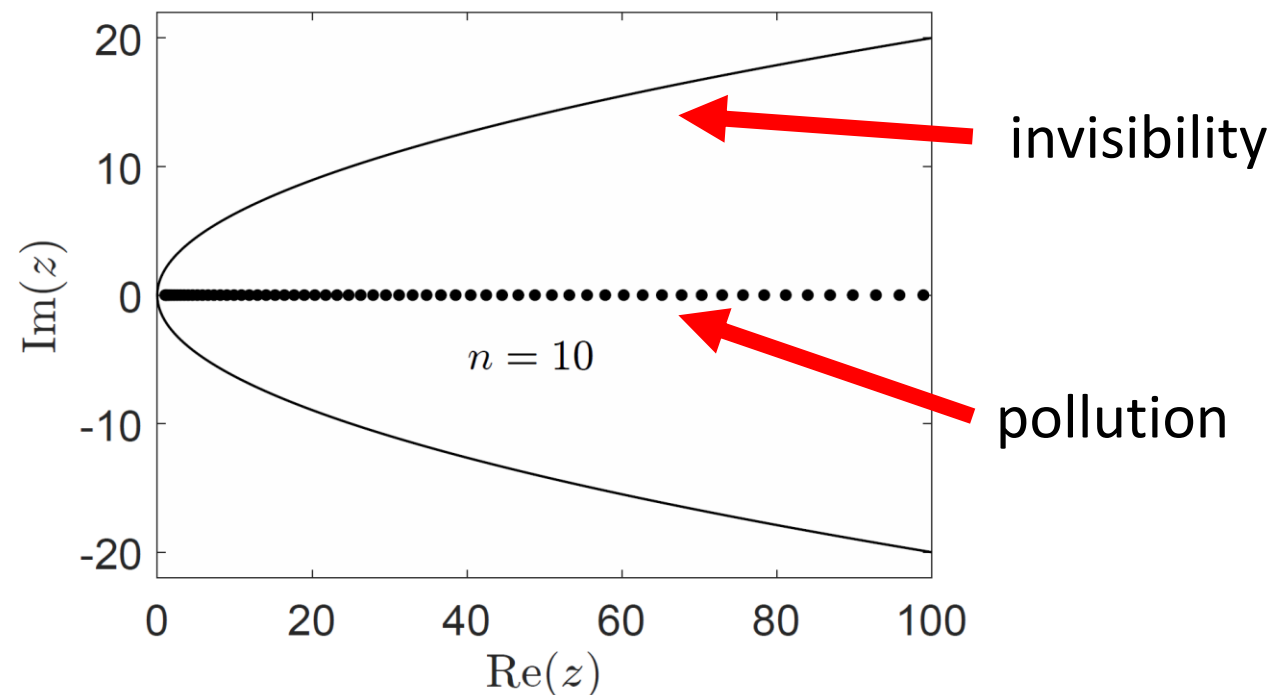
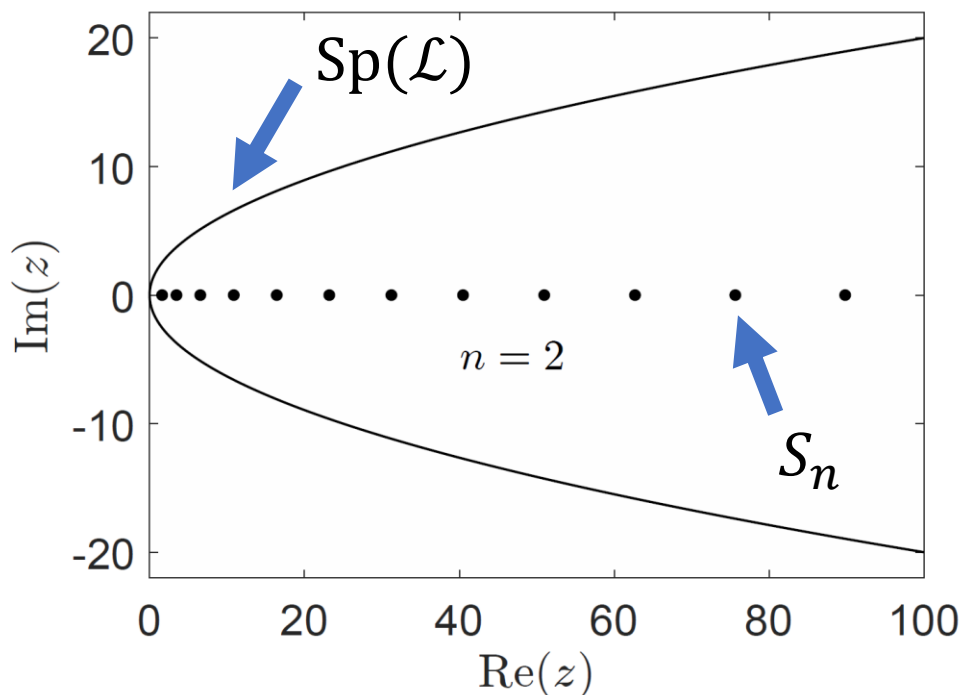
Currently no known characterization of invisibility  
(i.e., no analog to  $W_e(A)$  for spectral pollution).

# Spectral invisibility

- Convection-diffusion operator (normal) on  $L^2(\mathbb{R})$ :

$$\mathcal{L}u = -\frac{d^2u}{dx^2} - 2\frac{du}{dx}, \quad \text{Sp}(\mathcal{L}) = \{k^2 + 2ki : k \in \mathbb{R}\}$$

- Truncate to  $[-n, n]$  + Dirichlet BCs,  $S_n = \left\{1 + \frac{m^2\pi^2}{4n^2} : m \in \mathbb{N}\right\}$





A method that always works...

# Sketch of method

Lipschitz-1  
in  $z$  and  $A$

Spectra through  
injection moduli  
(smallest singular value)

$$\sigma_{\inf}(A) = \inf\{\|Av\|: v \in \mathfrak{D}(A), \|v\| = 1\}$$

$$\gamma(z, A) = \|(A - zI)^{-1}\|^{-1} = \min\{\sigma_{\inf}(A - zI), \sigma_{\inf}(A^* - \bar{z}I)\}$$

$$\text{Sp}(A) = \{z \in \mathbb{C}: \gamma(z, A) = 0\}$$

**Idea:**  $\mathcal{P}_n$  = orthog-projection onto  $\text{span}\{e_1, \dots, e_n\}$ .

Rectangular finite section.

$$\gamma_{n,m}(z, A) = \min\{\sigma_{\inf}(\mathcal{P}_m(A - zI)\mathcal{P}_n), \sigma_{\inf}(\mathcal{P}_m(A^* - \bar{z})\mathcal{P}_n)\}$$

$$\gamma_n(z, A) = \min\{\sigma_{\inf}((A - zI)\mathcal{P}_n), \sigma_{\inf}((A^* - \bar{z})\mathcal{P}_n)\}$$

**Dini's theorem:**  $\gamma_{n,m} \uparrow_{m \rightarrow \infty} \gamma_n \downarrow_{n \rightarrow \infty} \gamma$  uniformly on compacts

# Sketch of method

Hausdorff metric captures avoidance of pollution/invisibility:

$$d_H(X, Y) = \max \left\{ \sup_{x \in X} \inf_{y \in Y} |x - y|, \sup_{y \in Y} \inf_{x \in X} |x - y| \right\}$$

Algorithm that converges in **3 limits**:

$$\Gamma_{n_3, n_2, n_1}(A) = \left\{ z \in \frac{1}{n_2} (\mathbb{Z} + i\mathbb{Z}) : |z| \leq n_2, \gamma_{n_2, n_1}(z, A) + \frac{1}{n_2} \leq \frac{1}{n_3} \right\}$$

$$\lim_{n_2 \rightarrow \infty} \lim_{n_1 \rightarrow \infty} \Gamma_{n_3, n_2, n_1}(A) = \text{Sp}_{\frac{1}{n_3}}(A), \quad \lim_{n_3 \rightarrow \infty} \text{Sp}_{\frac{1}{n_3}}(A) = \text{Sp}(A)$$

$$\text{Sp}_\epsilon(A) = \{z \in \mathbb{C} : \gamma(z, A) \leq \epsilon\}$$

# Sketch of method

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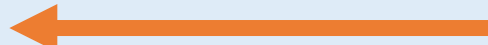
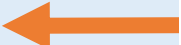
**Can we do better (than 3 limits)?**

$$\operatorname{Sp}_\epsilon(A) = \{z \in \mathbb{C} : \gamma(z, A) \leq \epsilon\}$$

A mathematical structure...

# Computational problem

**Definition:** A *computational problem* is a collection  $\{\Xi, \Omega, \mathcal{M}, \Lambda\}$  consisting of:

- Input class  $\Omega$ ;  E.g.,  $\Omega = \mathcal{B}(l^2(\mathbb{N}))$
- Metric space  $(\mathcal{M}, d)$ ;  E.g.,  $\mathcal{M} = \mathcal{M}_H$  (Hausdorff metric)
- Problem function  $\Xi: \Omega \rightarrow \mathcal{M}$ ;  Thing we want to compute E.g.,  $\Xi = \text{Sp}$
- Evaluation set,  $\Lambda$ , of  $\mathbb{C}$ -valued functions on  $\Omega$ ;

such that for  $A, B \in \Omega$ :

$$f(A) = f(B) \quad \forall f \in \Lambda \quad \Rightarrow \quad \Xi(A) = \Xi(B).$$

Info available to algorithms  
E.g. Matrix entries

$\Xi(A)$  determined by  $\{f(A): f \in \Lambda\}$

# General algorithm (consistency)

Info algorithm  
reads on input  $A$ .



**Definition:** Given  $\{\mathcal{E}, \Omega, \mathcal{M}, \Lambda\}$ , a general algorithm is a map  $\Gamma: \Omega \rightarrow \mathcal{M}$  such that for any  $A \in \Omega$ , there exists  $\Lambda_\Gamma(A) \subset \Lambda$  finite and non-empty such that for  $A, B \in \Omega$ ,

$$f(A) = f(B) \quad \forall f \in \Lambda_\Gamma(A) \Rightarrow \Lambda_\Gamma(A) = \Lambda_\Gamma(B), \Gamma(A) = \Gamma(B)$$

Can also consider restrictions (e.g., Turing or BSS machine)

Impossibility result for gen. alg.  $\Rightarrow$  impossibility result in any model



# Solvability Complexity Index Hierarchy

- $\Delta_0$ : Solved in finite time (v. rare for cts problems).
- $\Delta_1$ : Solved in “one limit” with full error control:

$$d(\Gamma_n(A), \mathbb{E}(A)) \leq 2^{-n}$$

- $\Delta_2$ : Solved in “one limit”:

$$\lim_{n \rightarrow \infty} \Gamma_n(A) = \mathbb{E}(A)$$

- $\Delta_3$ : Solved in “two successive limits”:

$$\vdots \quad \lim_{n \rightarrow \infty} \lim_{m \rightarrow \infty} \Gamma_{n,m}(A) = \mathbb{E}(A)$$

Can work in *any* model. E.g., BSS machine, Turing machine, interval arithmetic, inexact input etc.

- Ben-Artzi, C., Hansen, Nevanlinna, Seidel, “*On the solvability complexity index hierarchy and towers of algorithms*,” preprint.
- Hansen, “*On the solvability complexity index, the  $n$ -pseudospectrum and approximations of spectra of operators*,” **J. Amer. Math. Soc.**, 2011.

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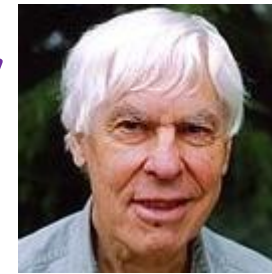
$$d(\Gamma_n(A), \Xi(A)) \leq 2^{-n}$$

- $\Delta_2$ : Solved in “one limit”:

$$\lim_{n \rightarrow \infty} \Gamma_n(A) = \Xi(A)$$

- $\Delta_3$ : Solved in “two successive limits”:

$$\lim_{n \rightarrow \infty} \lim_{m \rightarrow \infty} \Gamma_{n,m}(A) = \Xi(A)$$



Steve Smale  
(Berkeley, Fields Medal 1966)

Smale: “Is there any purely<sup>24</sup> rational iterative generally convergent algorithm for polynomial zero finding?”



Curt McMullen  
(Harvard, Fields Medal 1998)

McMullen: “Yes, if the degree is three; no, if the degree is higher.”



Peter Doyle  
(Dartmouth)

Doyle & McMullen: “The problem can be solved using successive limits for the quartic and quintic, but not the sextic.”

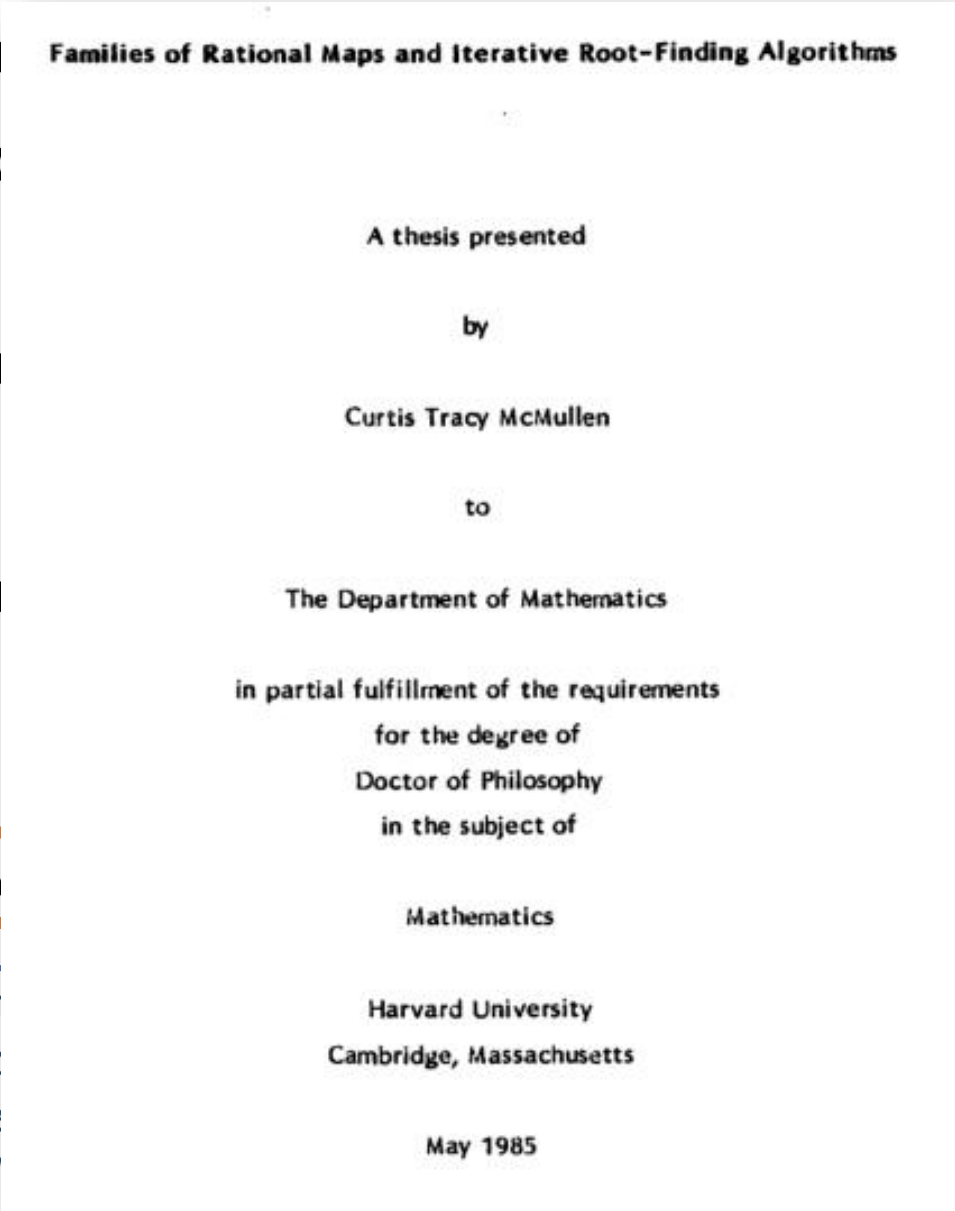
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- McMullen, “Families of rational maps and iterative root-finding algorithms,” **Ann. of Math.**, 1987.
- Doyle, McMullen, “Solving the quintic by iteration,” **Acta Math.**, 1989.
- Smale, “The fundamental theorem of algebra and complexity theory,” **Bull. Amer. Math. Soc.**, 1981.

# Solvability Complexity Index Hierarchy

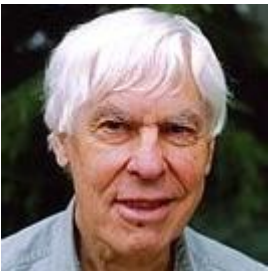
- $\Delta_0$ : Solved
- $\Delta_1$ : Solved
- $\Delta_2$ : Solved
- $\Delta_3$ : Solved
- $\vdots$

Can work in



problems).

Control:



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- "Approximations of spectra of operators," **J. Amer. Math. Soc.**, 2011.
- "Algorithms," **Ann. of Math.**, 1987.
- 9.

# Why no proven techniques (Arveson)?

$\mathcal{E}'$ :  $B \in \{0,1\}^{\mathbb{N} \times \mathbb{N}} = \Omega'$ , does  $B$  have finitely many cols with finitely many 1s?

Descriptive set theory + SCI  $\implies \{\mathcal{E}', \Omega', \{0,1\}, \Lambda\} \notin \Delta_3$

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Descriptive set theory + SCI  $\Rightarrow \{\mathcal{E}', \Omega', \{0,1\}, \Lambda\} \notin \Delta_3$

For  $\alpha \in \{0,1\}^{\mathbb{Z}}$  define

$$[C(\alpha)]_{k,l} = \begin{cases} 1, & k < l, \alpha_k = \alpha_l = 1, \alpha_n = 0 \text{ for } k < n < l \\ 0, & \text{otherwise.} \end{cases}$$

shift on  $\text{span}\{e_i : \alpha_i = 1\}$

Given  $B \in \{0,1\}^{\mathbb{N} \times \mathbb{N}}$  set

$$A(B) = \bigoplus_{j=1}^{\infty} C(\alpha_i^{(j)}), \quad \alpha_i^{(j)} = \begin{cases} 1, & |i| \leq j \\ B_{|i|-j,j}, & \text{otherwise.} \end{cases}$$

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If  $\Xi'(B) = 1$ ,  $\text{Sp}(B) = \{0\} \cup \mathbb{T}$ . Otherwise  $\text{Sp}(B) = \{z : |z| \leq 1\}$ .

If classical spectral problem  $\in \Delta_3$ , so is  $\{\Xi', \Omega', \{0,1\}, \Lambda\}$ , contradiction!

What about additional structure?  
Computing spectra with error control...




# Motivation: bounded diagonal operators

$$A = \begin{pmatrix} a_1 & & \\ & a_2 & \\ & & \ddots \end{pmatrix}$$

$\Lambda$ : Matrix entries of  $A$  (*readable info*)

**Algorithm:**  $\Gamma_n(A) = \{a_1, a_2, \dots, a_n\} \rightarrow \text{Sp}(A) = \overline{\{a_1, a_2, \dots\}}$  in Haus. Metric.

**One-sided error control:**  $\Gamma_n(A) \subset \text{Sp}(A)$

$$d_H(\Gamma_n(A), \text{Sp}(A)) = \max \left\{ \sup_{x \in \Gamma_n(A)} d(x, \text{Sp}(A)), \sup_{y \in \text{Sp}(A)} d(y, \Gamma_n(A)) \right\}$$



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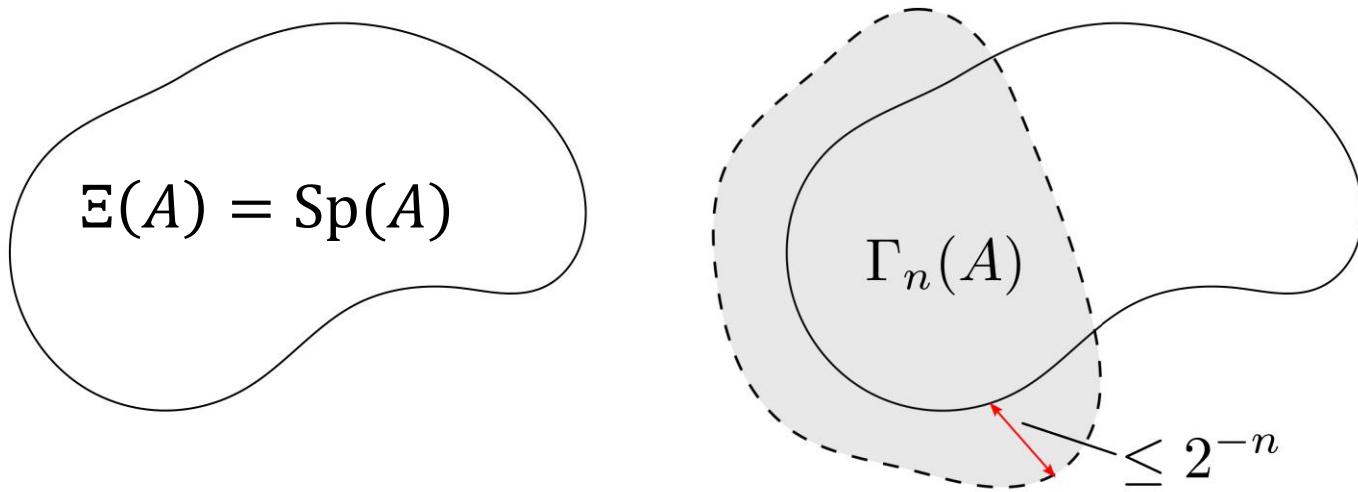
$$d_H(\Gamma_n(A), \text{Sp}(A)) = \max \left\{ \sup_{x \in \Gamma_n(A)} d(x, \text{Sp}(A)), \sup_{y \in \text{Sp}(A)} d(y, \Gamma_n(A)) \right\}$$


**But:** No algorithm with  $\hat{\Gamma}_n(A) \rightarrow \text{Sp}(A)$  with  $\text{Sp}(A) \subset \hat{\Gamma}_n(A)$ .

# Error control for spectral problems

$$d_H(X, Y) = \max \left\{ \sup_{x \in X} d(x, Y), \sup_{y \in Y} d(y, X) \right\}$$

$\Sigma_1$  convergence



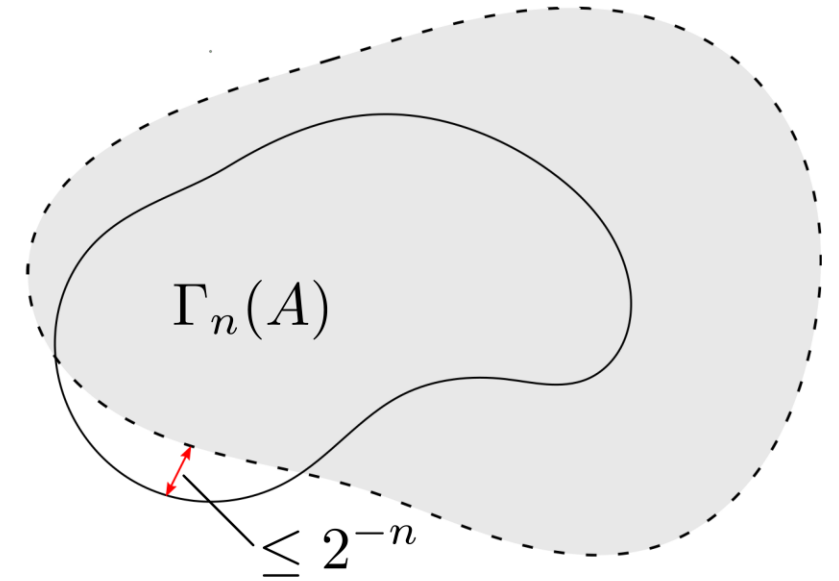
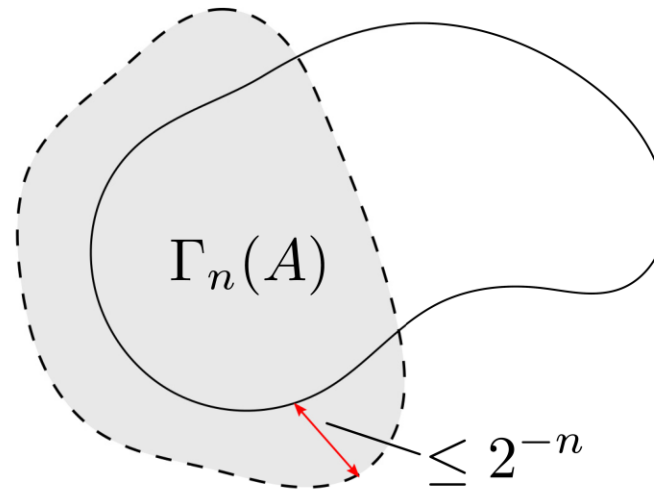
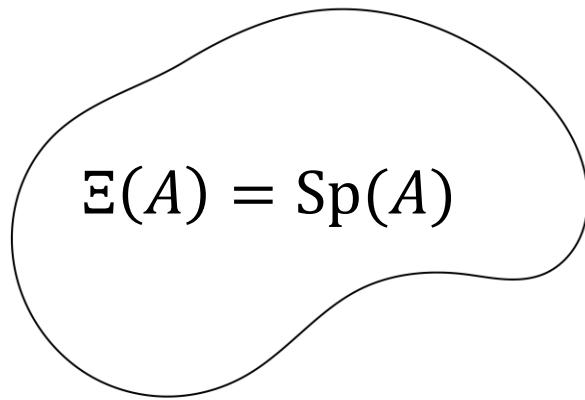
- $\Sigma_1: \exists \text{ alg. } \{\Gamma_n\} \text{ s.t. } \lim_{n \rightarrow \infty} \Gamma_n(A) = \Xi(A), \max_{z \in \Gamma_n(A)} \text{dist}(z, \Xi(A)) \leq 2^{-n}$

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$\Pi_1$  convergence



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**Such problems can be used in a proof!**

# Reasons it's hard I

$$A = \bigoplus_{r=1}^{\infty} J_{l_r}, \quad J_{l_r} = \begin{pmatrix} 0 & 1 & & \\ & 0 & \ddots & \\ & & \ddots & 1 \\ & & & 0 \end{pmatrix} \in \mathbb{C}^{l_r \times l_r}$$

**Instability**

$$\text{Sp}(A) = \begin{cases} \{0\}, & \sup l_r < \infty \\ \{z: |z| \leq 1\}, & \text{otherwise} \end{cases}$$

No  $\{\Gamma_n\}$  when given  $\{l_r\}_{r=1}^{\infty}$  can determine if it is bounded.

$\Rightarrow$  No  $\{\Gamma_n\}$  computes spectra of gen. tridiagonal operators.

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**Always have:**  $\|(A - zI)^{-1}\|^{-1} \leq \text{dist}(z, \text{Sp}(A))$

**Extra assumption:**  $g(\text{dist}(z, \text{Sp}(A))) \leq \|(A - zI)^{-1}\|^{-1}$

known cts. bijection

$$g: \mathbb{R}_{>0} \rightarrow \mathbb{R}_{>0}$$



## Reasons it's hard II

$$A = \bigoplus_{r=1}^{\infty} A_{l_r}, \quad A_{l_r} = \begin{pmatrix} 1 & & & & 1 \\ & 0 & & & \\ & & \ddots & & \\ & & & 0 & \\ 1 & & & & 1 \end{pmatrix} \in \mathbb{C}^{l_r \times l_r}$$

Info at  $\infty$

$$\text{Sp}(A) = \{0, 2\}, \quad \text{Sp}(\text{diag}(1, 0, \dots)) = \{0, 1\}$$

More involved: Suppose for a contradiction  $\{\Gamma_n\}$  converges, choose  $\{l_r\}_{r=1}^{\infty}$  so  $\Gamma_n(A)$  does not converge (try it!)

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More involved: Suppose for a contradiction  $\{\Gamma_n\}$  converges, choose  $\{l_r\}_{r=1}^{\infty}$  so  $\Gamma_n(A)$  does not converge (try it!)

**Assume access to  $\langle Ae_j, e_i \rangle$ ,  $\langle Ae_j, Ae_i \rangle$ ,  $\langle A^*e_j, A^*e_i \rangle$**

# Sketch of method with error control ( $\in \Sigma_1$ )

$$\sigma_{\inf}(A) = \inf\{\|Av\|: v \in \mathfrak{D}(A), \|v\| = 1\}$$

$$\gamma(z, A) = \|(A - zI)^{-1}\|^{-1} = \min\{\sigma_{\inf}(A - zI), \sigma_{\inf}(A^* - \bar{z}I)\}$$

$$\mathcal{P}_n = \text{orthog-projection onto } \text{span}\{e_1, \dots, e_n\}$$

**Idea:**  $\sqrt{\sigma_{\inf}(\mathcal{P}_n(A - zI)^*(A - zI)\mathcal{P}_n)} = \sigma_{\inf}([A - zI]\mathcal{P}_n) \downarrow \sigma_{\inf}(A - zI)$

$$g^{-1}(\min\{\sigma_{\inf}([A - zI]\mathcal{P}_n), \sigma_{\inf}([A^* - \bar{z}I]\mathcal{P}_n)\}) \downarrow g^{-1}(\|(A - zI)^{-1}\|^{-1}) \geq \text{dist}(z, \text{Sp}(A))$$

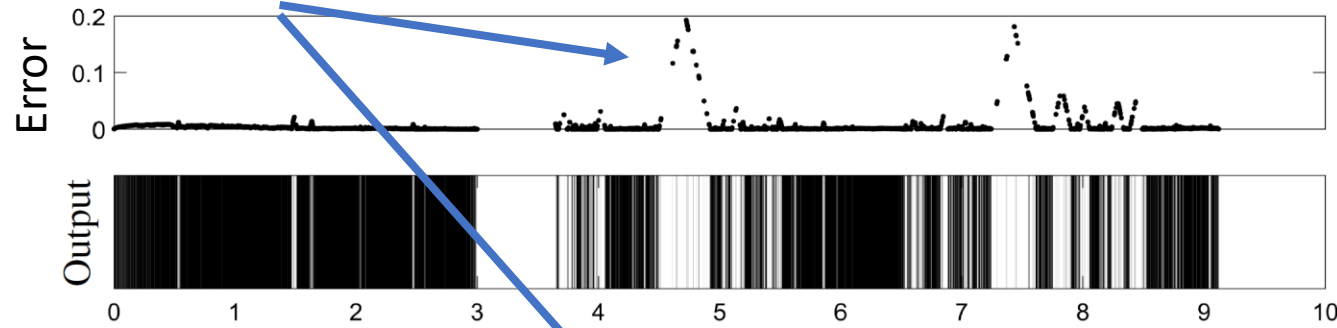
$$\|(A - z)^{-1}\|^{-1} \geq g(\text{dist}(z, \text{Sp}(A)))$$

**Final ingredient:** adaptive search for local minimisers.

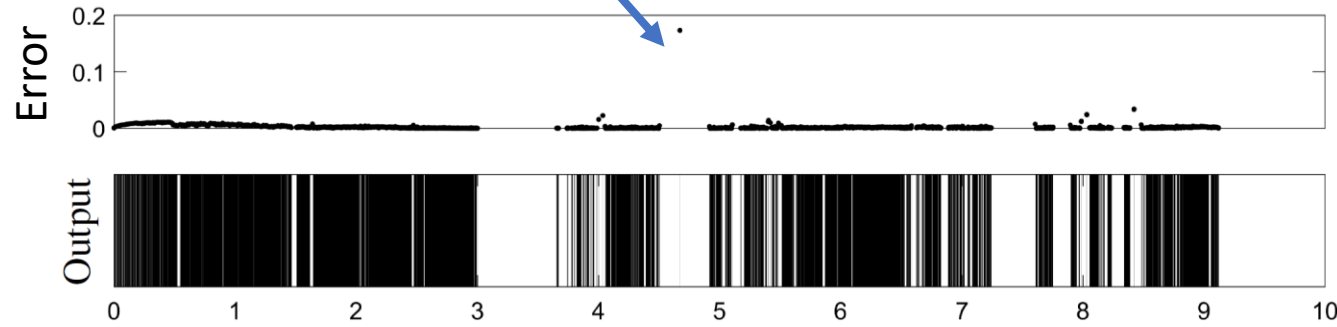
# Example: Quasicrystal

spectral pollution

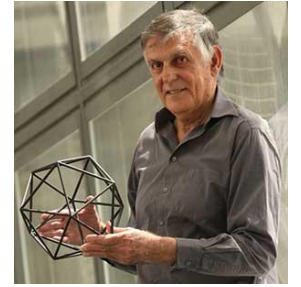
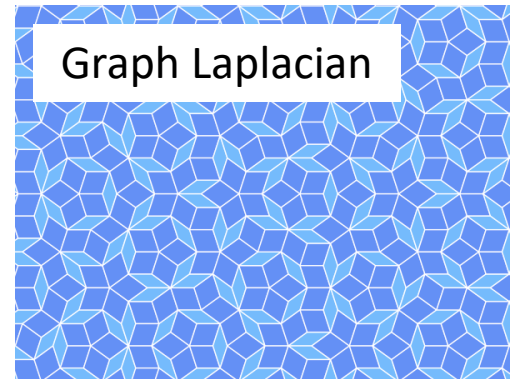
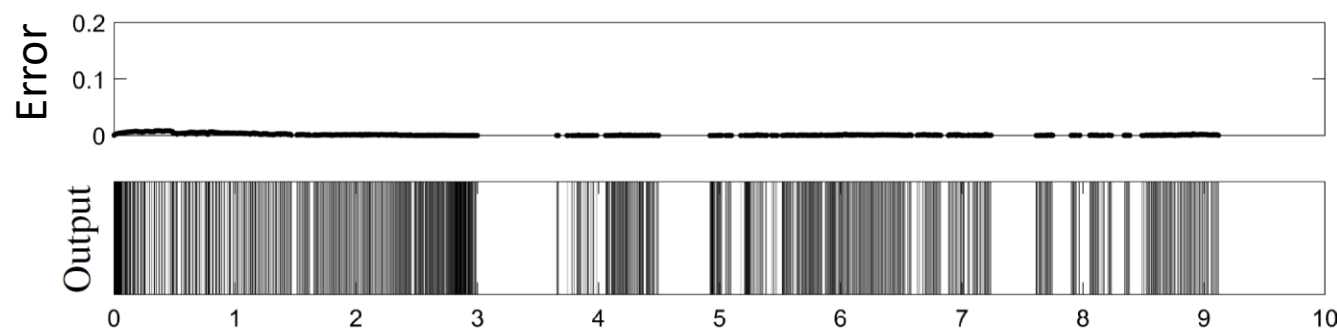
Finite Section



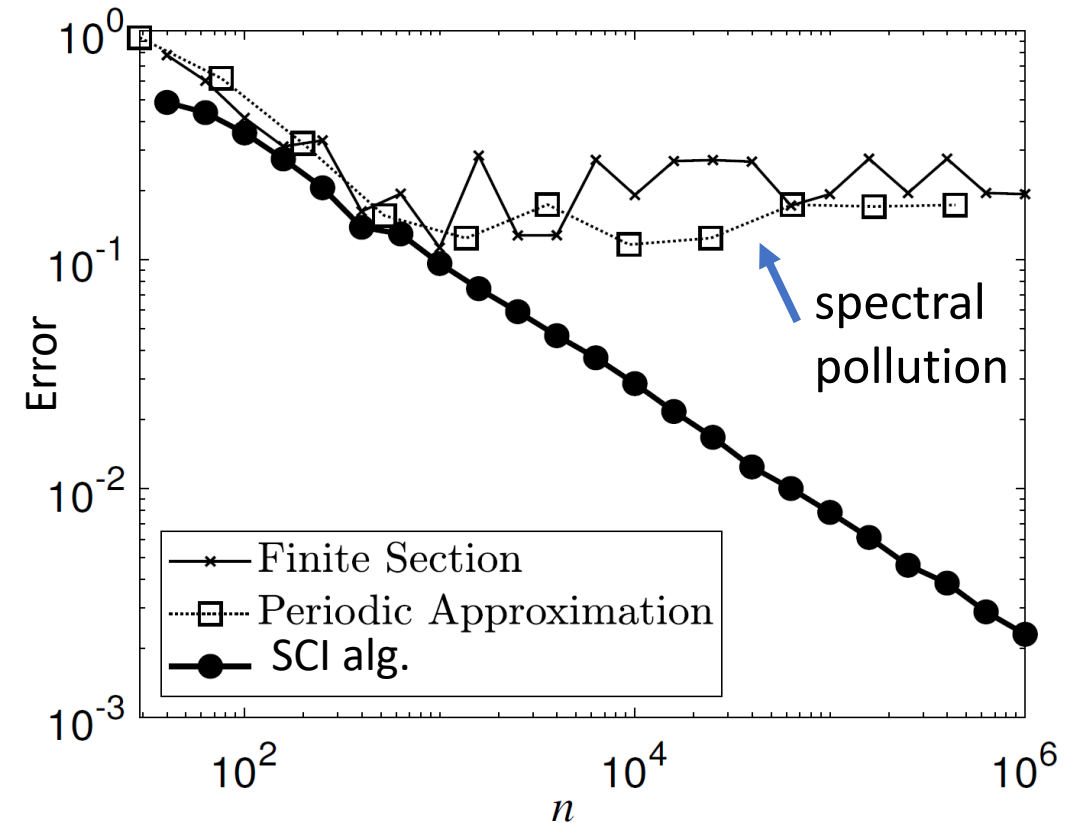
Periodic Approximation



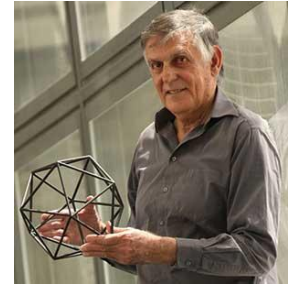
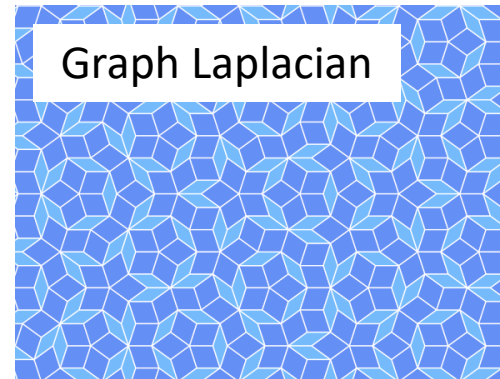
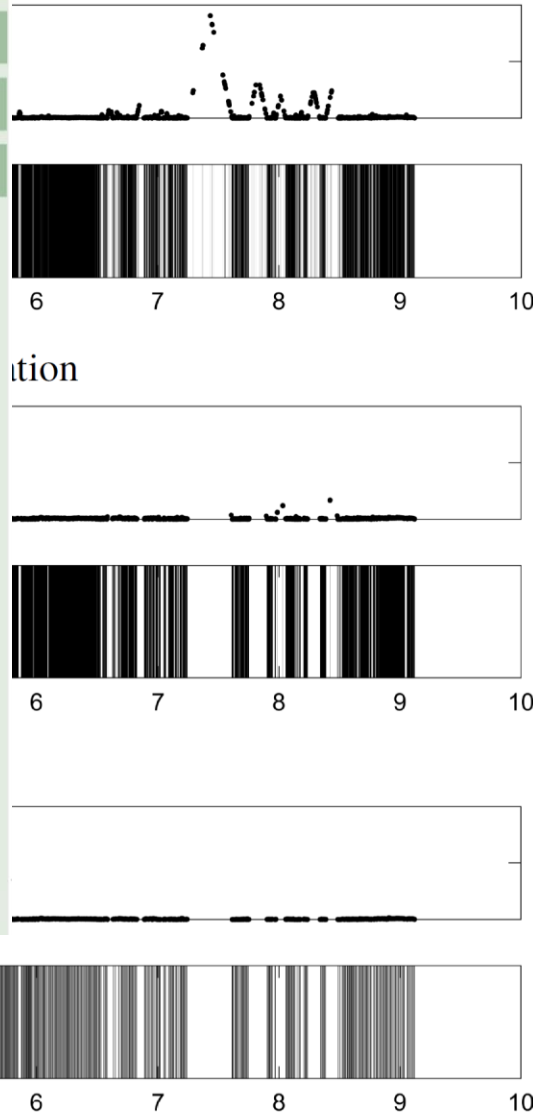
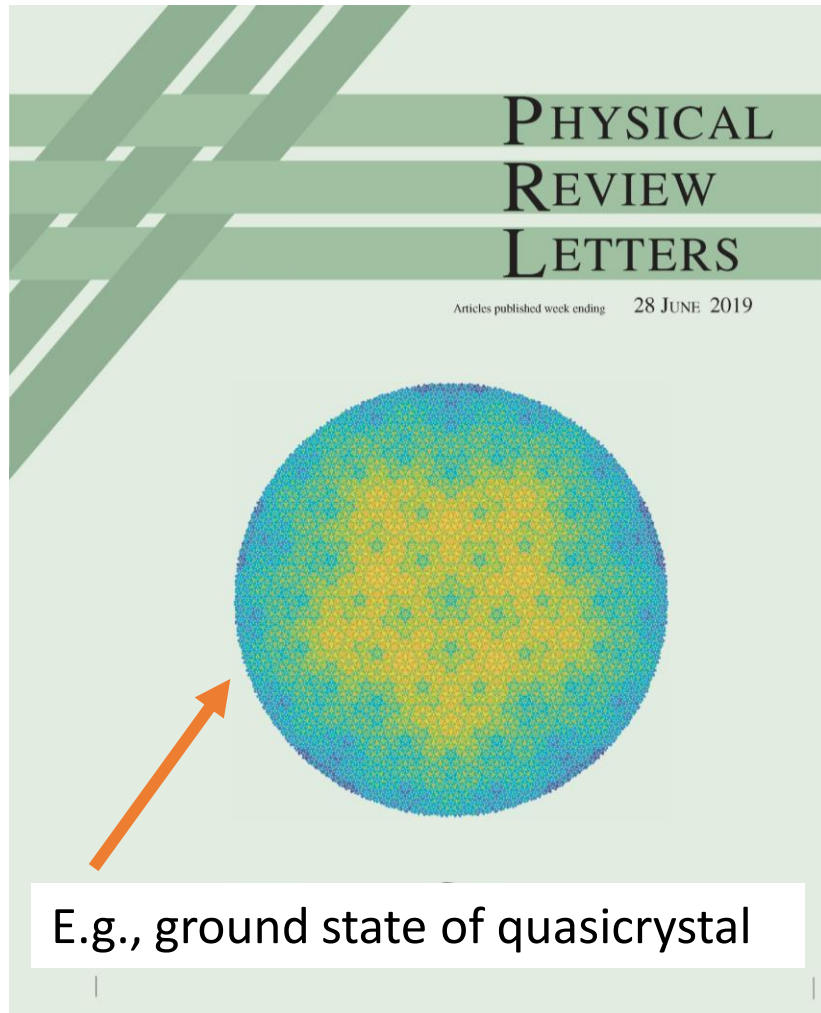
SCI alg.



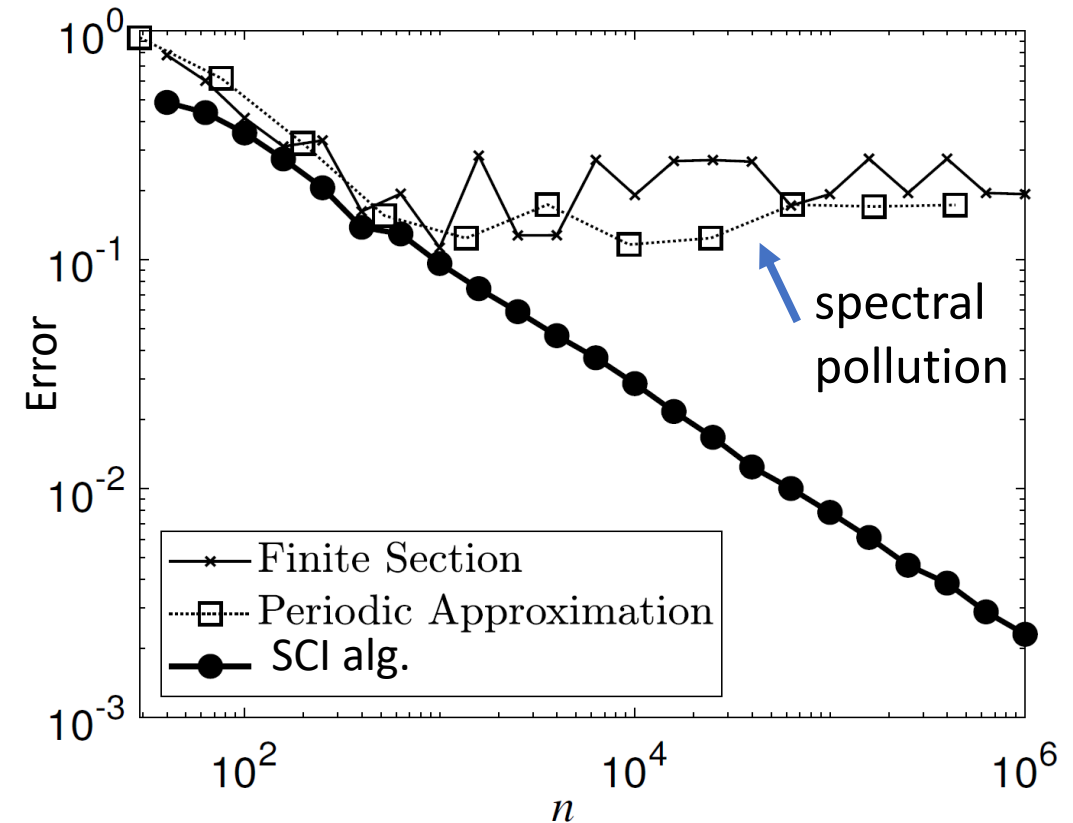
Dan Shechtman  
(Iowa State, Nobel Prize  
in Chemistry 2011)



# Example: Quasicrystal



Dan Shechtman  
(Iowa State, Nobel Prize  
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# Schwinger's problem

**Theorem:**  $\Omega$ : class of self-adjoint diff. operators on  $L^2(\mathbb{R}^d)$

$$T = \sum_{k \in \mathbb{Z}_{\geq 0}^d, |k| \leq N} c_k(x) \partial^k$$

- $C_0^\infty(\mathbb{R}^d)$  a core of  $T$ .
- $\{c_k\}$  poly bounded, locally bounded total variation.

Can access:

- $\{c_k(q)\}$  for  $q \in \mathbb{Q}^d$ .
- Polynomial that bounds  $\{c_k\}$  on  $\mathbb{R}^d$ .

(a) Know  $\|c_k\|_{\text{TV}([-n,n]^d)} \leq b_n \Rightarrow \{\text{Sp}, \Omega\} \in \Sigma_1$ .

(b) Know  $\|c_k\|_{\text{TV}([-n,n]^d)} = O(b_n) \Rightarrow \{\text{Sp}, \Omega\} \in \Delta_2 \setminus (\Sigma_1 \cup \Pi_1)$ .

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Sampling schemes  
to construct matrix.

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Can access:

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- Polynomial that bounds  $\{c_k\}$  on  $\mathbb{R}^d$ .

Extends to other domains,  
singular coefficients etc.

(a) Know  $\|c_k\|_{\text{TV}([-n,n]^d)} \leq b_n \Rightarrow \{\text{Sp}, \Omega\} \in \Sigma_1$ .

**Verifiable**

(b) Know  $\|c_k\|_{\text{TV}([-n,n]^d)} = O(b_n) \Rightarrow \{\text{Sp}, \Omega\} \in \Delta_2 \setminus (\Sigma_1 \cup \Pi_1)$ .

**Not verifiable**





Carl Bender

(Washington, MIT, Heineman Prize 2017)



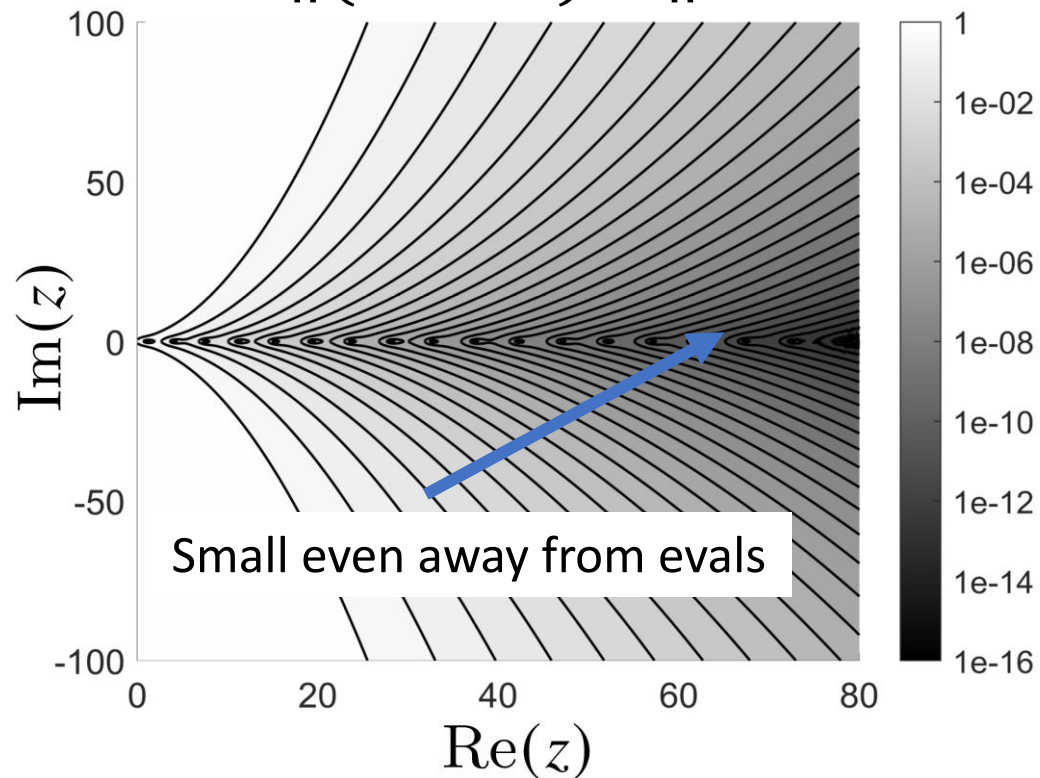
Michael Berry

(Bristol, Wolf Prize 1998)

# Non-self-adjoint example with non-trivial $g$

$$T = -\frac{d^2}{dx^2} + ix^3 \text{ on } \mathbb{R}$$

$$\|(T - zI)^{-1}\|^{-1}$$

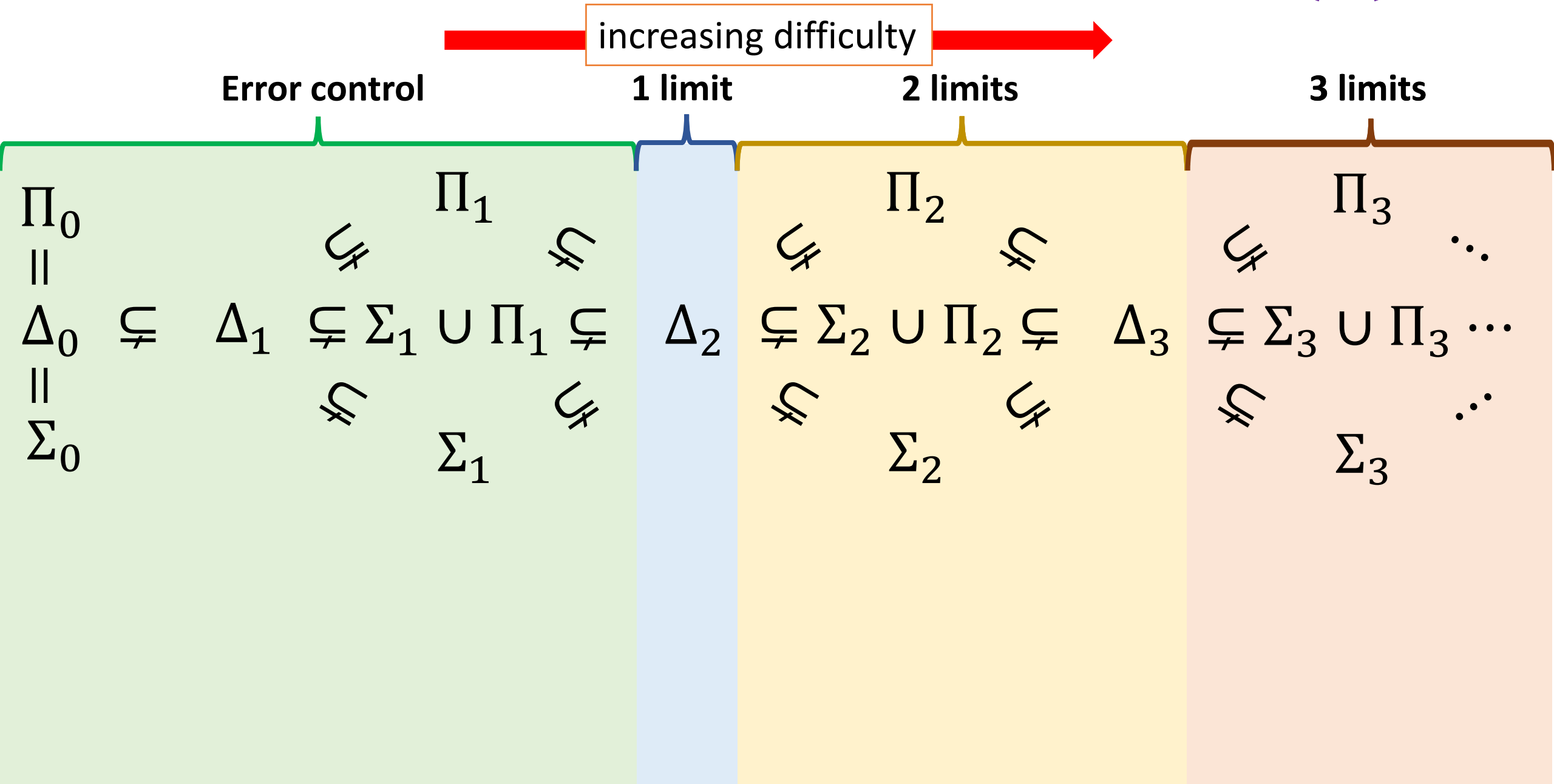


$j$   $E_j$  to 30 digits with interval arithmetic

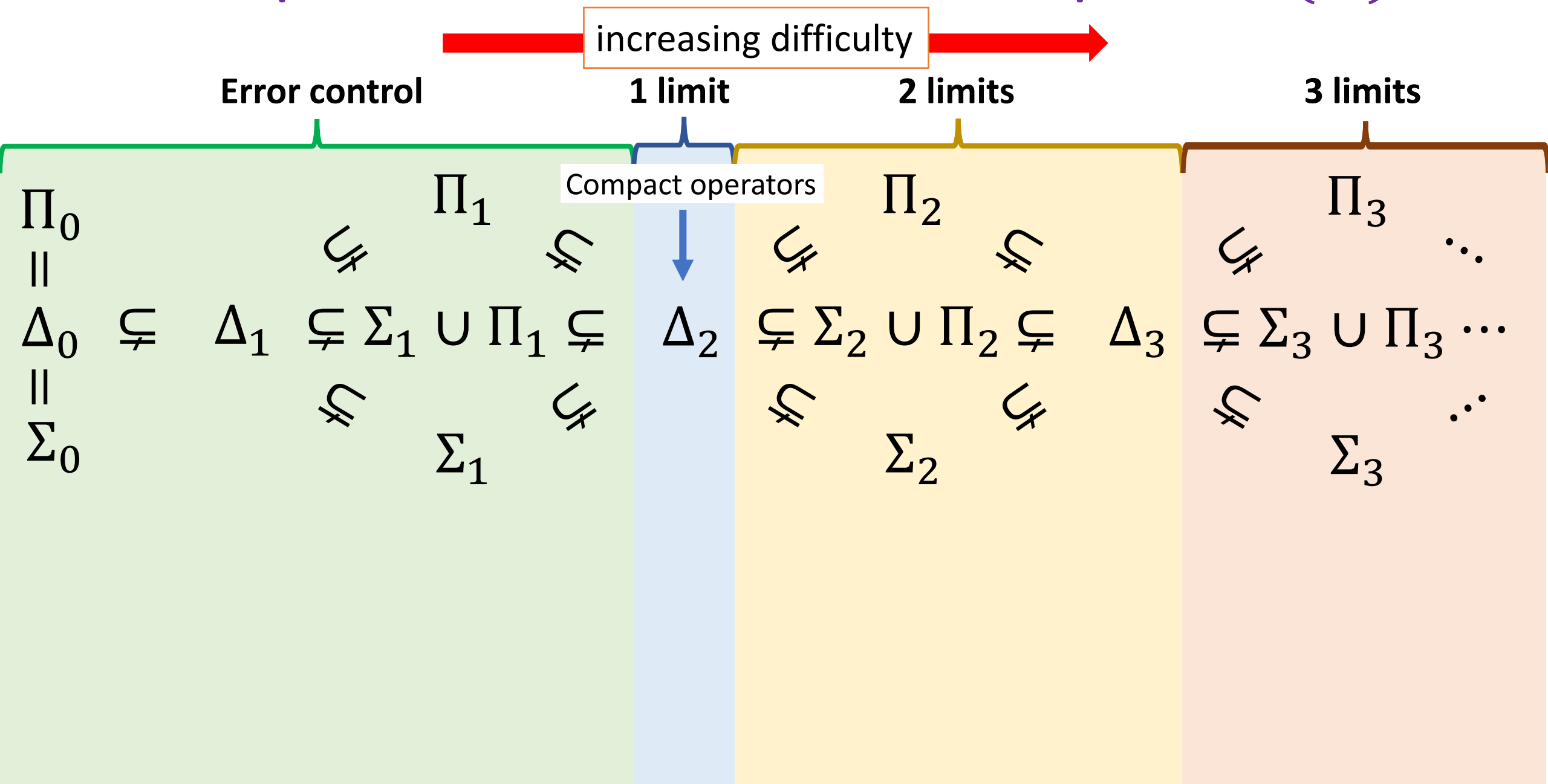
1	1.156 267 071 988 113 293 799 219 177 999 9
2	4.109 228 752 809 651 535 843 668 478 561 3
3	7.562 273 854 978 828 041 351 809 110 631 4
4	11.314 421 820 195 804 402 233 783 948 426 9
5	15.291 553 750 392 532 388 181 630 791 751 9
6	19.451 529 130 691 728 314 686 111 714 104 4
7	23.766 740 435 485 819 131 558 025 968 789 9
8	28.217 524 972 981 193 297 595 053 878 268 9
9	32.789 082 781 862 957 492 447 371 485 046 3
10	37.469 825 360 516 046 866 428 873 594 530 5
100	627.694 712 248 436 511 352 673 702 901 153 6



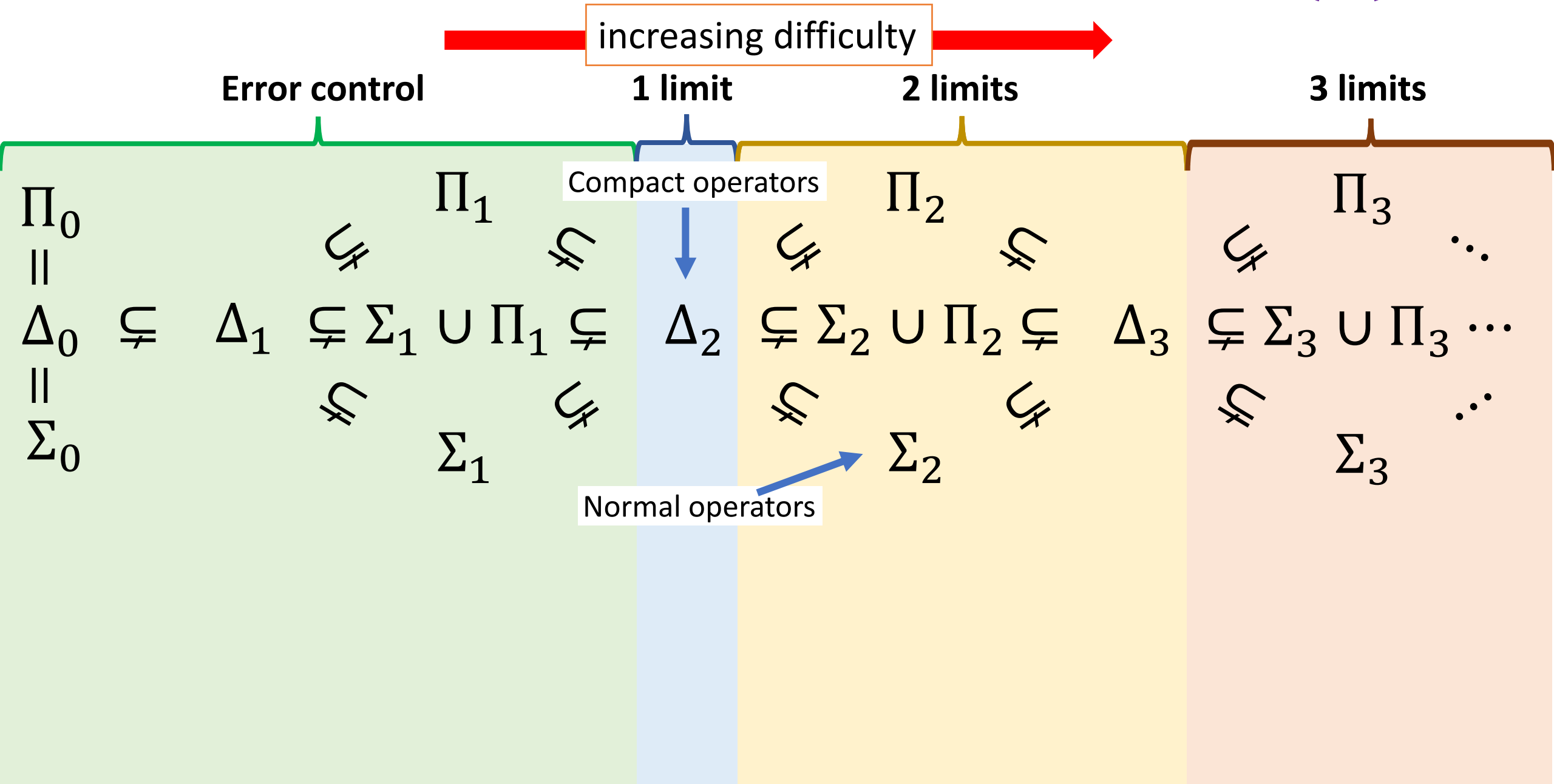
# Sampler of results for bounded op. on $l^2(\mathbb{N})$



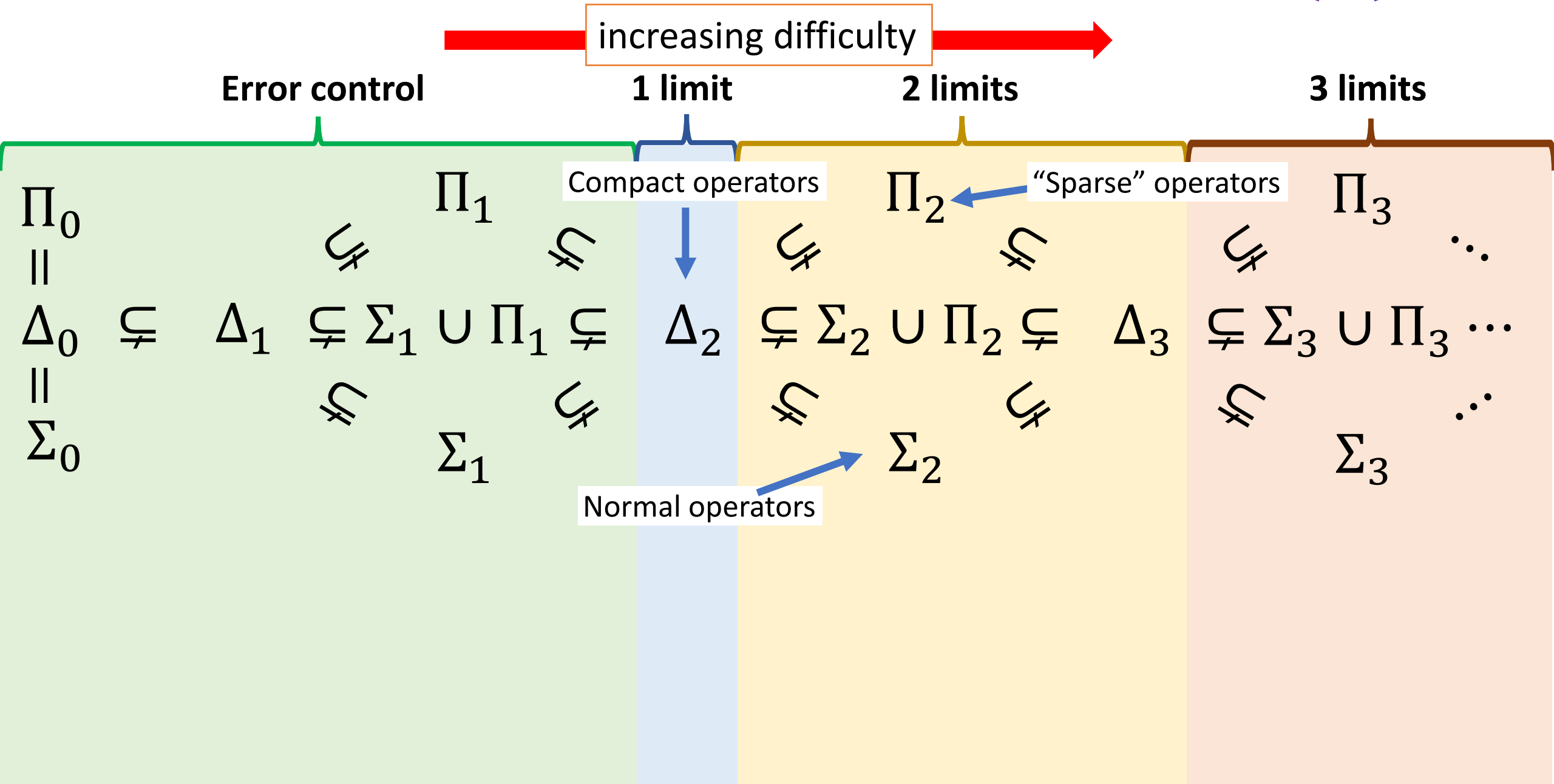
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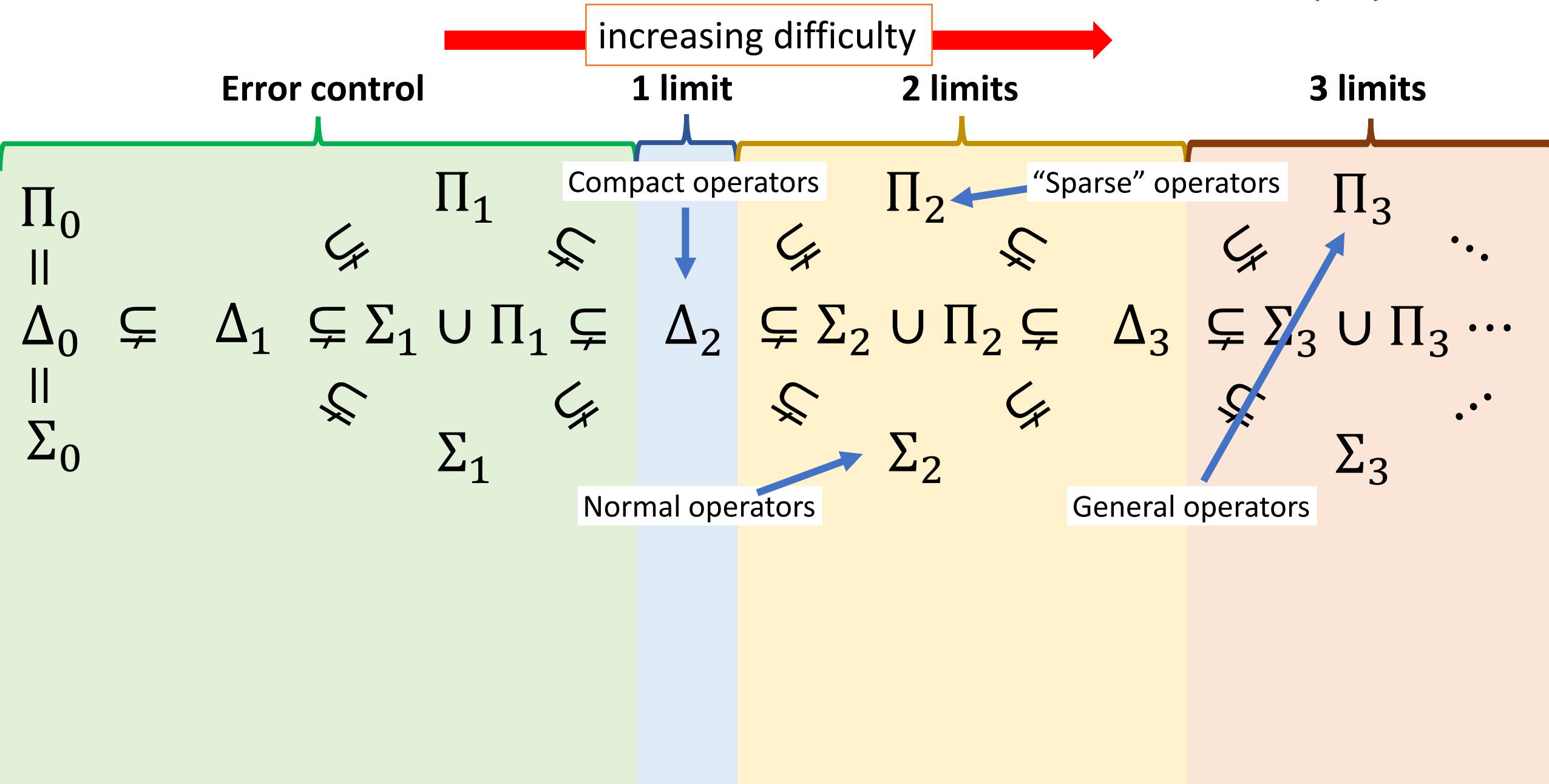
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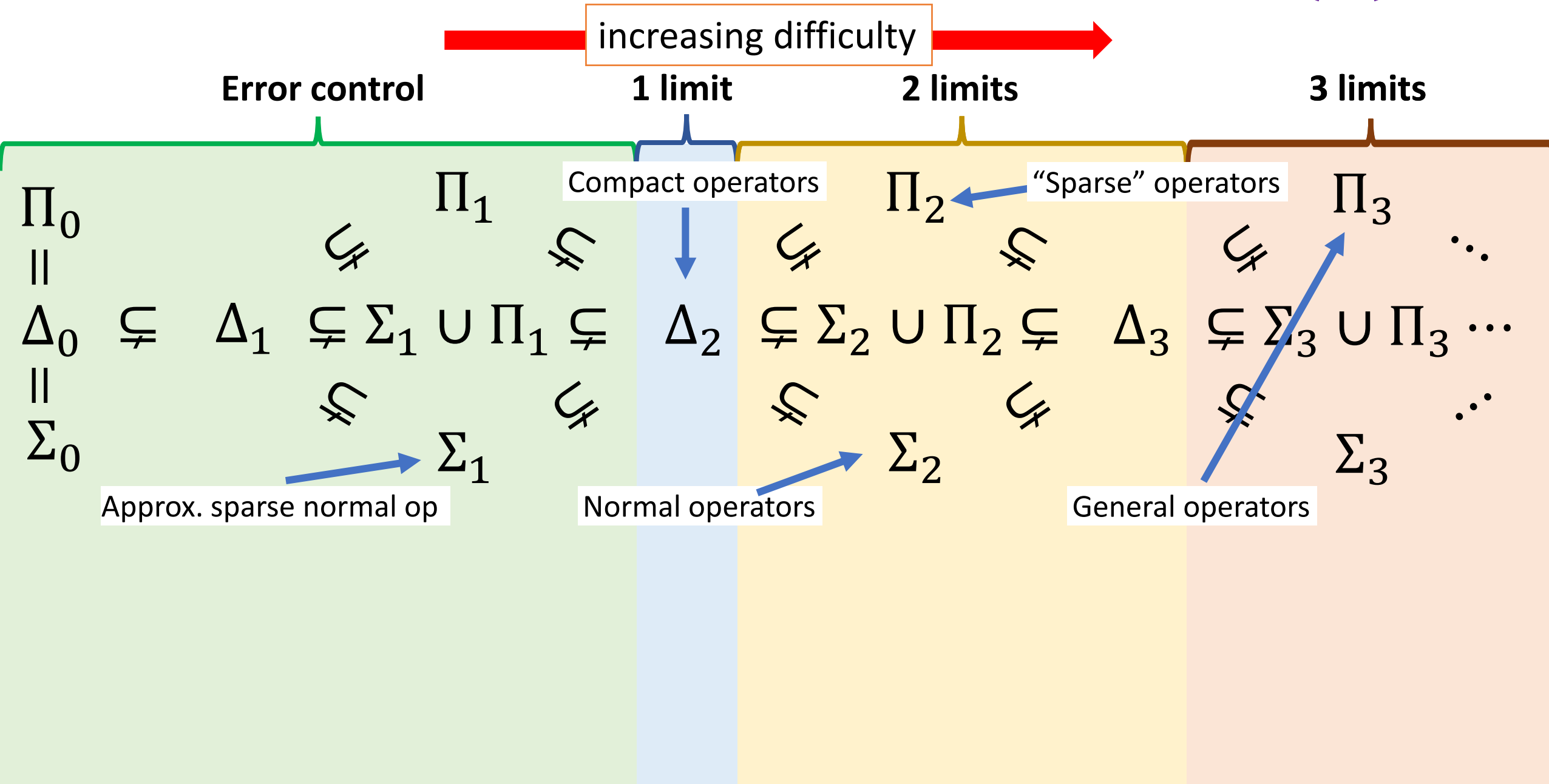
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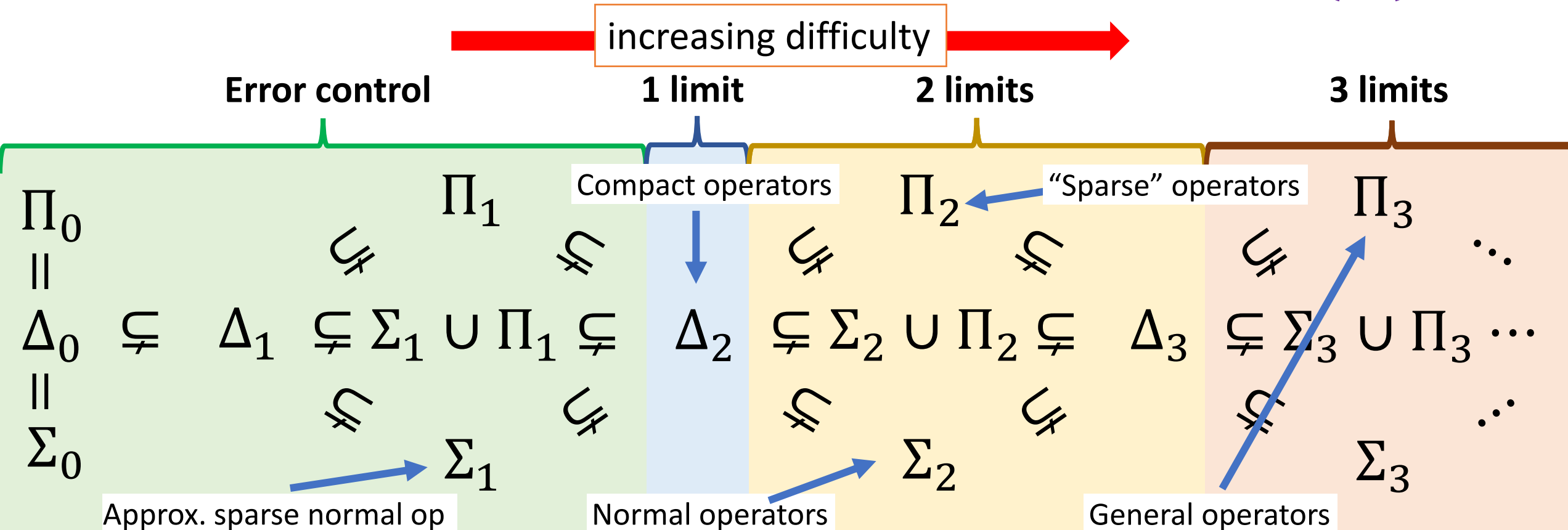
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**Zoo of problems:** spectral type (pure point, absolutely continuous, singularly continuous), Lebesgue measure and fractal dimensions of spectra, discrete spectra, essential spectra, eigenspaces + multiplicity, spectral radii, essential numerical ranges, geometric features of spectrum (e.g., capacity), spectral gap problem, resonances ...

Example: Analysis helps in applications in dynamical systems...



# Operator theory for dynamical systems

- Compact metric space  $(\mathcal{X}, d)$  – the state space
- $x \in \mathcal{X}$  – the state

cts  $F: \mathcal{X} \rightarrow \mathcal{X}$  – the dynamics:  $x_{n+1} = F(x_n)$

Henri Poincaré  
(Sorbonne)



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cts  $F: \mathcal{X} \rightarrow \mathcal{X}$  – the dynamics:  $x_{n+1} = F(x_n)$

- Borel measure  $\omega$  on  $\mathcal{X}$
- Function space  $L^2 = L^2(\mathcal{X}, \omega)$  (elements  $g$  called “observables”)
- Koopman operator  $\mathcal{K}_F: L^2 \rightarrow L^2; [\mathcal{K}_F g](x) = g(F(x))$

**NB:** Pointwise definition of  $\mathcal{K}_F$  needs  $F\#\omega \ll \omega$  – this will hold throughout.

**NB:**  $\mathcal{K}_F$  bounded equivalent to  $dF\#\omega/d\omega \in L^\infty$  – this will hold throughout (can be dropped).

Bernard Koopman  
(Columbia)



John von Neumann  
(IAS)



- Koopman, “Hamiltonian systems and transformation in Hilbert space,” **Proc. Natl. Acad. Sci. USA**, 1931.
- Koopman, v. Neumann, “Dynamical systems of continuous spectra,” **Proc. Natl. Acad. Sci. USA**, 1932.

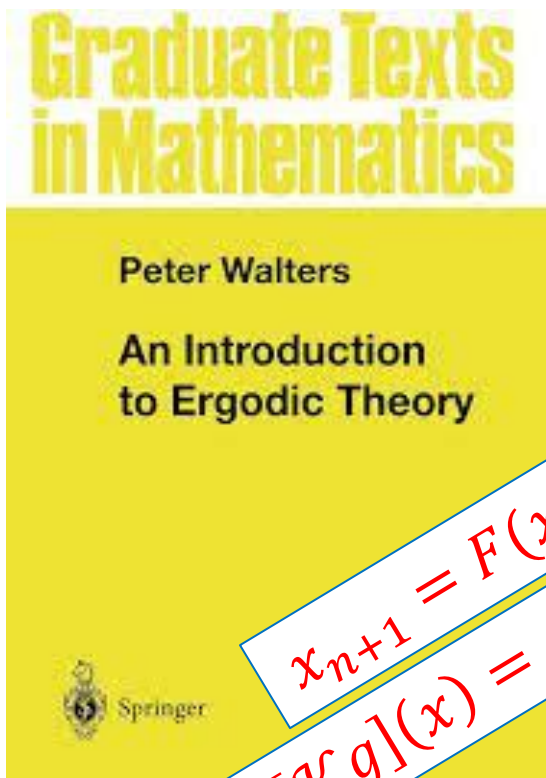
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- Unknown cts  $F: \mathcal{X} \rightarrow \mathcal{X}$  – the dynamics:  $x_{n+1} = F(x_n)$
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- Available snapshot data:  $\left\{ \left( x^{(m)}, y^{(m)} = F(x^{(m)}) \right) : m = 1, \dots, M \right\}$

**Can we compute spectral properties from sampling trajectories?**

# Fundamental object

Fundamental in ergodic theory



$$x_{n+1} = F(x_n)$$

$$[\mathcal{K}g](x) = g(F(x))$$

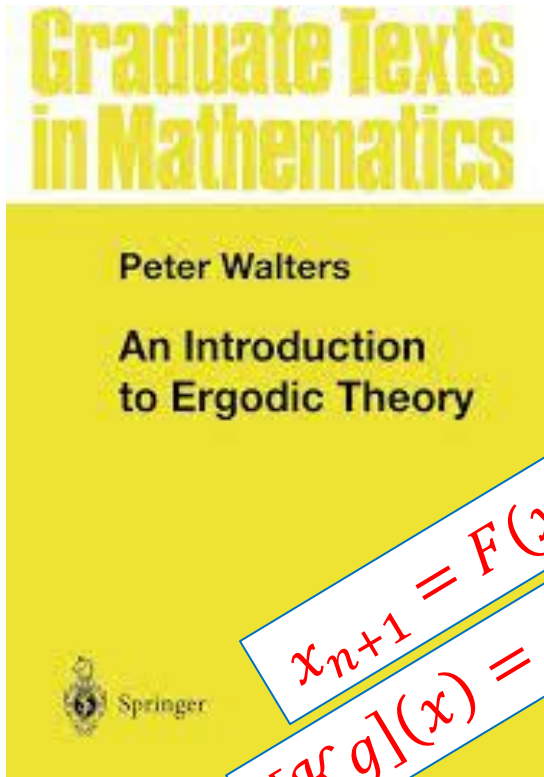
E.g., key to ergodic theorems of Birkhoff and von Neumann.

**Trades:** Nonlinear, finite-dimensional  $\Rightarrow$  Linear, infinite-dimensional.

# Fundamental object

Fundamental in ergodic theory

Can provide a *diagonalization* of a nonlinear system.



E.g., key to ergodic theorems of Birkhoff and von Neumann.

$$g(x) = \sum_{\text{eigenvalues } \lambda_j} c_{\lambda_j} \overset{\text{eigenfunction of } \mathcal{K}}{\varphi_{\lambda_j}(x)} + \int_{-\pi}^{\pi} \overset{\text{continuous spectrum}}{\phi_{\theta,g}(x)} d\theta$$

$$g(x_n) = [\mathcal{K}^n g](x_0)$$

$$= \sum_{\text{eigenvalues } \lambda_j} c_{\lambda_j} \boxed{\lambda_j^n} \varphi_{\lambda_j}(x_0) + \int_{-\pi}^{\pi} \boxed{e^{in\theta}} \phi_{\theta,g}(x_0) d\theta$$

**Spectral properties encode:** geometric features, invariant measures, transient behavior, long-time behavior, coherent structures, quasiperiodicity, etc.

**Trades:** Nonlinear, finite-dimensional  $\Rightarrow$  Linear, infinite-dimensional.

# Fundamental object

Fundamental in ergodic theory

Can provide a *diagonal*

Graduate Texts  
in Mathematics

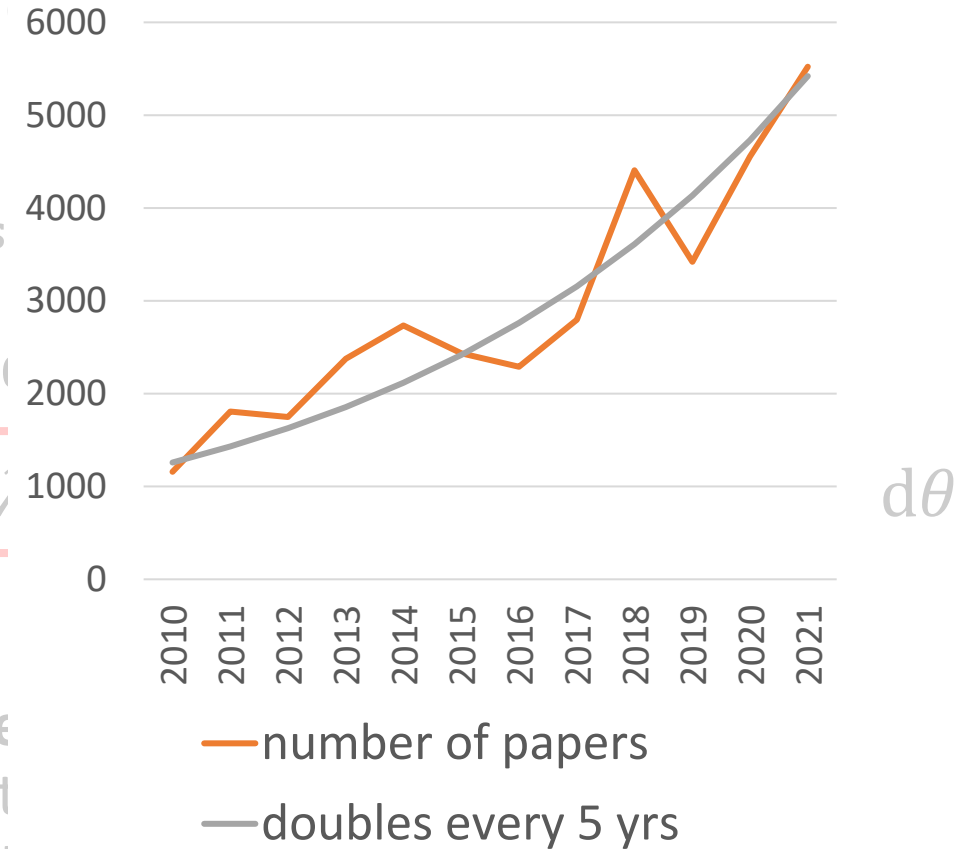
Peter Walters

**+ huge recent interest in  
applications of spectra  
from trajectories**

E.g., key to ergodic theorems of  
Birkhoff and von Neumann.

Spectral properties of  
invariant measures, their  
behavior, coherent structures, quasiperiodicity, etc.

New papers on spectra of  
Koopman operators



**Trades:** Nonlinear, finite-dimensional  $\Rightarrow$  Linear, infinite-dimensional.

# Extended Dynamic Mode Decomposition (EDMD)

Functions  $\psi_j: \mathcal{X} \rightarrow \mathbb{C}, j = 1, \dots, N$

$$\{x^{(m)}, y^{(m)} = F(x^{(m)})\}_{m=1}^M$$

quadrature points

$$\langle \psi_k, \psi_j \rangle \approx \sum_{m=1}^M w_m \overline{\psi_j(x^{(m)})} \psi_k(x^{(m)}) = \left[ \underbrace{\begin{pmatrix} \psi_1(x^{(1)}) & \dots & \psi_N(x^{(1)}) \\ \vdots & \ddots & \vdots \\ \psi_1(x^{(M)}) & \dots & \psi_N(x^{(M)}) \end{pmatrix}}_{\Psi_X}^* \underbrace{\begin{pmatrix} w_1 & & \\ & \ddots & \\ & & w_M \end{pmatrix}}_W \underbrace{\begin{pmatrix} \psi_1(x^{(1)}) & \dots & \psi_N(x^{(1)}) \\ \vdots & \ddots & \vdots \\ \psi_1(x^{(M)}) & \dots & \psi_N(x^{(M)}) \end{pmatrix}}_{\Psi_X} \right]_{jk}$$

quadrature weights

$$\langle \mathcal{K}\psi_k, \psi_j \rangle \approx \sum_{m=1}^M w_m \overline{\psi_j(x^{(m)})} \underbrace{\psi_k(y^{(m)})}_{[\mathcal{K}\psi_k](x^{(m)})} = \left[ \underbrace{\begin{pmatrix} \psi_1(x^{(1)}) & \dots & \psi_N(x^{(1)}) \\ \vdots & \ddots & \vdots \\ \psi_1(x^{(M)}) & \dots & \psi_N(x^{(M)}) \end{pmatrix}}_{\Psi_X}^* \underbrace{\begin{pmatrix} w_1 & & \\ & \ddots & \\ & & w_M \end{pmatrix}}_W \underbrace{\begin{pmatrix} \psi_1(y^{(1)}) & \dots & \psi_N(y^{(1)}) \\ \vdots & \ddots & \vdots \\ \psi_1(y^{(M)}) & \dots & \psi_N(y^{(M)}) \end{pmatrix}}_{\Psi_Y} \right]_{jk}$$

Finite Section  
Approximation

$$\mathcal{K} \rightarrow (\Psi_X^* W \Psi_X)^{-1} \Psi_X^* W \Psi_Y \in \mathbb{C}^{N \times N}$$

- Schmid, "Dynamic mode decomposition of numerical and experimental data," **J. Fluid Mech.**, 2010.
- Rowley, Mezić, Bagheri, Schlatter, Henningson, "Spectral analysis of nonlinear flows," **J. Fluid Mech.**, 2009.
- Williams, Kevrekidis, Rowley "A data-driven approximation of the Koopman operator: Extending dynamic mode decomposition," **J. Nonlinear Sci.**, 2015.

# Residual DMD (ResDMD)

$$\langle \psi_k, \psi_j \rangle \approx \sum_{m=1}^M w_m \overline{\psi_j(x^{(m)})} \psi_k(x^{(m)}) = [\Psi_X^* W \Psi_X]_{jk}$$

$$\langle \mathcal{K}\psi_k, \psi_j \rangle \approx \sum_{m=1}^M w_m \overline{\psi_j(x^{(m)})} \underbrace{\psi_k(y^{(m)})}_{[\mathcal{K}\psi_k](x^{(m)})} = [\Psi_X^* W \Psi_Y]_{jk}$$

**New matrix:**  $\langle \mathcal{K}\psi_k, \mathcal{K}\psi_j \rangle \approx \sum_{m=1}^M w_m \overline{\psi_j(y^{(m)})} \psi_k(y^{(m)}) = [\Psi_Y^* W \Psi_Y]_{jk}$

Uses same trajectory data

- C., Townsend, "Rigorous data-driven computation of spectral properties of Koopman operators for dynamical systems," **Commun. Pure Appl. Math.**, 2023.
- C., Ayton, Szóke, "Residual Dynamic Mode Decomposition," **J. Fluid Mech.**, 2023.
- Code: <https://github.com/MColbrook/Residual-Dynamic-Mode-Decomposition>



# Upper bound on SCl: $\in \Sigma_2$ Implies $\mathcal{K}$ is unitary



*Class of systems:*  $\Omega_{\mathcal{X}} = \{F: \mathcal{X} \rightarrow \mathcal{X} \mid F \text{ cts, measure preserving, invertible}\}.$

*Data an algorithm can use:*  $\mathcal{T}_F = \{(x, y_m) \mid x \in \mathcal{X}, d(y_m, F(x)) \leq 2^{-m}\}.$

**Theorem:** There **exists** *deterministic* algorithms  $\{\Gamma_{N,M}\}$  using  $\mathcal{T}_F$  such that  $\lim_{N \rightarrow \infty} \lim_{M \rightarrow \infty} \Gamma_{N,M}(F) = \text{Sp}(\mathcal{K}_F)$  for all  $F \in \Omega_{\mathcal{X}}$ . (Moreover  $\in \Sigma_2^A$ )

**Idea:** Use the above matrices to compute

$$\lim_{N \rightarrow \infty} \lim_{M \rightarrow \infty} \gamma_{N,M}(z, F) = \|(\mathcal{K}_F - zI)^{-1}\|^{-1} = \text{dist}(z, \text{Sp}(\mathcal{K}_F))$$

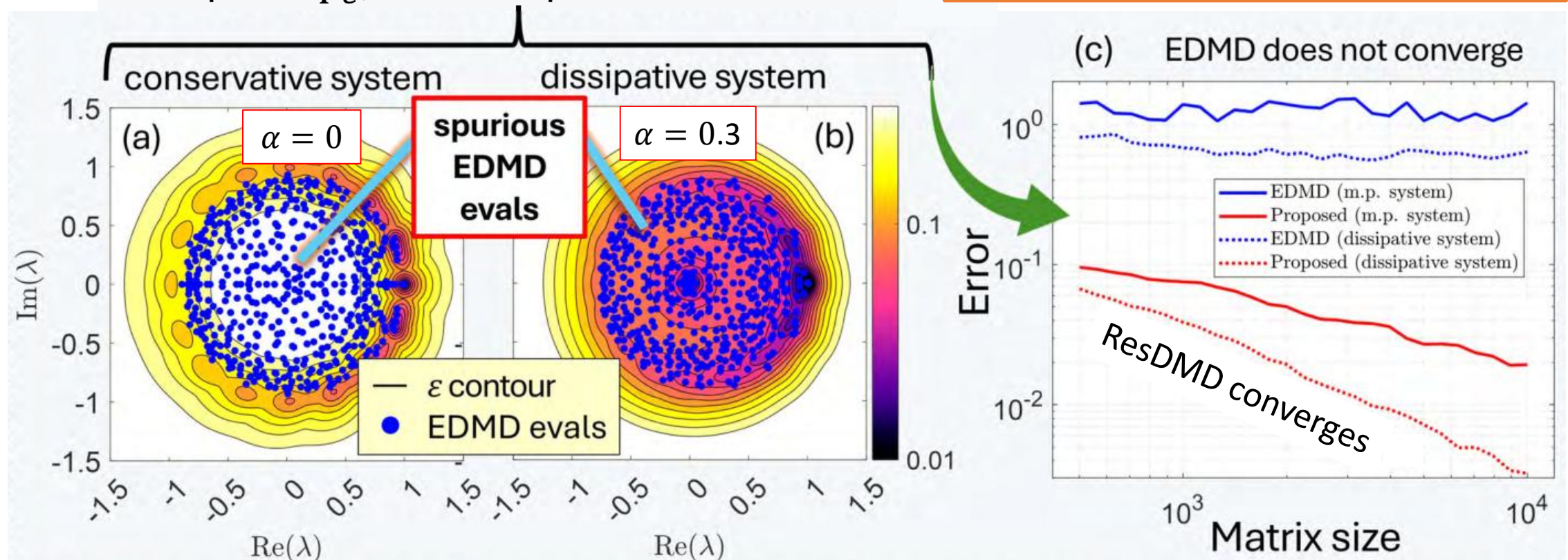
**$N$  = size of basis,  $M$  = amount of data (quadrature)**

# Example: Finite sections don't converge

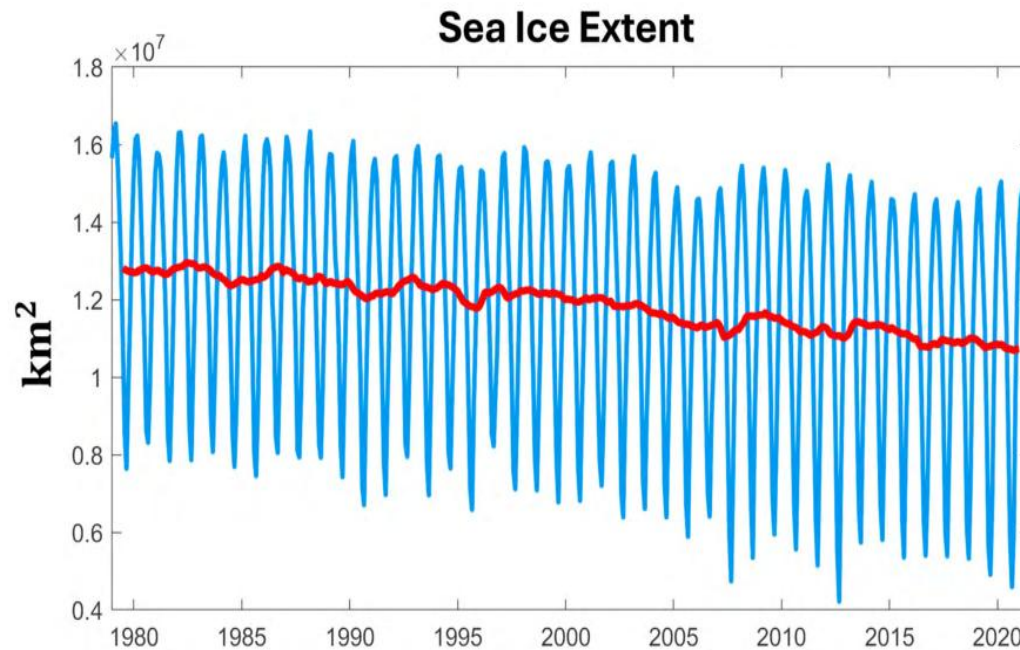
- Duffing oscillator:  $\dot{x} = y, \dot{y} = -\alpha y + x(1 - x^2)$ , sampled  $\Delta t = 0.3$ .
- Gaussian radial basis functions, Monte Carlo integration ( $M = 50000$ )

Compute  $\text{Sp}_\varepsilon$ , local adaptive control on  $\varepsilon \downarrow 0$

$$\text{Sp}_\varepsilon(\mathcal{K}_F) = \{z \in \mathbb{C} : \|(\mathcal{K}_F - zI)^{-1}\|^{-1} \leq \varepsilon\}$$



# Practical Gains: Arctic Sea Ice Forecasting

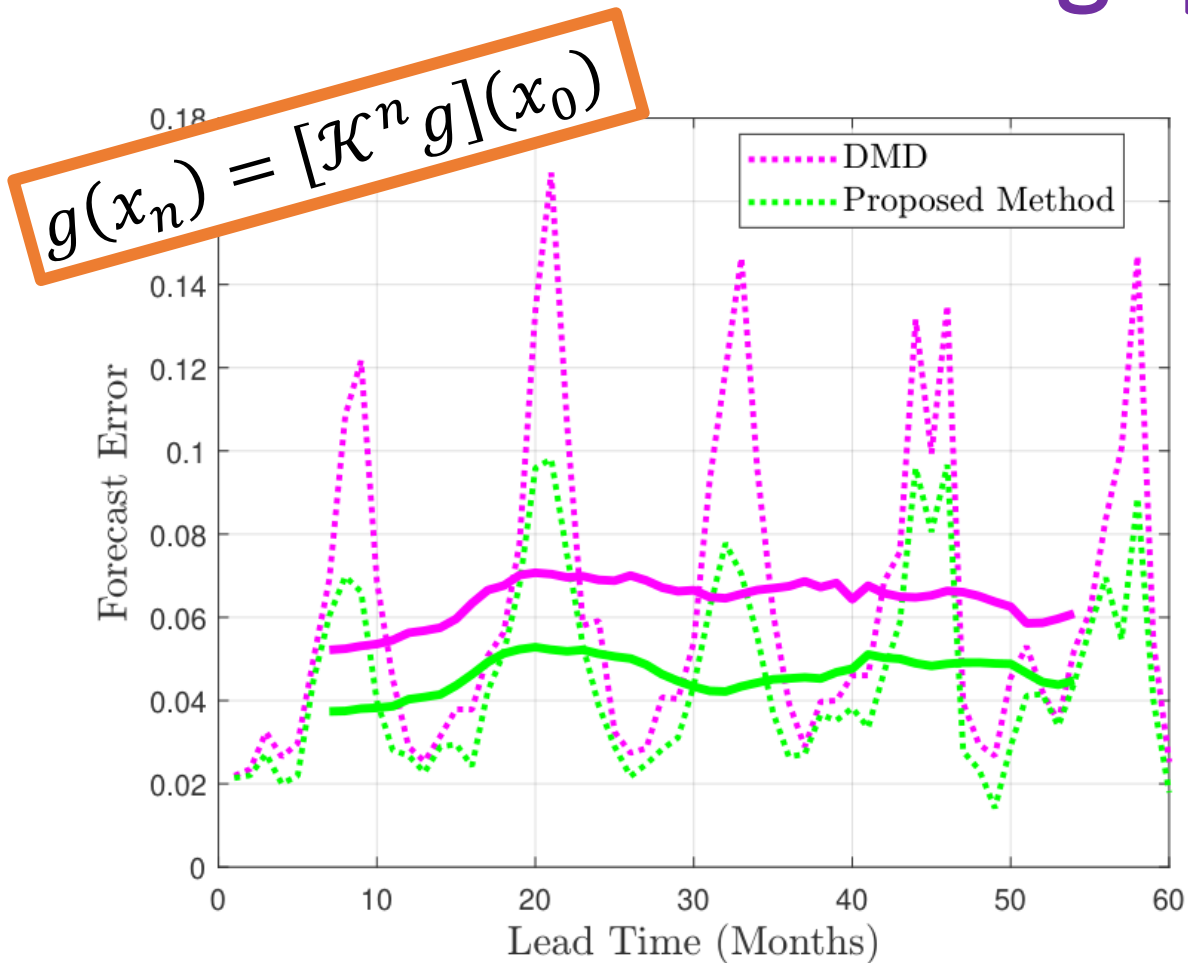


Monthly average from  
satellite passive  
microwave sensors.

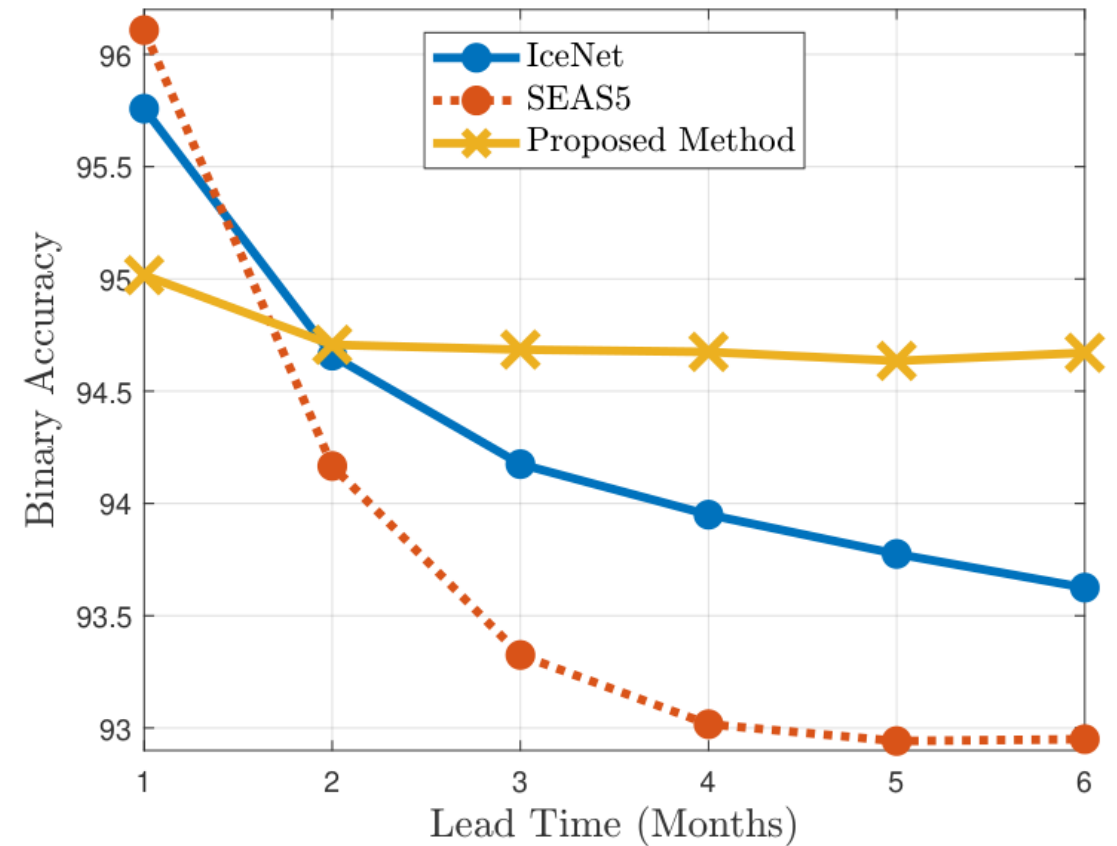
**Motivation:** Arctic amplification, polar bears, local communities, effect on extreme weather in Northern hemisphere,...

**Problem:** Very hard to predict more than two months in advance.

# Arctic case: Avoiding spurious eigenvalues helps!



Relative mean squared error over 2016-2020. Model built from 2005-2015 data. (Solid lines moving 12-month mean.)



Mean binary accuracy over test years 2012-2020. (*IceNet: Andersson et al, "Seasonal Arctic sea ice forecasting with probabilistic deep learning." Nature Communications, 2021.*)

# Lower bound on SCI: $\notin \Delta_2$

Implies  $\mathcal{K}$  is unitary

*Class of systems:*  $\Omega_{\mathbb{D}} = \{F: \bar{\mathbb{D}} \rightarrow \bar{\mathbb{D}} \mid F \text{ cts, measure preserving, invertible}\}.$

*Data an algorithm can use:*  $\mathcal{T}_F = \{(x, y_m) \mid x \in \bar{\mathbb{D}}, \|F(x) - y_m\| \leq 2^{-m}\}.$

**Theorem:** There **does not exist** any sequence of deterministic algorithms  $\{\Gamma_n\}$  using  $\mathcal{T}_F$  such that  $\lim_{n \rightarrow \infty} \Gamma_n(F) = \text{Sp}(\mathcal{K}_F) \quad \forall F \in \Omega_{\mathbb{D}}.$

**NB:** Similarly, no random algorithms converging with probability  $> 1/2$ .

**Double limit is necessary.**

# Proof idea: Constructing an adversary

$$F_0: \text{rotation by } \pi, \operatorname{Sp}(\mathcal{K}_{F_0}) = \{\pm 1\}$$

**Phase transition lemma:** Let  $X = \{x_1, \dots, x_N\}, Y = \{y_1, \dots, y_N\}$  be distinct points in annulus  $\mathcal{A} = \{x \in \mathbb{D} \mid 0 < R < \|x\| < r < 1\}$  with  $X \cap Y = \emptyset$ . There exists a measure-preserving homeomorphism  $H$  such that  $H$  acts as the identity on  $\mathbb{D} \setminus \mathcal{A}$  and  $H(y_j) = F_0(H(x_j)), j = 1, \dots, N$ .

*Conjugacy of data ( $x_j \rightarrow y_j$ ) with  $F_0$*

**Idea:** Use lemma to trick any algorithm into oscillating between spectra.



# Proof idea: Constructing an adversary

Suppose (for contradiction)  $\{\Gamma_n\}$  uses  $\mathcal{T}_F$ ,  $\lim_{n \rightarrow \infty} \Gamma_n(F) = \text{Sp}(\mathcal{K}_F) \quad \forall F \in \Omega_{\mathbb{D}}$ .

Build an **adversarial**  $F$ ...

$$\mathcal{T}_F = \{(x, y_m) \mid \|F(x) - y_m\| \leq 2^{-m}\}$$

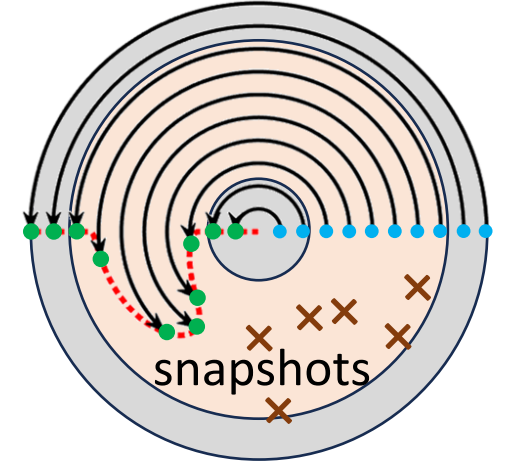
# Proof idea: Constructing an adversary

Suppose (for contradiction)  $\{\Gamma_n\}$  uses  $\mathcal{T}_F$ ,  $\lim_{n \rightarrow \infty} \Gamma_n(F) = \text{Sp}(\mathcal{K}_F) \quad \forall F \in \Omega_{\mathbb{D}}$ .

Build an **adversarial**  $F$ ...

$$\widetilde{F}_1(r, \theta) = (r, \theta + \pi + \phi(r)), \text{ supp}(\phi) \subset [1/4, 3/4]$$

$$\text{Sp}(\mathcal{K}_{\widetilde{F}_1}) = \mathbb{T} \text{ (unit circle).}$$



$$\mathcal{T}_F = \{(x, y_m) \mid \|F(x) - y_m\| \leq 2^{-m}\}$$



# Proof idea: Constructing an adversary

Suppose (for contradiction)  $\{\Gamma_n\}$  uses  $\mathcal{T}_F$ ,  $\lim_{n \rightarrow \infty} \Gamma_n(F) = \text{Sp}(\mathcal{K}_F) \quad \forall F \in \Omega_{\mathbb{D}}$ .

Build an **adversarial**  $F$ ...

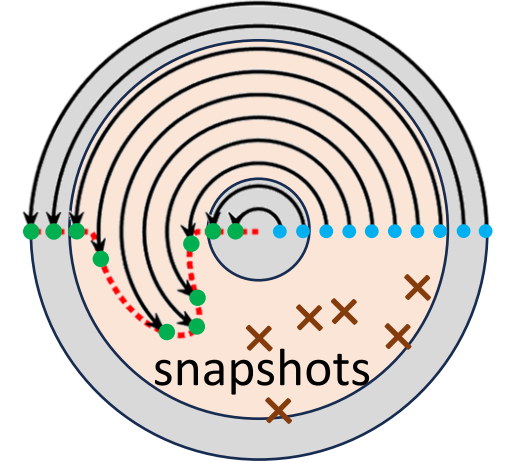
$$\widetilde{F}_1(r, \theta) = (r, \theta + \pi + \phi(r)), \text{supp}(\phi) \subset [1/4, 3/4]$$

$$\text{Sp}(\mathcal{K}_{\widetilde{F}_1}) = \mathbb{T} \text{ (unit circle).}$$

$$\lim_{n \rightarrow \infty} \Gamma_n(\widetilde{F}_1) = \text{Sp}(\mathcal{K}_{\widetilde{F}_1}) \Rightarrow \exists n_1 \text{ s.t. } \text{dist}(i, \Gamma_{n_1}(\widetilde{F}_1)) \leq 1.$$

**BUT**  $\Gamma_{n_1}$  uses finite amount of info to output  $\Gamma_{n_1}(\widetilde{F}_1)$ .

Let  $X, Y$  correspond to these snapshots.



$$\mathcal{T}_F = \{(x, y_m) \mid \|F(x) - y_m\| \leq 2^{-m}\}$$

# Proof idea: Constructing an adversary

Suppose (for contradiction)  $\{\Gamma_n\}$  uses  $\mathcal{T}_F$ ,  $\lim_{n \rightarrow \infty} \Gamma_n(F) = \text{Sp}(\mathcal{K}_F) \quad \forall F \in \Omega_{\mathbb{D}}$ .

Build an **adversarial**  $F$ ...

$$\widetilde{F}_1(r, \theta) = (r, \theta + \pi + \phi(r)), \text{supp}(\phi) \subset [1/4, 3/4]$$

$$\text{Sp}(\mathcal{K}_{\widetilde{F}_1}) = \mathbb{T} \text{ (unit circle).}$$

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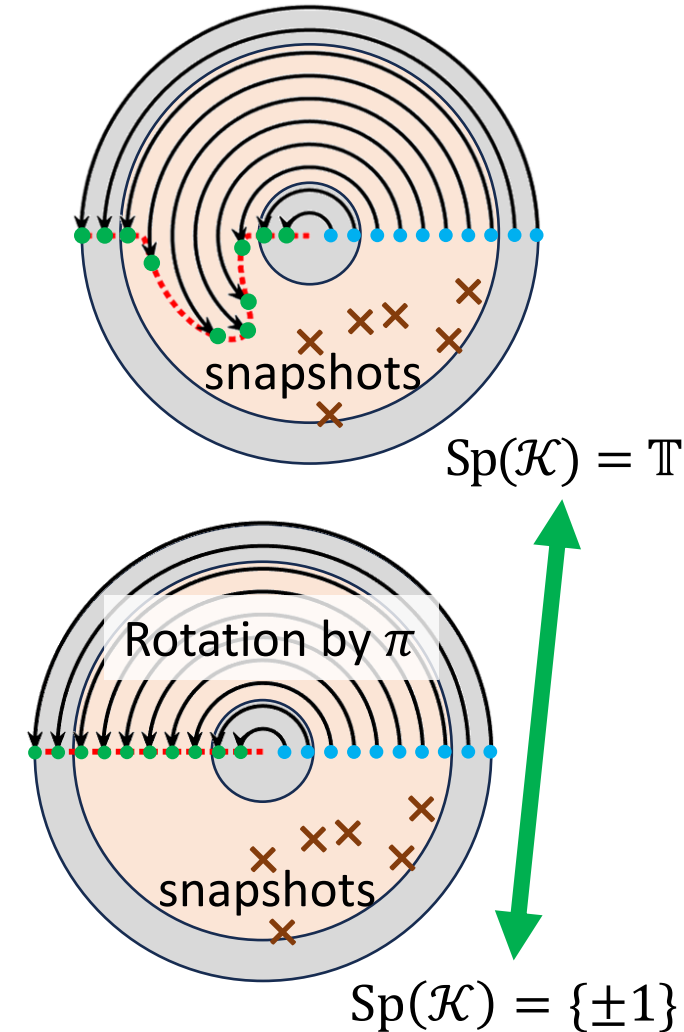
**BUT**  $\Gamma_{n_1}$  uses finite amount of info to output  $\Gamma_{n_1}(\widetilde{F}_1)$ .

Let  $X, Y$  correspond to these snapshots.

Lemma:  $F_1 = H_1^{-1} \circ F_0 \circ H_1$  on annulus  $\mathcal{A}_1$ .

Consistent data  $\Rightarrow \Gamma_{n_1}(F_1) = \Gamma_{n_1}(\widetilde{F}_1)$ ,  $\text{dist}(i, \Gamma_{n_1}(F_1)) \leq 1$

**BUT**  $\text{Sp}(\mathcal{K}_{F_1}) = \text{Sp}(\mathcal{K}_{F_0}) = \{\pm 1\}$



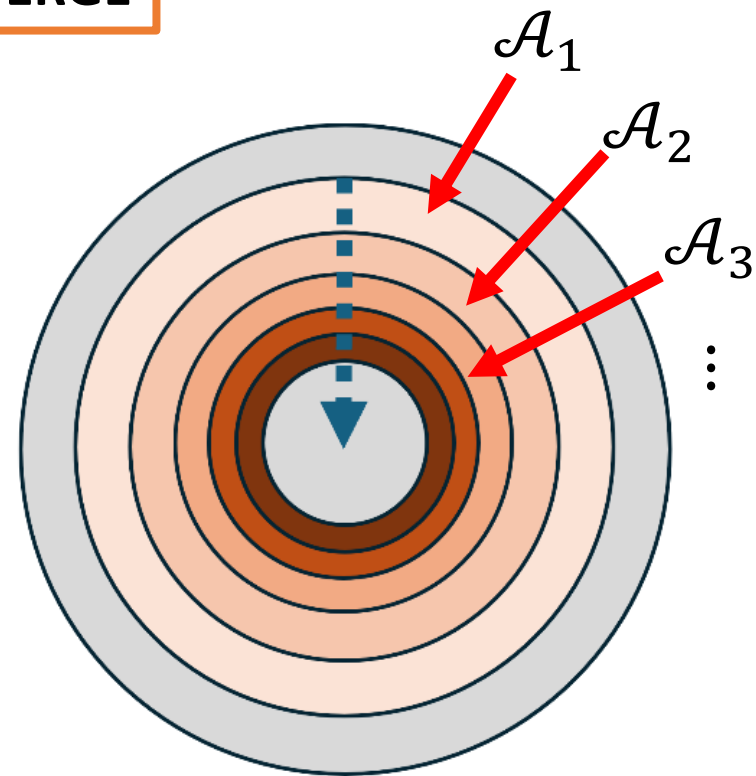
# Proof idea: Constructing an adversary

**Inductive step:** Repeat on annuli,  $F_k = H_k^{-1} \circ F_0 \circ H_k$  on  $\mathcal{A}_k$ .  $F = \lim_{k \rightarrow \infty} F_k$

Consistent data  $\Rightarrow \Gamma_{n_k}(F) = \Gamma_{n_k}(\widetilde{F_k})$ ,  $\text{dist}(i, \Gamma_{n_k}(F)) \leq 1$ ,  $n_k \rightarrow \infty$

**BUT**  $\text{Sp}(\mathcal{K}_F) = \text{Sp}(\mathcal{K}_{F_0}) = \{\pm 1\}$

**CANNOT CONVERGE**



Cascade of disks

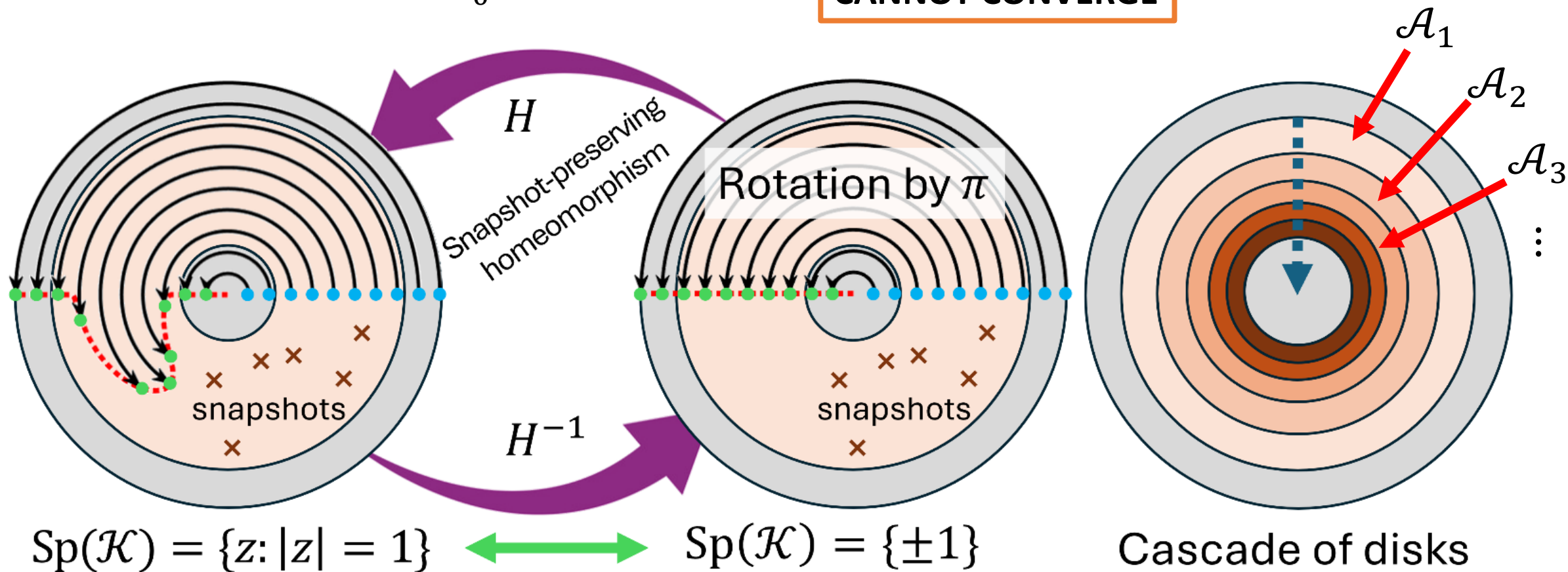
# Proof idea: Constructing an adversary

**Inductive step:** Repeat on annuli,  $F_k = H_k^{-1} \circ F_0 \circ H_k$  on  $\mathcal{A}_k$ .  $F = \lim_{k \rightarrow \infty} F_k$

Consistent data  $\Rightarrow \Gamma_{n_k}(F) = \Gamma_{n_k}(\widetilde{F}_k)$ ,  $\text{dist}(i, \Gamma_{n_k}(F)) \leq 1$ ,  $n_k \rightarrow \infty$

**BUT**  $\text{Sp}(\mathcal{K}_F) = \text{Sp}(\mathcal{K}_{F_0}) = \{\pm 1\}$

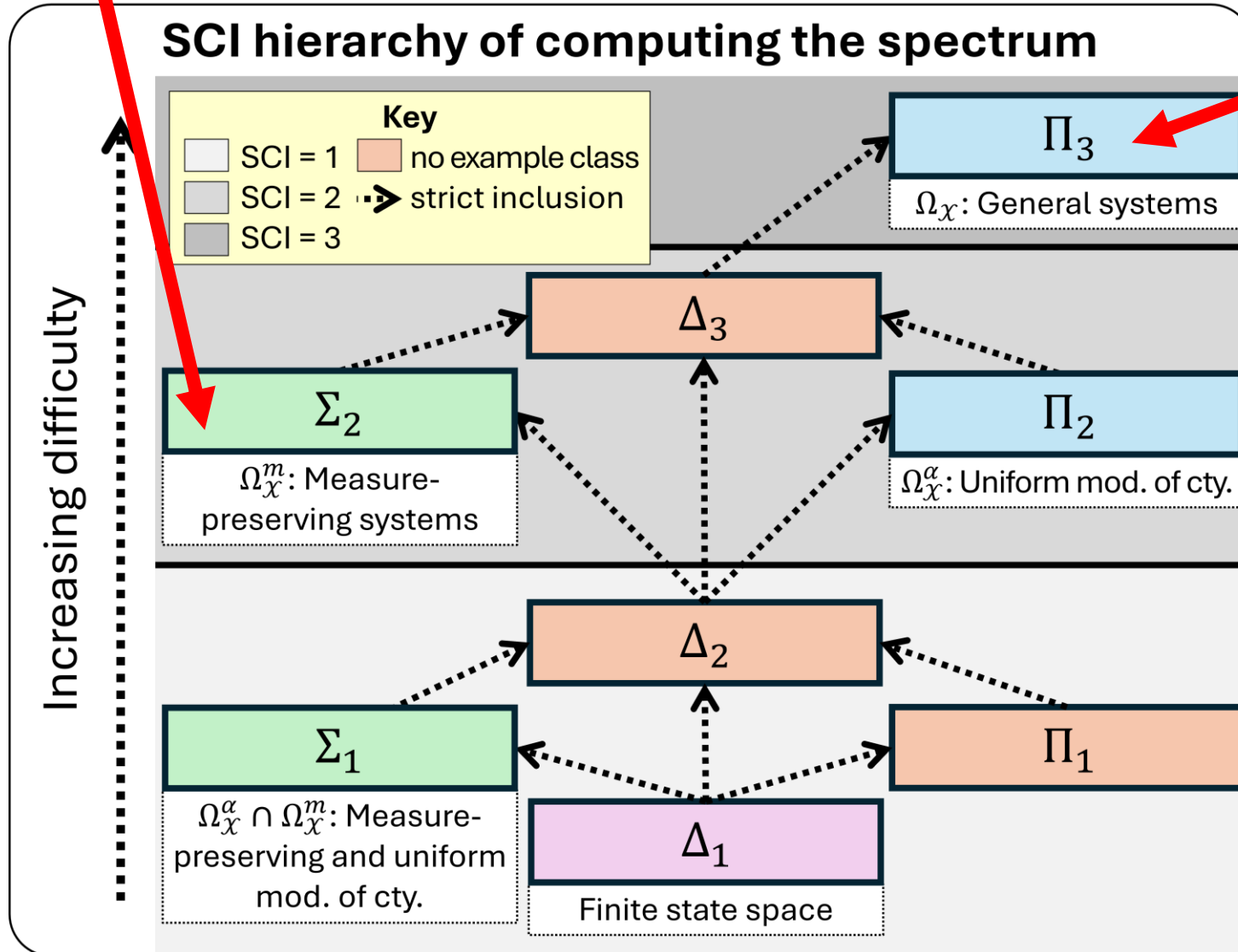
**CANNOT CONVERGE**



Lower + upper bounds

# Classification for Koopman

3 limits needed in general!



**Different classes:**

$$\Omega_{\mathcal{X}} = \{F: \mathcal{X} \rightarrow \mathcal{X} \mid F \text{ cts}\}$$

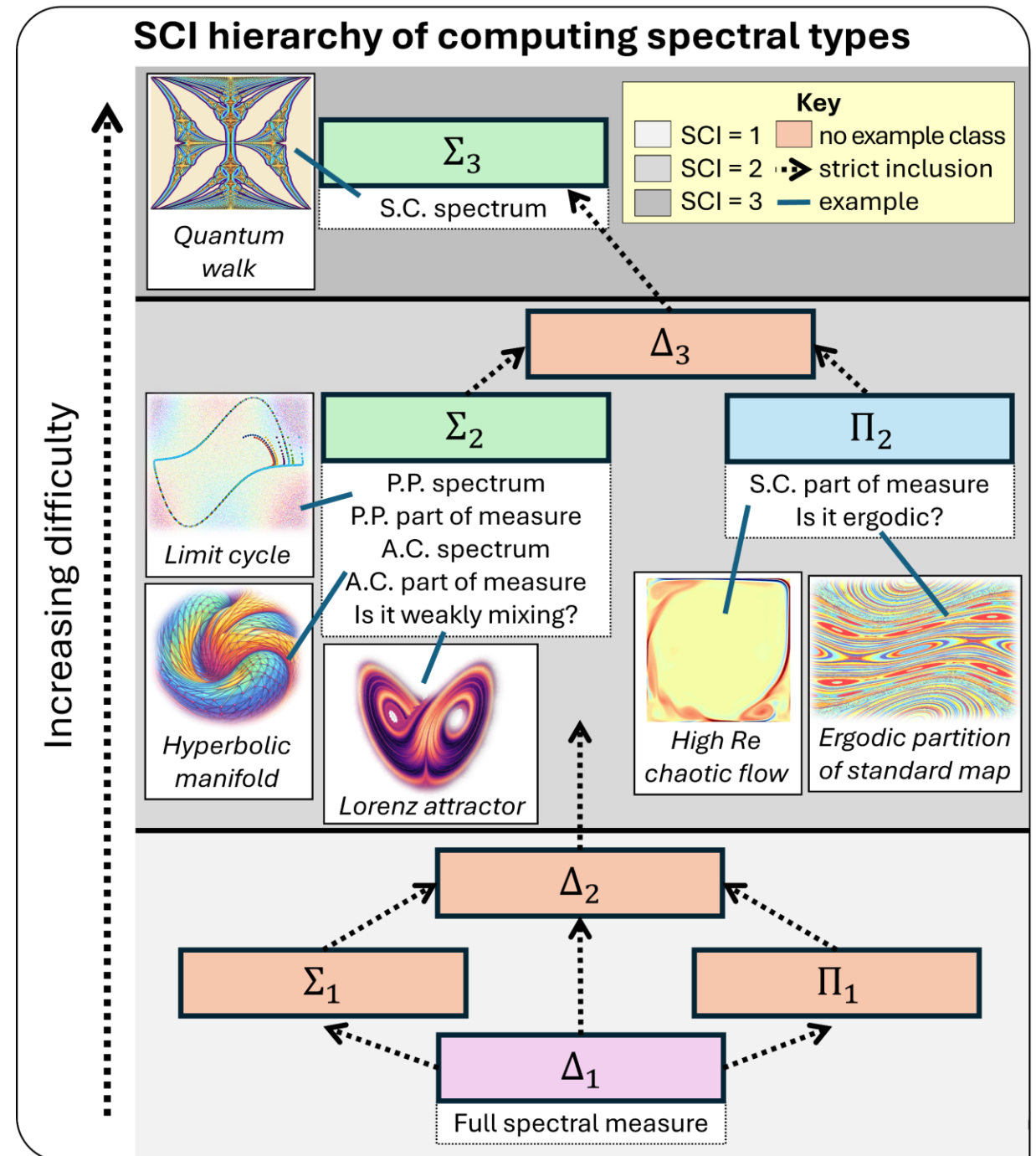
$$\Omega_{\mathcal{X}}^m = \{F: \mathcal{X} \rightarrow \mathcal{X} \mid F \text{ cts, m. p.}\}$$

$$\Omega_{\mathcal{X}}^{\alpha} = \{F: \mathcal{X} \rightarrow \mathcal{X} \mid F \text{ mod. cty. } \alpha\}$$

$$[d_{\mathcal{X}}(F(x), F(y)) \leq \alpha(d_{\mathcal{X}}(x, y))]$$

**Optimal algorithms and classifications of dynamical systems.**

# Classification for Koopman II



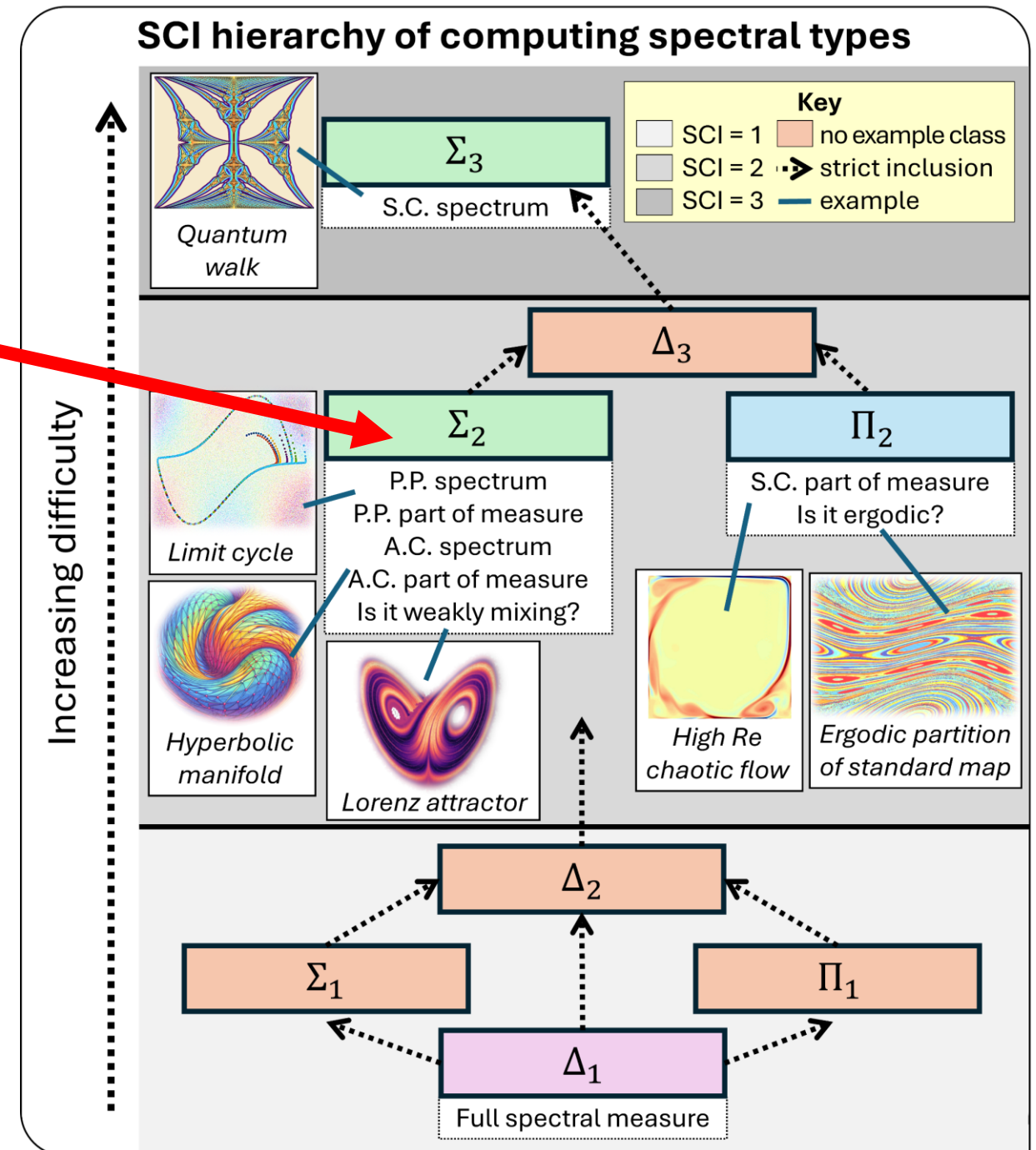


# Classification for Koopman II

## Example: Theorem

For smooth, measure-preserving systems on a torus, learning eigenfunctions or even determining if there are any has  $\text{SCI} = 2$  (even if we can sample derivatives).

Finding finite-dimensional embeddings in which the dynamics are linear is very hard!



# Conclusion: FOUNDATIONS $\leftrightarrow$ METHODS

- $\exists$  interesting mathematical structure in inf.-dim. spectral computations.
- Many spectral problems in inf. dim. are impossible. *Some harder than others*
- **SCI hierarchy** is a tool for discovering the foundations of computation.
  - Lower bounds**  $\Rightarrow$  spot assumptions needed to lower SCI.
  - Upper bounds**  $\Rightarrow$  new “inf.-dim.” algorithms. Rigorous, optimal, practical.
- $\Sigma_1 \cup \Pi_1 \Rightarrow$  computer-assisted proofs (e.g., Dirac-Schwinger proof implicit  $\Sigma_1$ )

Further examples not covered in talk: foundations of AI, optimization, PDEs, resonances, computer-assisted proofs, spectral measures,...



# Shameless final plug...

Upcoming book with CUP:

## INFINITE-DIMENSIONAL SPECTRAL COMPUTATIONS

### Foundations, Algorithms, and Modern Applications

**100s of:** classifications, algorithms,  
examples (including full code), figures,  
exercises (including full solutions).

**\*\*Out this (2025) holiday season  
(hopefully!)... \*\***

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please speak to me after.*

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## INFINITE-DIMENSIONAL SPECTRAL COMPUTATIONS

Foundations, Algorithms, and Applications

*Connections with harmonic analysis. Main tool is computing  $(A, z, u) \mapsto (A - zI)^{-1}u$ . Lower bounds through things like Anderson localization.*

**100s of:** classifications, examples (including full solutions), exercises (including full solutions).

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Foundations, Algorithms, and Applications

Use  $\gamma(z, A)$  to compute  
more complex objects like  
fractal dimensions.  
Applications include  
aperiodic operators.

**100s of:** classifications, algorithms, examples (including full code), figures, exercises (including full solutions).

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### Foundations, Algorithms, and Modern

*Main tool is essential injection moduli (Edmunds & Evans 1987):*

$$\tau_{\inf}(A) = \inf \left\{ \liminf_{n \rightarrow \infty} \|Ax_n\| : x_n \in \mathcal{D}(A), \|x_n\| = 1, x_n \rightarrow^w 0 \right\}$$

*Typically incurs and extra limit.  $W_e(A)$  is universally  $\Pi_2$*

... *classifications, algorithms,*  
examples (including full code), figures,  
exercises (including full solutions).

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**100s of:** classificat  
examples (includin  
exercises (including full solutions).

*Injection moduli for  $T(z)$ .  
Contour methods for discrete  
spectra of holomorphic families.*

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